```
/*
* Ultrasonic.h
* Library for Ultrasonic Ranging Module in a minimalist way
*/
#ifndef Ultrasonic_h
#define Ultrasonic_h
* Values of divisors
*/
#define CM 28
#define INC 71
class Ultrasonic {
 public:
  Ultrasonic(uint8_t sigPin) : Ultrasonic(sigPin, sigPin) {};
  Ultrasonic(uint8_t trigPin, uint8_t echoPin, unsigned long timeOut = 20000UL);
  unsigned int read(uint8_t und = CM);
  unsigned int distanceRead(uint8_t und = CM) __attribute__ ((deprecated ("This method is
deprecated, use read() instead.")));
  void setTimeout(unsigned long timeOut) {timeout = timeOut;}
  void setMaxDistance(unsigned long dist) {timeout = dist*CM*2;}
 private:
  uint8_t trig;
  uint8_t echo;
  boolean threePins = false;
```

```
unsigned long previousMicros;
unsigned long timeout;
unsigned int timing();
};
#endif // Ultrasonic_h
```