

Import and unzip the dataset

```
from google.colab import drive
drive.mount('/content/drive')
```

Mounted at /content/drive

```
#unzip the downloaded dataset
!unzip '/content/drive/MyDrive/damage vehicle.zip'
```

```
Archive: /content/drive/MyDrive/damage vehicle.zip
  creating: damage vehicle/
  creating: damage vehicle/body/ creating:
  damage vehicle/body/training/
  creating: damage vehicle/body/training/00-front/ inflating:
  damage vehicle/body/training/00-front/0001.jpeg inflating:
  damage vehicle/body/training/00-front/0002.JPEG inflating:
  damage vehicle/body/training/00-front/0003.JPEG inflating:
  damage vehicle/body/training/00-front/0004.JPEG inflating:
  damage vehicle/body/training/00-front/0005.JPEG inflating:
  damage vehicle/body/training/00-front/0006.JPEG inflating:
  damage vehicle/body/training/00-front/0007.JPEG inflating:
  damage vehicle/body/training/00-front/0008.jpeg inflating:
  damage vehicle/body/training/00-front/0009.JPEG inflating:
  damage vehicle/body/training/00-front/0010.JPEG inflating:
  damage vehicle/body/training/00-front/0011.JPEG inflating:
  damage vehicle/body/training/00-front/0012.jpeg inflating:
  damage vehicle/body/training/00-front/0013.JPEG inflating:
  damage vehicle/body/training/00-front/0014.JPEG inflating:
  damage vehicle/body/training/00-front/0015.JPEG inflating:
  damage vehicle/body/training/00-front/0016.JPEG inflating:
  damage vehicle/body/training/00-front/0017.JPEG inflating:
  damage vehicle/body/training/00-front/0018.JPEG inflating:
  damage vehicle/body/training/00-front/0019.JPEG inflating:
  damage vehicle/body/training/00-front/0020.jpeg inflating:
  damage vehicle/body/training/00-front/0021.JPEG inflating:
  damage vehicle/body/training/00-front/0022.JPEG inflating:
  damage vehicle/body/training/00-front/0023.JPEG inflating:
  damage vehicle/body/training/00-front/0024.JPEG inflating:
  damage vehicle/body/training/00-front/0025.jpeg inflating:
  damage vehicle/body/training/00-front/0026.JPEG inflating:
  damage vehicle/body/training/00-front/0027.JPEG inflating:
  damage vehicle/body/training/00-front/0028.JPEG inflating:
  damage vehicle/body/training/00-front/0029.JPEG inflating:
  damage vehicle/body/training/00-front/0030.JPEG inflating:
  damage vehicle/body/training/00-front/0031.JPEG inflating:
  damage vehicle/body/training/00-front/0032.JPEG inflating:
  damage vehicle/body/training/00-front/0033.JPEG inflating:
  damage vehicle/body/training/00-front/0034.JPEG inflating:
  damage vehicle/body/training/00-front/0035.jpeg inflating:
  damage vehicle/body/training/00-front/0036.JPEG inflating:
  damage vehicle/body/training/00-front/0037.JPEG inflating:
  damage vehicle/body/training/00-front/0038.JPEG inflating:
  damage vehicle/body/training/00-front/0039.JPEG inflating:
  damage vehicle/body/training/00-front/0040.JPEG inflating:
  damage vehicle/body/training/00-front/0041.JPEG inflating:
  damage vehicle/body/training/00-front/0042.JPEG inflating:
  damage vehicle/body/training/00-front/0043.JPEG inflating:
  damage vehicle/body/training/00-front/0044.JPEG inflating:
  damage vehicle/body/training/00-front/0045.JPEG inflating:
  damage vehicle/body/training/00-front/0046.jpeg inflating:
  damage vehicle/body/training/00-front/0047.JPEG inflating:
  damage vehicle/body/training/00-front/0048.JPEG inflating:
  damage vehicle/body/training/00-front/0049.JPEG inflating:
  damage vehicle/body/training/00-front/0050.JPEG inflating:
  damage vehicle/body/training/00-front/0051.JPEG inflating:
  damage vehicle/body/training/00-front/0052.JPEG inflating:
  damage vehicle/body/training/00-front/0053.JPEG
```

Image Preprocessing

1. Import The ImageDataGenerator Library

```
# Import required lib
```

```
from tensorflow.keras.preprocessing.image import ImageDataGenerator
```

