Develop the Python Script

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Project Name	Smart waste management system for metropolitan cities

Interfacing Load Sensor HX711 with

ESP32

WOKWI Code:

Main. py

```
from hx711 import HX711
hx = HX711(5,4,64)
print(1)
while True:
    hx.tare()
    read = hx.read()
    #average=hx.read_average()
    value=hx.read_average()
    print(value,"#")
```

hx711.py

```
from machine import Pin, enable_irq, disable_irq, idle

class HX711:
    def __init__(self, dout, pd_sck, gain=128):

        self.pSCK = Pin(pd_sck , mode=Pin.OUT)
        self.pOUT = Pin(dout, mode=Pin.IN, pull=Pin.PULL_DOWN)
        self.pSCK.value(False)

        self.GAIN = 0
        self.OFFSET = 0
        self.SCALE = 1

        self.time_constant = 0.1
        self.filtered = 0

        self.set_gain(gain);

    def set_gain(self, gain):
        if gain is 128:
            self.GAIN = 1
```

```
elif gain is 64:
        self.GAIN = 3
    elif gain is 32:
        self.GAIN = 2
    self.read()
    self.filtered = self.read()
    print('Gain & initial value set')
def is_ready(self):
    return self.pOUT() == 0
def read(self):
   # wait for the device being ready
   while self.pOUT() == 1:
        idle()
    # shift in data, and gain & channel info
    result = 0
    for j in range(24 + self.GAIN):
        state = disable irq()
        self.pSCK(True)
        self.pSCK(False)
        enable_irq(state)
        result = (result << 1) | self.pOUT()</pre>
    # shift back the extra bits
    result >>= self.GAIN
   # check sign
    if result > 0x7ffffff:
        result -= 0x1000000
    return result
def read_average(self, times=3):
   s = 0
    for i in range(times):
        s += self.read()
    ss=(s/times)/210
    return '%.1f' %(ss)
def read_lowpass(self):
    self.filtered += self.time_constant * (self.read() - self.filtered)
    return self.filtered
def get_value(self, times=3):
    return self.read_average(times) - self.OFFSET
def get_units(self, times=3):
    return self.get_value(times) / self.SCALE
def tare(self, times=15):
```

```
s = self.read_average(times)
    self.set_offset(s)
def set_scale(self, scale):
    self.SCALE = scale
def set_offset(self, offset):
    self.OFFSET = offset
def set_time_constant(self, time_constant = None):
    if time_constant is None:
        return self.time_constant
    elif 0 < time_constant < 1.0:</pre>
        self.time_constant = time_constant
def power_down(self):
    self.pSCK.value(False)
    self.pSCK.value(True)
def power_up(self):
    self.pSCK.value(False)
```

