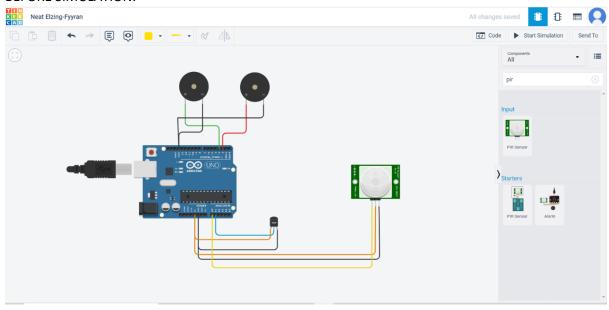
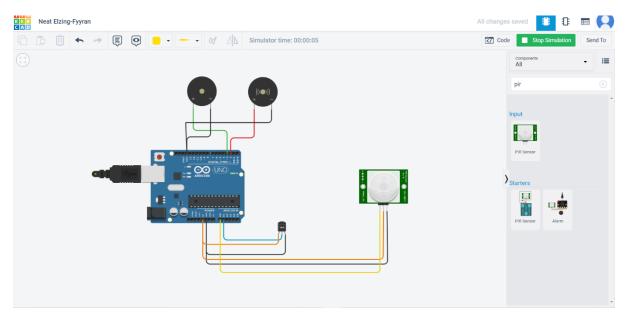
## **BEFORE SIMULATION:**



## AFTER SIMULATION:



## CODE:

```
Code ► Start Simulation Send To
                                                           - A = A
      Text
                                                                                                                                                    1 (Arduino Uno R3)
       byte tmp=A1;
byte buzzer=2;
byte buzzer1=3;
byte PIR=A0;
int tmplevel,tmplevel1,PIR1;
       6
7
8
             void setup()
               pinMode(buzzer, OUTPUT);
pinMode(tmp,INPUT);
pinMode(FIR, INPUT);
pinMode(buzzer, OUTPUT);
pinMode(buzzer, OUTPUT);
pinMode(buzzer1, OUTPUT);
Serial.begin(9400);
     9
pinrac
pinMode(bu.
serial.begin(94c)

tovoid loop()

tmplevel=analogRead(tmp);

PIR1=digitalRead(PIR);

tmplevel1=tmplevel*0.488;

//Temperature chech
if(tmplevel1>60)

serial.println("Temperature High");

serial.println(tmplevel1);
digitalWrite(buzzer,HIGH);
delay(100);
}

and "Temperature Low");

regr, LOW);

}
else
{
   Serial.println("Temperature Low");
   digitalWrite(buzzer, LOW);
   .
}

               //Movement check if (PIR1==HIGH)
     34
     35
     36
                Serial.println("Movement Detected");
digitalWrite(buzzer1, HIGH);
     37
     39
                    delay(100);
     40
                else
     42
                     Serial.println("Movement not Detected");
    43
                     digitalWrite(buzzer1,LOW);
    44
    45
    46 }
   Serial Monitor
```