Assignment - 4

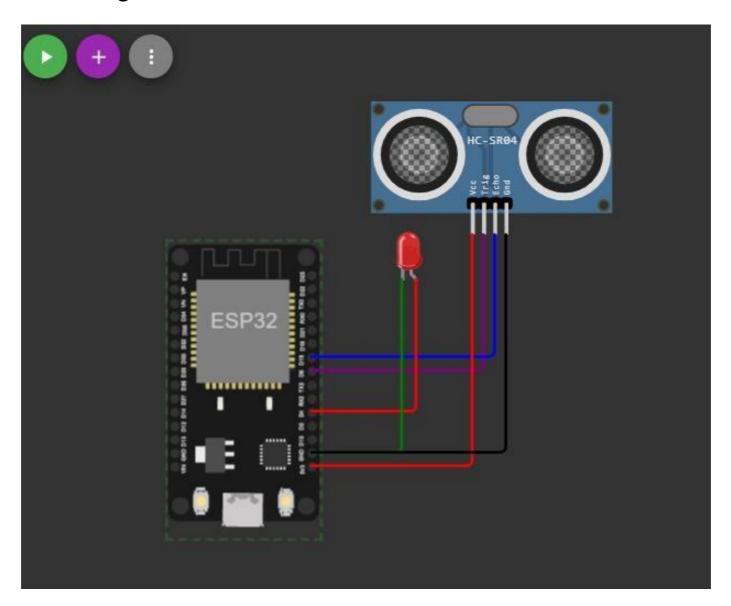
Assignment Date	16/11/2022
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Question:

Write code and connections in WokWi for Ultrasonic Sensor. Whenever the distance is less 100cm, send "Alert" to IBM cloud and display in device recent events.

Solution:

Circuit Diagram:



