ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	05 November 2022
Team ID	PNT2022TMID43114
Project Name	Smart Waste Management System for Metropolitan Cities
Maximum Marks	2 Marks

Ouestion 1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 centimeters it should send "alert" to IBM cloud and display in device recent events.

CODE:

```
#include <WiFi.h>//library for wifi
 #include <Pubsubclient.h>//library for Hott
 void callback(char subscribetopic, byte payload, unsigned int payloadLength);
#define ORG 4h0jp"//IBM ORGANITION IO
#define DEVICE_TYPE "ULTRASON
 #define TOKEN "wuo5s7PR)ZSegvk&Rx"
String data3;
float dist;
char server[] -ORG ".messaging internetofthings.ibmcloud.com";// Server Name
char publishTopic[] "iot-2/evata/fmt/json";
char authMethod[]"use-token-auth";// authentication method
char token[] TOKEN;
char clientId[]"d:" ORG ":" DEVICE_TYPE":"DEVICE_ID;//client id
int LED = 4;
 int trig 5;
int echo= 18;
void setic()
Serial.begin(115200);
```

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
         mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
### displaying a libraries bd | Library Manager |

### If (client.publish(publishTopic, (char*) payload.c_str())) {

### Serial.println("Publish ok"); // if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed |

### Serial.println("Publish failed"); |

### Serial.println("Serial.println("); |

### Serial.println("); |

### Serial.println("); |

### Serial.println("); |

### Serial.println(); |

### Serial.println(); |

### Serial.println(); |

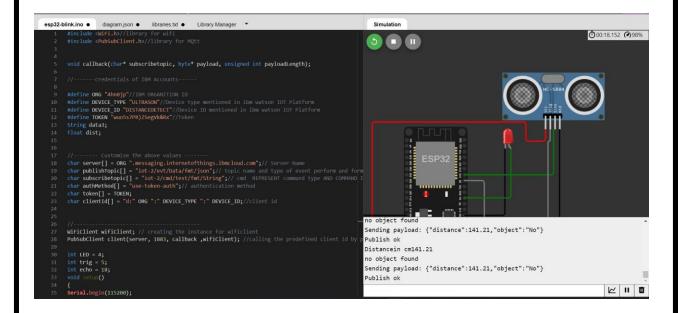
### Serial.println(); |

### Serial.println("); |

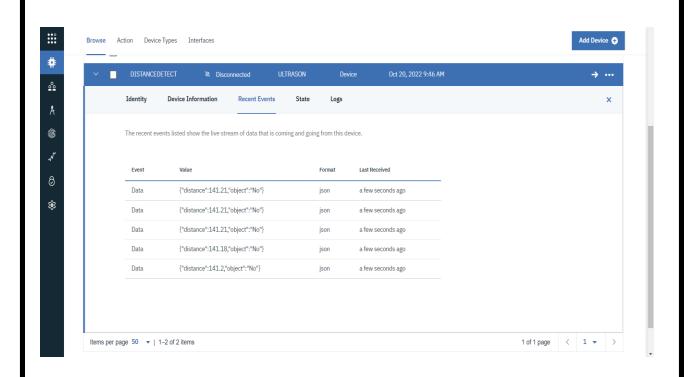
### Serial.println("
```

```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

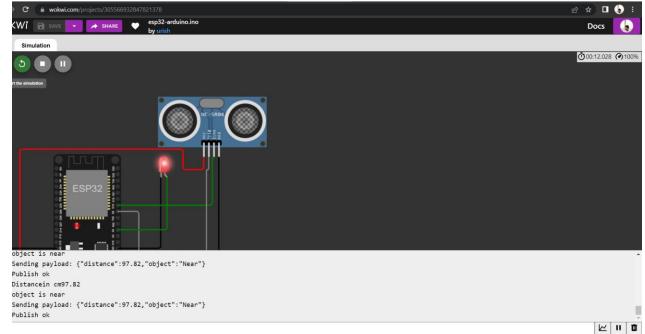
OUTPUT:



Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

