

**Assignment -4**  
Python Programming

|                     |                 |
|---------------------|-----------------|
| Assignment Date     | 17 October 2022 |
| Student Name        | Shalini S       |
| Student Roll Number | 211419106250    |
| Maximum Marks       | 2 Marks         |

**Question-1:**

Write python code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send “alert” to IBM cloud and display in device recent events.

**Solution:**

```
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)

GPIO_ECHO = 13
GPIO_TRIG = 11

GPIO.setup(GPIO_ECHO, GPIO.IN)
GPIO.setup(GPIO_TRIG, GPIO.OUT)

GPIO.output(GPIO_TRIG, GPIO.LOW)
Time.sleep(2)

GPIO.output(GPIO_TRIG, GPIO.HIGH)
time.sleep(0.00001)
GPIO.output(GPIO_TRIG, GPIO.LOW)

while GPIO.input(GPIO_ECHO)==0:
    start_time = time.time()

while GPIO.input(GPIO_ECHO)==1:
    Bounce_back_time = time.time()

pulse_duration = Bounce_back_time - start_time
distance = round(pulse_duration * 17150, 2)
print (f"Distance: {distance} cm")

while True:
    if distance < 100 :
        print('!!!!!!!!! Alert !!!!!!!!!!')
```

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import time
```

```
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```

```
GPIO_ECHO = 13
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```
GPIO_TRIG = 11
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GPIO.setup(GPIO_ECHO, GPIO.IN)
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GPIO.output(GPIO_TRIG, GPIO.LOW)
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GPIO.output(GPIO_TRIG, GPIO.HIGH)
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time.sleep(0.00001)
```

```
GPIO.output(GPIO_TRIG, GPIO.LOW)
```

```
while GPIO.input(GPIO_ECHO)==0:
```

```
    start_time = time.time()
```

```
while GPIO.input(GPIO_ECHO)==1:
```

```
    Bounce_back_time = time.time()
```

```
pulse_duration = Bounce_back_time - start_time
```

```
distance = round(pulse_duration * 17150, 2)
```

```
print (f"Distance: {distance} cm")
```

```
#print ("Distance:",distance,"cm")
```

```
while True:
```

```
    if distance < 100 :
```

```
        print('!!!!!!! Alert !!!!!!!!')
```