## **ASSIGNMENT 1**

## **Problem Statement:**

IoT - Based Industry - Real-Time River Water Quality Monitoring and ControlSystem

**Topic**: Circuit design Home automation system in TinkerCad

## Code:

```
const int pingPin = 10;
const int ledUS = 2;
const int light = 7;
const int pir = 4;
int const PINO_SGAS = A5;
int const ledGas = 8;
int const button = 5;
int const motor = 13;
void setup(){
pinMode(ledUS, OUTPUT);
pinMode(light, OUTPUT);
pinMode(buzzer, OUTPUT);
pinMode(ledGas, OUTPUT);
pinMode(motor, OUTPUT);
```

```
pinMode(pir, INPUT);
pinMode(button, INPUT);
pinMode(photoSensor, INPUT);
Serial.begin(9600);
}
void loop(){
long duration, cm;
int valLight = analogRead(photoSensor);
int valPIR= digitalRead(pir);
int valGAS = analogRead(PINO_SGAS);
valGAS = map(valGAS, 300, 750, 0, 100);
int valBt = digitalRead(button);
pinMode(pingPin, OUTPUT);
digitalWrite(pingPin, LOW);
delayMicroseconds(2);
digitalWrite(ping Pin, HIGH);
delayMicroseconds(5);
digitalWrite(ping Pin, LOW);
pinMode(pingPin, INPUT);
duration= pulseln(pingPin, HIGH);
cm = microsecondsToCentimeters(duratio n);
if(cm < 336){
```

```
digitalWrite(ledUS, HIGH);
}
Else
digitalWrite(ledUS,LOW);
if(valLight < 890){
digitalWrite(light, HIGH);
}
Else
digitalWrite(light, LOW);
if(valPIR == 1){
digitalWrite(buzzer, HIGH);
}
Else
digitalWrite(buzzer, LOW);
if(valBt == 1){
digitalWrite(motor,HIGH);
} else {
digitalWrite(motor, LOW);
if(valGAS > 20){
```

```
digitalWrite(ledGas, HIGH);
}
else{
digitalWrite(ledGas, LOW);
Serial.print(val PIR);
Serial.println();
}
```

## **OUTPUT:**

