### **ASSIGNMENT-4**

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Team ID	PNT2022TMID51073
Project Name	SmartFarmer – Iot Enabled Smart Farming Application

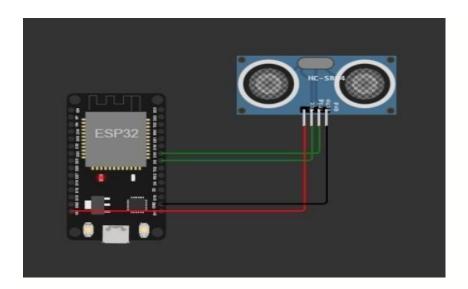
### **CODE:**

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "hzu4n4"
#define DEVICE TYPE "Harini"
#define DEVICE_ID "27092002"
#define TOKEN ")onRVxyT7sOrIDrGoh"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/data/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
```

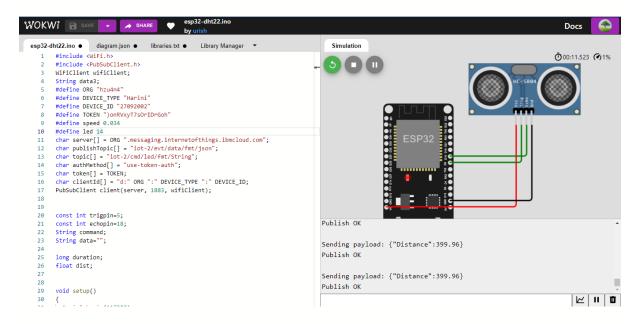
```
mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
   mqttConnect();
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
   Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
   Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
```

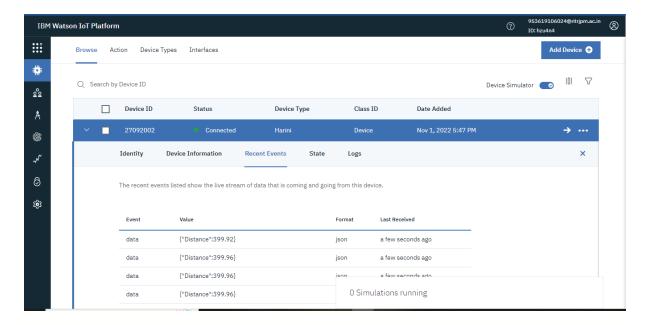
```
digitalWrite(trigpin,LOW);
digitalWrite(trigpin, HIGH);
delayMicroseconds(10);
digitalWrite(trigpin, LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){</pre>
  String payload = "{\"Alert Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
  }
}
  if(dist>100){
  String payload = "{\"Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
  }else {
    Serial.println("Publish FAILED");
  }
}
}
```

### **CONNECTIONS:**



# **OUTPUT:**





# **WOKWI LINK:**

https://wokwi.com/projects/347132377024168532