# **ASSIGNMENT 4**

### Ultrasonic sensor simulation in Wokwi

Date	27 October2022
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Maximum Marks	2 Marks

### **Ouestion-1:**

Write a code and connections in wokwi for the ultrasonic sensor.

#### Code:

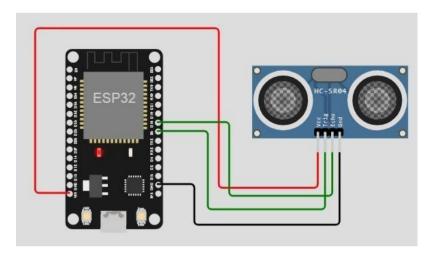
```
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5:
const int echoPin = 18;
#define SOUND SPEED 0.034
long duration:
float distance;
void setup() {
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
void loop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)</pre>
Serial.println("ALERT!!");
delay(1000);
```

```
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
delay(1000);
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
```

```
initManagedDevice();
Serial.println();
void wificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL CONNECTED) {
delay(500);
Serial.print(".");
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {</pre>
```

```
//Serial.print((char)payload[i]);
data3 += (char)pavload[i]:
Serial.println("data: "+ data3):
data3="";
}
Diagram.ison:
  "version": 1,
 "author": "G7"
  "editor": "wokwi",
  "parts": [
   { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": -4.67, "left": -114.67, "attrs": {} },
   { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 15.96, "left": 89.17, "attrs": {} }
  1,
  "connections": [
   [ "esp:TX0", "$serialMonitor:RX", "", [] ],
    [ "esp:RX0", "$serialMonitor:TX", "", [] ],
      "esp:VIN",
      "ultrasonic1:VCC",
      "red",
      [ "h-37.16", "v-178.79", "h200", "v173.33", "h100.67" ]
    [ "esp:GND.1", "ultrasonic1:GND", "black", [ "h39.87", "v44.04", "h170" ] ],
   [ "esp:D5", "ultrasonic1:TRIG", "green", [ "h54.54", "v85.07", "h130.67" ] ],
    [ "esp:D18", "ultrasonic1:ECHO", "green", [ "h77.87", "v80.01", "h110" ] ]
```

# } Circuit Diagram:



# Output:

## Wokwi output:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

### IBM cloud output:

