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PROJECT NAME	FIRE MANAGEMENT
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ASSIGNMENT 4

### Ultrasonic sensor simulation in Wokwi

### **Question:**

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

#### Code:

```
#include <PubSubClient.h> void callback(char*
subscribetopic, byte* payload, unsigned int
payloadLength);
//-----credentials of IBM Accounts----#define
ORG "ge3f42"//IBM ORGANITION ID
#define DEVICE_TYPE "ESP32"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "3A-85-DD-94-7D-BC"//Device ID mentioned in ibm watson
IOT Platform #define TOKEN "sPNIlvo1-SQoK4Dhx8" //Token
String data3; char
server[] = ORG
".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-
2/evt/Data/fmt/json"; char subscribetopic[] =
```

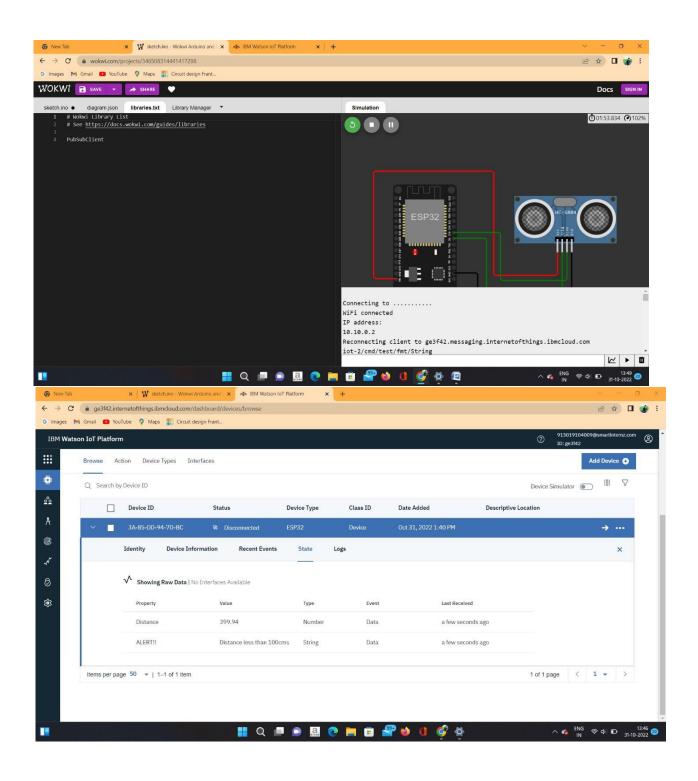
```
"iot-2/cmd/test/fmt/String"; char
authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback
,wifiClient); const int trigPin = 5; const
int echoPin = 18; #define SOUND SPEED
0.034 long duration; float distance; void
setup()
Serial.begin(115200);
pinMode(trigPin,
OUTPUT);
pinMode(echoPin,
INPUT);
wificonnect();
mqttconnect();
} void
loop()
digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
digitalWrite(trigPin, LOW); duration
 = pulseIn(echoPin, HIGH); distance =
 Serial.print("Distance (cm): ");
 Serial.println(distance);
 if(distance>100)
 Serial.println("ALERT!!");
 delay(100);
 delay(100); if
 (!client.loop()) {
 delay(100);
void PublishData(float dist) {
String payload = "{\"Distance\":";
 payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
 payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
```

```
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");
} else {
    Serial.println("Publish failed");
} void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
        Serial.print("."); delay(100); } initManagedDevice();
        Serial.println();
}
}
```

```
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(100);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
 else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";}
DIAGRAM. JSON
  "version": 1,
  "author": "sweetysharon",
  "editor": "wokwi",
  "parts": [
   { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -112.87, "attrs": {} },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
 ],
  "connections": [
   [ "esp:TX0", "$serialMonitor:RX", "", [] ],
[ "esp:RX0", "$serialMonitor:TX", "", [] ],
```

```
"esp:VIN",
 "ultrasonic1:VCC
 ", "red",
 [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
[ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ]
 "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ]
[ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
```

## **OUTPUT:**



# **CIRCUIT DIAGRAM:**

