PROJECT DEVELOPEMENT PHASE DELIVERY OF SPRINT – 2

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Team ID	PNT2022TMID43114
Project Name	Smart Waste Management System For Metropolitan Cities

CODE:

```
// library for wifi
#include <WiFi.h>
#include < PubSubClient.h>
                                 // library for MQTT
#include <LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);
//----- credentials of IBM Accounts -----
                            // IBM organisation id
#define ORG "80bbqy"
#define DEVICE_TYPE "cse2019"
                                // Device type mentioned in ibm watson iot platform
#define DEVICE_ID "ganesh1601"
                                // Device ID mentioned in ibm watson iot platform
#define TOKEN "12345678"
                            // Token
//----- customise above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
                                                               // server name
char publishTopic[] = "iot-2/evt/data/fmt/json";
                                                      // topic name and type of event perform and format in
which data to be send
char topic[] = "iot-2/cmd/led/fmt/String";
                                                     // cmd Represent type and command is test format of
char authMethod[] = "use-token-auth";
                                                     // authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
                                                          //Client id
//------
WiFiClient wifiClient;
                                          // creating instance for wificlient
PubSubClient client(server, 1883, wifiClient);
#define ECHO PIN 12
#define TRIG_PIN 13
float dist;
void setup()
 Serial.begin(115200);
 pinMode(LED_BUILTIN, OUTPUT);
 pinMode(TRIG_PIN, OUTPUT);
 pinMode(ECHO_PIN, INPUT);
 //pir pin
```

```
pinMode(34, INPUT);
//ledpins
pinMode(23, OUTPUT);
pinMode(2, OUTPUT);
pinMode(4, OUTPUT);
pinMode(15, OUTPUT);
lcd.init();
lcd.backlight();
lcd.setCursor(1, 0);
lcd.print("");
wifiConnect();
mqttConnect();
}
float readcmCM()
{
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
 digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
int duration = pulseIn(ECHO_PIN, HIGH);
return duration * 0.034 / 2;
}
void loop()
{
lcd.clear();
publishData();
delay(500);
if (!client.loop())
 {
  mqttConnect();
                                 // function call to connect to IBM
 }
}
         -----*/
void wifiConnect()
{
Serial.print("Connecting to ");
```

```
Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED)
   delay(500);
   Serial.print(".");
  }
 Serial.print("WiFi connected, IP address: ");
 Serial.println(WiFi.localIP());
}
void mqttConnect()
  if (!client.connected())
   {
    Serial.print("Reconnecting MQTT client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
      Serial.print(".");
      delay(500);
     }
    initManagedDevice();
    Serial.println();
   }
 }
void initManagedDevice()
 {
  if (client.subscribe(topic))
   {
    Serial.println("IBM subscribe to cmd OK");
   }
 else
   {
    Serial.println("subscribe to cmd FAILED");
   }
 }
void publishData()
```

```
{
 float cm = readcmCM();
if(digitalRead(34))
                                     //pir motion detection
  Serial.println("Motion Detected");
 Serial.println("Lid Opened");
 digitalWrite(15, HIGH);
 if(digitalRead(34)== true)
{
 if(cm <= 60)
                                       //Bin level detection
 {
  digitalWrite(2, HIGH);
  Serial.println("High Alert!!!,Trash bin is about to be full");
  Serial.println("Lid Closed");
  lcd.print("Full! Don't use");
  delay(2000);
  lcd.clear();
  digitalWrite(4, LOW);
  digitalWrite(23, LOW);
 else if(cm > 60 && cm < 120)
 {
  digitalWrite(4, HIGH);
  Serial.println("Warning!!,Trash is about to cross 50% of bin level");
  digitalWrite(2, LOW);
  digitalWrite(23, LOW);
 }
 else if(cm > 120)
 {
  digitalWrite(23, HIGH);
  Serial.println("Bin is available");
  digitalWrite(2,LOW);
  digitalWrite(4, LOW);
 }
  delay(10000);
  Serial.println("Lid Closed");
```

```
}
else
{
 Serial.println("No motion detected");
  digitalWrite(2, LOW);
  digitalWrite(15, LOW);
  digitalWrite(4, LOW);
  digitalWrite(23, LOW);
}
 }
 else
  digitalWrite(15, LOW);
  }
if(cm <= 60)
{
digitalWrite(21,HIGH);
String payload = "{\"High_Alert\":";
payload += cm;
payload += " }";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))
                                                            // if data is uploaded to cloud successfully, prints publish ok
else prints publish failed
{
Serial.println("Publish OK");
}
}
else if(cm <= 120)
{
digitalWrite(22,HIGH);
String payload = "{\"Warning\":";
payload += cm;
payload += " }";
Serial.print("\n");
```

```
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
else
{
Serial.println();
}
float inches = (cm / 2.54);
                                                //print on lcd
 lcd.setCursor(0,0);
 lcd.print("Inches");
 lcd.setCursor(4,0);
 lcd.setCursor(12,0);
 lcd.print("cm");
 lcd.setCursor(1,1);
 lcd.print(inches, 1);
 lcd.setCursor(11,1);
 lcd.print(cm, 1);
 lcd.setCursor(14,1);
 delay(1000);
 lcd.clear();
}
```

CIRCUIT:



