ASSIGNMENT-4 PYTHON PROGRAMMING

Date	17 October 2022
Student Name	Nivetha.R
Student Roll Number	211419106188
Maximum Marks	2 Marks

Question:

Write code and connections in wokwi for the ultrasonic sensor.

Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events.

Upload document with wokwi share link and images of IBM cloud.

Solution:

```
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO ECHO = 13
GPIO_TRIG = 11
GPIO.setup(GPIO ECHO, GPIO.IN)
GPIO.setup(GPIO_TRIG, GPIO.OUT)
GPIO.output(GPIO TRIG, GPIO.LOW)
Time.sleep(2)
GPIO.output(GPIO_TRIG, GPIO.HIGH)
time.sleep(0.00001)
GPIO.output(GPIO_TRIG, GPIO.LOW)
while GPIO.input(GPIO ECHO)==0:
  start_time = time.time()
while GPIO.input(GPIO_ECHO)==1:
  Bounce_back_time = time.time()
pulse duration = Bounce back time - start time
distance = round(pulse_duration * 17150, 2)
```

```
print (f"Distance: {distance} cm")
#print ("Distance:",distance,"cm")
while True:
  if distance < 100:
    print('!!!!!!!! Alert !!!!!!!!)
P5.py - C:/Users/HP/P5.py (3.10.7)
 File Edit Format Run Options Window Help
 import RPi.GPIO as GPIO
 import time
 GPIO.setmode (GPIO.BCM)
 GPIO ECHO = 13
 GPIO TRIG = 11
 GPIO.setup(GPIO ECHO, GPIO.IN)
 GPIO.setup(GPIO TRIG, GPIO.OUT)
 GPIO.output (GPIO TRIG, GPIO.LOW)
 Time.sleep(2)
 GPIO.output (GPIO TRIG, GPIO.HIGH)
 time.sleep(0.00001)
 GPIO.output (GPIO TRIG, GPIO.LOW)
 while GPIO.input(GPIO ECHO) == 0:
    start time = time.time()
 while GPIO.input(GPIO ECHO) == 1:
    Bounce back time = time.time()
 pulse duration = Bounce back time - start time
 distance = round(pulse duration * 17150, 2)
 print (f"Distance: {distance} cm")
 #print ("Distance:", distance, "cm")
 while True:
    if distance < 100 :
         print('!!!!!!!!! Alert !!!!!!!!)
```