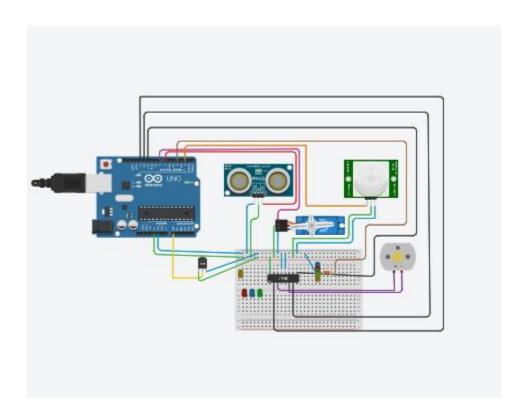
## **Home Automation using IOT**



## CODE:

```
#include<Servo.h>
const int pingPin = 7;
int servoPin = 8;
Servo servo1;
void setup() {
// initialize serial communication:
Serial.begin(9600);
servo1.attach(servoPin);
```

```
pinMode(2,INPUT);
pinMode(4,OUTPUT);
pinMode(11,OUTPUT);
pinMode(12,OUTPUT);
pinMode(13,OUTPUT);
pinMode(A0,INPUT);
digitalWrite(2,LOW);
digitalWrite(11,HIGH);
}
void loop() {
long duration, inches, cm;
pinMode(pingPin, OUTPUT);
digitalWrite(pingPin, LOW);
delayMicroseconds(2);
digitalWrite(pingPin, HIGH);
delayMicroseconds(5);
digitalWrite(pingPin, LOW);
// The same pin is used to read the signal from the PING))): a HIGH pulse
// whose duration is the time (in microseconds) from the sending of the ping
// to the reception of its echo off of an object.
pinMode(pingPin, INPUT);
duration = pulseIn(pingPin, HIGH);
// convert the time into a distance
inches = microsecondsToInches(duration);
cm = microsecondsToCentimeters(duration);
//Serial.print(inches);
//Serial.print("in, ");
//Serial.print(cm);
//Serial.print("cm");
```

```
//Serial.println();
//delay(100);
servo1.write(0);
if(cm < 40)
servo1.write(90);
delay(2000);
}
else
servo1.write(0);
}
// PIR with LED starts
int pir = digitalRead(2);
if(pir == HIGH)
{
digitalWrite(4,HIGH);
delay(1000);
}
else if(pir == LOW)
{
digitalWrite(4,LOW);
}
//temp with fan
float value=analogRead(A0);
float temperature=value*0.48;
Serial.println("temperature");
Serial.println(temperature);
if(temperature > 20)
```

```
digitalWrite(12,HIGH);
digitalWrite(13,LOW);
}
else
{
digitalWrite(12,LOW);
digitalWrite(13,LOW);
}

long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
}
```

## **OUTPUT:**