2. Configure ImageDataGenerator Class

```
#Creating augmentation on training variable train_datagen  
= ImageDataGenerator(rescale=1./255,  
shear_range = 0.1, zoom_range=0.1, horizontal_flip=True)
```

```
# Creating augmentation on testing variable
```

```
test_datagen = ImageDataGenerator(rescale=1./255)
```

3. Apply ImageDataGenerator Functionality To Trainset And Testset

```
# Passing training data to train variable for body
```

```
xtrain = train_datagen.flow_from_directory('/content/damage vehicle/body/training',  
target_size=(224,224), class_mode='categorical', batch_size=10)
```

Found 979 images belonging to 3 classes.

```
# Passing testing data to test variable for body
```

```
xtest = test_datagen.flow_from_directory('/content/damage vehicle/body/validation',  
target_size=(224,224), class_mode='categorical', batch_size=10)
```

Found 171 images belonging to 3 classes.

```
# Passing training data to train variable for level
```

```
x_train = train_datagen.flow_from_directory('/content/damage vehicle/level/training',  
target_size=(224,224), class_mode='categorical', batch_size=10)
```

Found 979 images belonging to 3 classes.

```
# Passing testing data to test variable for level
```

```
x_test = test_datagen.flow_from_directory('/content/damage vehicle/level/validation',  
target_size=(224,224), class_mode='categorical', batch_size=10)
```

Found 171 images belonging to 3 classes.

Model Building

For Body

1. Importing The Model Building Libraries

```
#Import the library  
from tensorflow.keras.layers import Dense, Flatten, Input  
from tensorflow.keras.models import Model  
from tensorflow.keras.preprocessing import image  
from tensorflow.keras.preprocessing.image import ImageDataGenerator,  
load_img from tensorflow.keras.applications.vgg16 import VGG16,  
preprocess_input  
from glob import glob
```

```
import numpy as np

import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda, Dense, Flatten
from tensorflow.keras.models import Model
from tensorflow.keras.applications.vgg16 import VGG16
from tensorflow.keras.applications.vgg19 import VGG19
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator, load_img
from tensorflow.keras.models import Sequential
import numpy as np
from glob import glob
```

2. Loading The Model

```
IMAGE_SIZE = [224, 224]
```

```
train_path = '/content/damage_vehicle/body/training'
valid_path = '/content/damage_vehicle/body/validation'
```

```
vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', include_top=False)
```

Downloading data from https://storage.googleapis.com/tensorflow/keras-applications/vgg16/vgg16_weights_tf_dim_ordering_tf_kernels/58889256/58889256 [=====] - 3s 0us/step

<  >

3. Adding Flatten Layer

```
for layer in vgg16.layers:
    layer.trainable = False
```

```
folders = glob('/content/damage_vehicle/body/training/**')
```

```
folders

['/content/damage_vehicle/body/training/00-front',
 '/content/damage_vehicle/body/training/01-rear',
 '/content/damage_vehicle/body/training/02-side']
```

```
x = Flatten()(vgg16.output)
```

```
len(folders)

3
```

4. Adding Output Layer

```
prediction = Dense(len(folders), activation='softmax')(x)
```

5. Creating A Model Object

```
model = Model(inputs=vgg16.input, outputs=prediction)
```

```
model.summary()

Model: "model"
```

Layer (type)	Output Shape	Param #
=====		
input_1 (InputLayer)	[(None, 224, 2	
block1_conv1 (Conv2D)	(None, 224, 22	
block1_conv2 (Conv2D)	(None, 224, 22	
block1_pool (MaxPooling2D)	(None, 112, 11	

block2_pool (MaxPooling2D)	(None, 56, 56, 128)	0
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168
block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808
block4_conv3 (Conv2D)	(None, 28, 28, 512)	2359808
block4_pool (MaxPooling2D)	(None, 14, 14, 512)	0
block5_conv1 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv2 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv3 (Conv2D)	(None, 14, 14, 512)	2359808
block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0
flatten (Flatten)	(None, 25088)	0
dense (Dense)	(None, 3)	75267

```

=====
Total params: 14,789,955
Trainable params: 75,267
Non-trainable params: 14,714,688

```

6. Configure The Learning Process

```

model.compile(
    loss='categorical_crossentropy',
    optimizer='adam',
    metrics=['accuracy']
)

```

7. Train The Model

```

r = model.fit_generator(
    xtrain,
    validation_data=xtest,
    epochs=25,
    steps_per_epoch=len(xtrain),
    validation_steps=len(xtest)
)

