S P R I N T   P L A N

Form an ad hoc network to collaborate and communicate with the UAVs	**1**
Detect the fire with the help of visual sensor to identify the event	**2**
Identify the location of the fire to proceed with the fire extinguishing task	**3**
To avoid get damaged during the task, the UAV continuously monitors its system status	**4**
UAV needs to avoid the obstacles in order to avoid accident in its path to the fire location	**5**