Assignment 4

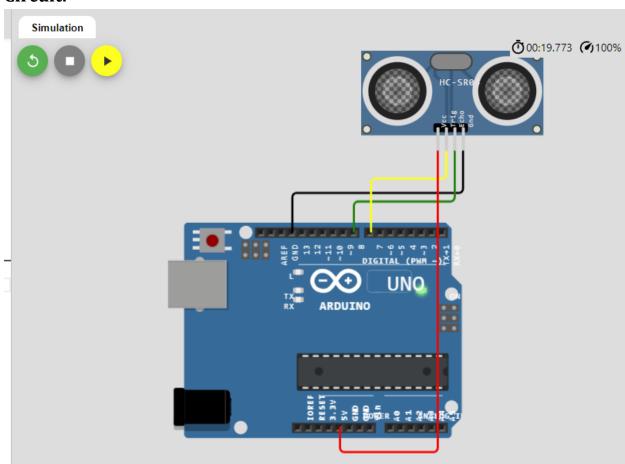
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Write Code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

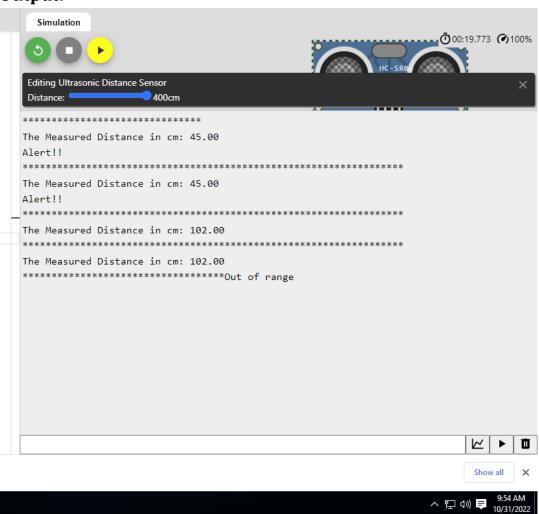
Program code:

```
const int TRIG PIN = 7;
const int ECHO_PIN = 8;
const unsigned int MAX_DIST = 23200;
void setup()
{
  pinMode(TRIG PIN, OUTPUT);
  digitalWrite(TRIG_PIN, LOW);
  pinMode(ECHO_PIN, INPUT );
  Serial.begin(9600);
}
void loop()
  unsigned long t1;
  unsigned long t2;
  unsigned long pulse_width;
  float cm;
  float inches;
  digitalWrite(TRIG PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  while (digitalRead( ECHO_PIN )==0 );
  t1= micros ();
  while (digitalRead(ECHO_PIN) == 1);
  t2= micros ();
  pulse_width = t2-t1;
  cm=pulse_width / 58;
  inches = pulse_width/148.0;
  if (pulse_width >MAX_DIST )
  {
  Serial.println("Out of range");
```

Circuit:



Output:



Wokwi code:

```
sketch.ino •
             diagram.json •
                            Library Manager *
  const int TRIG_PIN = 7;
  2 const int ECHO_PIN = 8;
  3 const unsigned int MAX_DIST = 23200;
  4 void setup()
  5 {
      pinMode(TRIG_PIN, OUTPUT);
  6
      digitalWrite(TRIG_PIN, LOW);
  7
  8 pinMode(ECHO_PIN, INPUT );
      Serial.begin(9600);
  9
  10 }
  11
      void loop()
  12
      {
  unsigned long t1;
  14 unsigned long t2;
  unsigned long pulse_width;
  16 float cm;
  17 float inches;
  18 digitalWrite(TRIG_PIN, HIGH);
  19 delayMicroseconds(10);
  20 digitalWrite(TRIG_PIN, LOW);
  21 while (digitalRead( ECHO_PIN )==0 );
  22 t1= micros ();
  23 while (digitalRead(ECHO_PIN) == 1);
  24 t2= micros ();
  25  pulse_width = t2-t1;
  26 cm=pulse width / 58;
  27 inches = pulse width/148.0;
  28 if (pulse_width >MAX_DIST )
  29 {
  30 Serial.println("Out of range");
  31 }
  32 else
  33 {
  34 Serial.println("**********************");
  29 {
  30 Serial.println("Out of range");
  31 }
  32 else
  33
  34 Serial.println("***************************);
  35 Serial.print("The Measured Distance in cm: ");
  36     Serial.println(cm);
37     if( cm < 100 )</pre>
  38
  39
      Serial.println("Alert!!");
  40
       Serial.print("**********************************);
  41
  42
  43 delay(1000);
  44 }
```