Code:

```
sketch.ino
                diagram.json
                                      libraries.txt Library Manager ▼
           #include <WiFi.h>
          #include <PubSubClient.h>
          void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);
          #define ORG "um5y3e"//IBM ORGANITION ID
         #define DEVICE_TYPE "ESP32" //Device type mentioned in ibm watson IOT Platform #define DEVICE_ID "ESP3240P"//Device ID mentioned in ibm watson IOT Platform
          #define TOKEN "Sv*Ygwum-RMJXiOBy?"//Token
          float dist;
         //----Customise the above values------
char server[] = ORG ".messaging.internetofthings.ibmcloud.com"; // Server Name
char publishTopic[] = "iot-2/evt/Data/fat/json";// topic name and type of event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING
          char authMethod[] =
          char token[] = TOKEN;
char clientid[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
          WiFiClient wificlient; // creating the instance for wificlient
          PubSubClient client(server, 1883, callback,wificlient); //calling the predefined client id by passing parameter like server id, portand wificredential
          int trig = 5;
             Serial.begin(115200);
             pinMode(trig, OUTPUT);
pinMode(echo, INPUT);
pinMode(LED, OUTPUT);
             delay(10);
```

```
wificonnect();
mqttconnect();

mqttconnect();

woid loop()// Recursive Function

digitalwrite(trig, LOW);

digitalwrite(trig, LOW);

digitalwrite(trig, LOW);

delayWicroseconds(18);

delayWicroseconds(18);

delayWicroseconds(18);

float dur - pulseIn(echo, HIGH);

float dist = (dur * 0.0943)/2;

Serial.println(dist);

PublishData(dist);

delay(1000);

if (Cilent.looy()) {

mqttconnect();

mqttconnect();

//.retrieving to cloud...

//.retrieving to cloud...

//.retrieving to stoud...

String object;
if (dist <1000)

digitalwrite(LED, HIGH);
serial.println(object is near*);</pre>
```

```
Serial.println('object is near");

object = "Near";

else

digitalwrite(LED, LON);

serial.println('no object found");

object - "No";

String payload="\"distance\":";

payload += object;

payload += object
```

```
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength){

Serial.print("callback invoked for topic: ");

Serial.println(subscribetopic);

for (int i=0; i < payloadLength; i++) {

    //Serial.print((char)payload[1]);

    data3 += (char)payload[1];

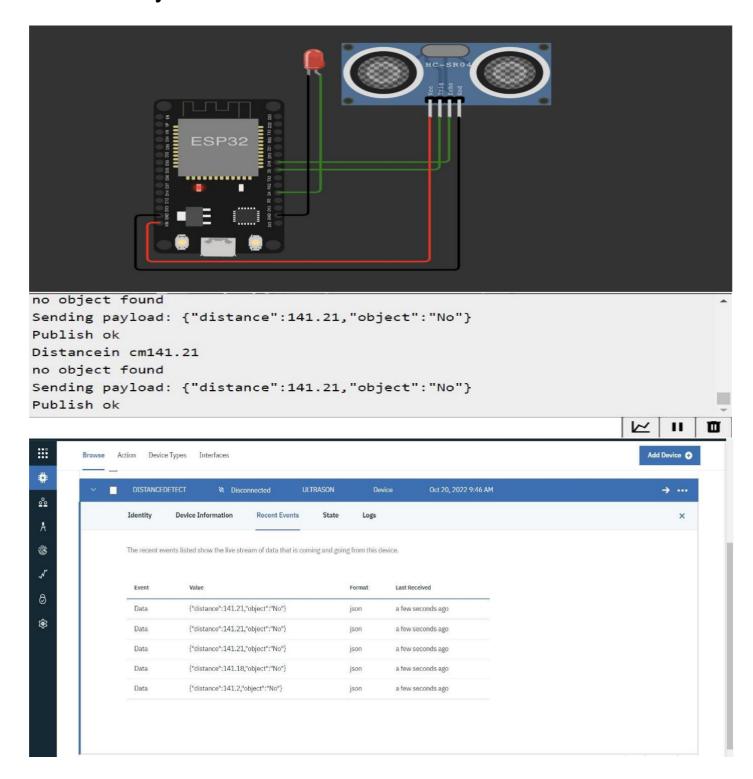
}

data3 = "";

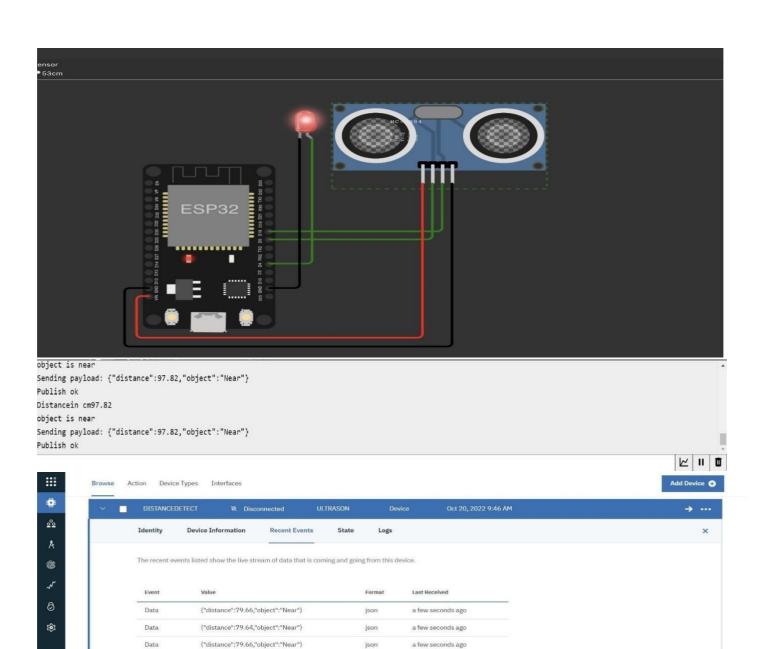
442
}</pre>
```

OUTPUT:

When the Object is Far:



When the Object is Near:



json

a few seconds ago

a few seconds ago

Data

Data

{"distance":79.64,"object":"Near"}

{"distance":79.66,"object":"Near"}