

B3-3M5E

ASSIGNMENT-1

CODE:

```
#include <Servo.h>

int output1Value = 0;
int sen1Value = 0;
int sen2Value = 0;
int const gas_sensor = A1;
int const LDR = A0;
int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)
{
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);

    // Reads the echo pin, and returns the sound wave travel time
    in microseconds
    return pulseIn(echoPin, HIGH);
}
```

```

Servo servo_7;
void setup()
{
    Serial.begin(9600);           //initialize serial communication
    pinMode(A0, INPUT);           //LDR
    pinMode(A1, INPUT);           //gas sensor
    pinMode(13, OUTPUT);          //connected to relay
    servo_7.attach(7, 500, 2500); //servo motor
    pinMode(8, OUTPUT);           //signal to piezo buzzer
    pinMode(9, INPUT);            //signal to PIR
    pinMode(10, OUTPUT);          //signal to npn as switch
    pinMode(4, OUTPUT);           //Red LED
    pinMode(3, OUTPUT);           //Green LED
}
void loop()
{
    //-----light intensity control-----//
    //-----
    int val1 = analogRead(LDR);
    if (val1 > 500)
    {
        digitalWrite(13, LOW);
        Serial.print("Bulb ON = ");
        Serial.print(val1);
    }
}

```

```

else
{
    digitalWrite(13, HIGH);
    Serial.print("Bulb OFF = ");
    Serial.print(val1);
}

//-----
//----- light & fan control -----//
//-----

sen2Value = digitalRead(9);
if (sen2Value == 0)
{
    digitalWrite(10, LOW); //npn as switch OFF
    digitalWrite(4, HIGH); // Red LED ON, indicating no motion
    digitalWrite(3, LOW); //Green LED OFF, since no Motion
detected
    Serial.print("    || NO Motion Detected    ");
}

if (sen2Value == 1)
{
    digitalWrite(10, HIGH); //npn as switch ON
    delay(5000);
    digitalWrite(4, LOW); // RED LED OFF
    digitalWrite(3, HIGH); //GREEN LED ON , indicating motion
detected

```

```
Serial.print("      || Motion Detected!    ");  
}
```

```
//-----
```

```
    // ----- Gas Sensor -----//
```

```
//-----
```

```
int val = analogRead(gas_sensor);    //read sensor value
```

```
Serial.print("|| Gas Sensor Value = ");
```

```
Serial.print(val);                    //Printing in serial monitor
```

```
//val = map(val, 300, 750, 0, 100);
```

```
if (val > limit)
```

```
{
```

```
tone(8, 650);
```

```
}
```

```
delay(300);
```

```
noTone(8);
```

```
//-----
```

```
    //----- servo motor -----//
```

```
//-----
```

```
sen1Value = 0.01723 * readUltrasonicDistance(6, 6);
```

```
if (sen1Value < 100)
```

```
{
```

```
        servo_7.write(90);
        Serial.print("          || Door Open! ; Distance = ");
        Serial.print(sen1Value);
        Serial.print("\n");

    }
else
    {
        servo_7.write(0);
        Serial.print("          || Door Closed! ; Distance = ");
        Serial.print(sen1Value);
        Serial.print("\n");
    }
    delay(10); // Delay a little bit to improve simulation
performance
}
```