```

/usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:6: UserWarning: `Model.fit_generator` is deprecated and will be

```

Epoch 1/25
98/98 [=====] - 23s 146ms/step - loss: 1.2077 - accuracy: 0.5465 - val_loss: 1.2900 - val_accuracy:
Epoch 2/25
98/98 [=====] - 13s 128ms/step - loss: 0.8364 - accuracy: 0.7028 - val_loss: 0.8665 - val_accuracy:
Epoch 3/25
98/98 [=====] - 13s 128ms/step - loss: 0.5293 - accuracy: 0.7998 - val_loss: 1.3260 - val_accuracy:
Epoch 4/25
98/98 [=====] - 12s 127ms/step - loss: 0.3978 - accuracy: 0.8611 - val_loss: 0.9842 - val_accuracy:
Epoch 5/25
98/98 [=====] - 12s 127ms/step - loss: 0.2783 - accuracy: 0.9030 - val_loss: 0.9397 - val_accuracy:
Epoch 6/25
98/98 [=====] - 13s 128ms/step - loss: 0.2690 - accuracy: 0.9070 - val_loss: 0.9892 - val_accuracy:
Epoch 7/25
98/98 [=====] - 12s 127ms/step - loss: 0.1788 - accuracy: 0.9448 - val_loss: 1.0052 - val_accuracy:
Epoch 8/25
98/98 [=====] - 13s 129ms/step - loss: 0.1671 - accuracy: 0.9469 - val_loss: 1.1693 - val_accuracy:
Epoch 9/25
98/98 [=====] - 13s 129ms/step - loss: 0.1277 - accuracy: 0.9561 - val_loss: 1.0058 - val_accuracy:
Epoch 10/25
98/98 [=====] - 13s 128ms/step - loss: 0.1184 - accuracy: 0.9591 - val_loss: 1.0620 - val_accuracy:
Epoch 11/25
98/98 [=====] - 13s 130ms/step - loss: 0.0963 - accuracy: 0.9745 - val_loss: 1.1219 - val_accuracy:
Epoch 12/25

```

```

98/98 [=====] - 13s 129ms/step - loss: 0.0857 - accurac
Epoch 13/25
98/98 [=====] - 13s 129ms/step - loss: 0.0582 - accurac
Epoch 14/25
98/98 [=====] - 13s 129ms/step - loss: 0.0688 - accurac
Epoch 15/25
98/98 [=====] - 13s 131ms/step - loss: 0.0709 - accurac
Epoch 16/25
98/98 [=====] - 13s 128ms/step - loss: 0.0895 - accurac

Epoch 17/25 - 13s 129ms/step - loss: 0.0609 - accurac
98/98 [=====]
Epoch 18/25 - 13s 128ms/step - loss: 0.0998 - accurac
98/98 [=====]

Epoch 19/25
98/98 [=====]

Epoch 20/25
98/98 [=====]
Epoch 21/25
98/98 [=====]
Epoch 22/25
98/98 [=====]
Epoch 23/25
98/98 [=====]

Epoch 24/25
98/98 [=====]
Epoch 25/25
98/98 [=====]

```



8. Save The Model

```

from tensorflow.keras.models import load_model

model.save('/content/damage_vehicle/Model/body.h5')

```

9. Test The Model

```

f
r
o
m
t
e

```

```

1/1 [=====] - 0s 148ms/step
front

```

Model Building

For Level



1. Importing The Model Building Libraries

```
import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda, Dense, Flatten
from tensorflow.keras.models import Model
from tensorflow.keras.applications.vgg16 import
VGG16 from tensorflow.keras.applications.vgg19
import VGG19 from tensorflow.keras.preprocessing
import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator,load_img
from tensorflow.keras.models import Sequential
import numpy as np
from glob import
glob
```

2. Loading The Model

```
IMAGE_SIZE = [224, 224]

train_path = '/content/damage vehicle/level/training'
valid_path = '/content/damage vehicle/level/validation'

vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', include_top=False)
```

3. Adding Flatten Layer

```
for layer in vgg16.layers:
    layer.trainable = False

folders = glob('/content/damage vehicle/level/training/*')

fold
ers

['/content/damage vehicle/level/training/03-severe',
 '/content/damage vehicle/level/training/02-moderate',
 '/content/damage vehicle/level/training/01-minor']
```

```
x = Flatten()(vgg16.output)
```

```
len(folders)
```

```
3
```

