# Professional Readiness for Innovation, Employability and Entrepreneurship

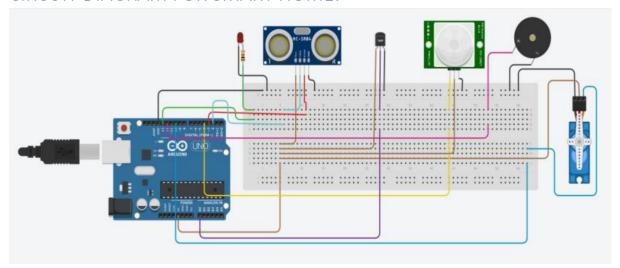
### **Smart Home**

## **Assignment 1**

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### CIRCUIT DIAGRAM FOR SMART HOME:



#### CODING:

```
#include <Servo.h>
int location=0;
int i=0;
int j=0;
Servo s;
Void setup()
{
Serial.begin(9600);
pinMode(4,INPUT);
pinMode(13,OUTPUT);
pinMode(12,OUTPUT);
s.attach(10,500,2500);
pinMode(3,INPUT);
pinMode(2,OUTPUT);
}
void loop()
{
int n=digitalRead(4);
```

```
Serial.println(n);
If(n){
Serial.println("MOTION DETECTD!!!");
Location=0;
For(location=1;location<=180;location+=60){
s.write(location);
delay(100);
double a=analogRead(A0);
double t=(((a/1024)*5)-0.5)*100;
Serial.print("TEMP VALUE:");
Serial.println(t);
If(t>100){
for(int j=200;j<220;j++)
{
tone(12,j);
}
delay(1000);
noTone(12);
}
digitalWrite(2,LOW);
digitalWrite(2,HIGH);
delay(1000);
digitalWrite(2,Low);
float dur=pulseIn(3,HIGH);
digitalWrite(13,LOW);
if(dis<20){
Serial.print("Distance");
Serial.print(dis);
Serial.println("cm");
digitalWrite(13,HIGH);
```

```
}
}
digitalWrite(2,LOW);
digitalWrite(2,HIGH);
delay(1000);
digitalWrite(2,Low);
float dur=pulseIn(3,HIGH);
float dis=(dur*0.0343)2;
digitalWrite(13,LOW);
if(dis<20){
Serial.print("Distance");
Serial.print(dis);
Serial.println("cm");
digitalWrite(13,HIGH);
}
}
delay(1000);
}
```