

PROJECT DEVELOPMENT PHASE

Team ID	PNT2022TMID50055
Project Name	Smart Waste Management System For Metropolitan Cities

DELIVERY OF SPRINT 3

```
import RPi.GPIO as GPIO
```

```
import yagmail
```

```
import time
```

```
import mysql.connector
```

```
TRIG=21
```

```
ECHO=20
```

```
dusbinLevellInper=0
```

```
confirmtion=0
```

```
GPIO.setmode(GPIO.BCM)
```

```
GPIO.setup(TRIG,GPIO.OUT)
```

```
GPIO.setup(ECHO,GPIO.IN)
```

```
GPIO.setup(19, GPIO.OUT)
```

```
def mailsender():
```

```
    if(confirmtion==3):
```

```
        mydb = mysql.connector.connect(
```

```
host="192.168.143.95",  
user="root",  
password="mysqlpassword",  
database="lbnDataBase"  
)
```

```
mycursor = mydb.cursor()
```

```
confirmtion=0
```

```
sql = "SELECT * FROM dsbn WHERE dusid =1"
```

```
mycursor.execute(sql)
```

```
myresult = mycursor.fetchall()
```

```
Frommailadress="from@gmail.com"
```

```
password="myapp password"
```

```
yag = yagmail.SMTP(Frommailadress,password)
```

```
yag.send("TO@gmail.com",
```

```
""
```

```
"Level of the dustbin is "+str(myresult[0][1])+
```

```
" locations of the dustbin "+str(myresult[0][3])+ " "+str(myresult[0][2])+""")
```

```
print("sended successfull")
```

```
else:
```

```
print(confirmtion)
```

```
def DataBaseCon():
```

```
mydb = mysql.connector.connect(
```

```
host="192.168.143.95",  
user="root",  
password="mynewpassword",  
database="IbmDataBase"  
)
```

```
mycursor = mydb.cursor()
```

```
sql = "UPDATE dsbn SET dusLevel = "+str(dusbinLevelInper)+" WHERE dusId = '1'"
```

```
mycursor.execute(sql)
```

```
mydb.commit()
```

```
print(mycursor.rowcount, "record(s) affected")
```

```
def ledblinkon():
```

```
    GPIO.output(19, GPIO.HIGH)
```

```
def ledblinkoff():
```

```
    GPIO.output(19, GPIO.LOW)
```

```
while True:
```

```
    print("distance measurement in progress")
```

```
    GPIO.output(TRIG,False)
```

```
    print("waiting for sensor to settle")
```

```
    time.sleep(0.2)
```

```
    GPIO.output(TRIG,True)
```

```
    time.sleep(0.00001)
```

```
    GPIO.output(TRIG,False)
```

```
while GPIO.input(ECHO)==0:
    pulse_start=time.time()
while GPIO.input(ECHO)==1:
    pulse_end=time.time()
pulse_duration=pulse_end-pulse_start
distance=pulse_duration*17150
distance=round(distance,2)
print("distance:",distance,"cm")
time.sleep(2)
```

```
if(distance>=60):
    dusbinLevelInper=0
    ledblinkoff()
elif(distance<=60 and distance>=45):
    dusbinLevelInper=25
    ledblinkoff()
elif(distance<=45 and distance>=30):
    dusbinLevelInper=50
    ledblinkoff()
elif(distance<=30 and distance>=10):
    dusbinLevelInper=80
    ledblinkoff()
```

```
else:
    dusbinLevelInper=100
    ledblinkon()
    confirmtion+=1
    mailsender()
```

DataBaseCon()

time.sleep(20)