4. Adding Output Layer

```
prediction = Dense(len(folders), activation='softmax')(x)
```

5. Creating A Model Object

```
model = Model(inputs=vgg16.input, outputs=prediction)
```

```
model.summary()
```

```
Model: "model_1"
```

Layer (type)	Output Shape	Param #
=====		
input_2 (InputLayer)	[(None, 224, 224, 3)]	0
block1_conv1 (Conv2D)	(None, 224, 224, 32)	320
block1_conv2 (Conv2D)	(None, 224, 224, 32)	320
block1_pool (MaxPooling2D)	(None, 112, 112, 32)	0
block2_conv1 (Conv2D)	(None, 112, 112, 64)	640

block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808
block4_conv3 (Conv2D)	(None, 28, 28, 512)	2359808
block4_pool (MaxPooling2D)	(None, 14, 14, 512)	0
block5_conv1 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv2 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv3 (Conv2D)	(None, 14, 14, 512)	2359808
block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0
flatten_1 (Flatten)	(None, 25088)	0
dense_1 (Dense)	(None, 3)	75267

```

B
=====
Total params: 14,789,955
Trainable params: 75,267
Non-trainable params: 14,714,688

```

6. Configure The Learning Process

```

model.compile(
    loss='categorical_crossentropy',
    optimizer='adam',
    metrics=['accuracy']
)

```

7. Train The Model

```

r = model.fit_generator(
    x_train,
    validation_data=x_test,
    epochs=25,
    steps_per_epoch=len(x_train),
    validation_steps=len(x_test)
)

```

/usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:6: UserWarning: `Model.fit_generator` is deprecated and will be

```

Epoch 1/25
98/98 [=====] - 14s 133ms/step - loss: 1.1629 - accurac
Epoch 2/25
98/98 [=====] - 13s 130ms/step - loss: 0.7157 - accurac
Epoch 3/25
98/98 [=====] - 13s 130ms/step - loss: 0.4978 - accurac
Epoch 4/25
98/98 [=====] - 13s 128ms/step - loss: 0.5277 - accurac

Epoch 5/25 - 13s 128ms/step - loss: 0.3763 - accurac
98/98 [=====]
Epoch 6/25 - 13s 128ms/step - loss: 0.2445 - accurac
98/98 [=====]
Epoch 7/25
98/98 [=====]

Epoch 8/25
98/98 [=====]
Epoch 9/25
98/98 [=====]
Epoch 10/25
98/98 [=====]
Epoch 11/25
98/98 [=====]

Epoch 12/25
98/98 [=====]
Epoch 13/25
98/98 [=====]

Epoch 14/25

```

```

98/98 [=====] - 12s 127ms/step - loss: 0.0474 - accurac
Epoch 15/25
98/98 [=====] - 13s 129ms/step - loss: 0.0366 - accurac
Epoch 16/25
98/98 [=====] - 13s 128ms/step - loss: 0.0493 - accurac
Epoch 17/25
98/98 [=====] - 13s 128ms/step - loss: 0.0320 - accurac
Epoch 18/25
98/98 [=====] - 13s 129ms/step - loss: 0.0363 - accurac

Epoch 19/25 - 13s 128ms/step - loss: 0.0298 - accurac
98/98 [=====]
Epoch 20/25
98/98 [=====]
Epoch 21/25
98/98 [=====]

Epoch 22/25
98/98 [=====]
Epoch 23/25
98/98 [=====]
Epoch 24/25
98/98 [=====]
Epoch 25/25
98/98 [=====]

```



8. Save The Model

```

from tensorflow.keras.models import load_model

model.save('/content/damage_vehicle/Model/level.h5')

```

9. Test The Model

```

from tensorflow.keras.models import load_model import cv2
from skimage.transform import resize

model = load_model('/content/damage_vehicle/Model/level.h5')

def detect(frame):
    img = cv2.resize(frame,(224,224))
    img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)

    if(np.max(img)>1):
        img = img/255.0
    img = np.array([img])
    prediction = model.predict(img)
    label = ["minor","moderate","severe"]
    preds = label[np.argmax(prediction)]
    return preds

import numpy as np

data = "/content/damage_vehicle/level/validation/01 -minor/0005.JPEG"
image = cv2.imread(data)
print(detect(image))

1/1 [=====] - 0s 142ms/step
minor

```


