

1. Write Code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to IBM cloud and display in device recent events.

**Solution:**

```
// Pins
const int
TRIG_PIN = 7 ;
const int
ECHO_PIN = 8;

// Anything over 400 cm (23200 us pulse) is "out
of range" const unsigned int MAX_DIST =
23200;

void setup() {

// The Trigger pin will tell the sensor to
range find Pin Mode(TRIG_PIN,
OUTPUT);
digitalWrite(TRIG_PIN, LOW);

// Set Echo pin as input to measure the duration of
// pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT ) ;
```

```

// We'll use the serial monitor to view the sensor
output Serial.begin(9600);
}
void
loop()
{ unsign
ed long
t1;

unsigned long t2;
unsigned long
pulse_width; float
cm;
float inches;

// Hold the trigger pin high for at
least 10 us digitalWrite(TRIG_PIN,
HIGH); delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);

// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0 );

// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow
after-70 min t1= micros ();

```

```

while
  (digitalRead(ECHO_PIN)
    == 1); t2= micros ();
  pulse_width = t2-t1;

// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed
speed
// of sound in air at sea level
(- 340m/s) cm=pulse_Width
/ 58 ;
inches = pulse_width/148.0;

// Print out results
if (pulse_width
  >MAX _ DIST
){ Serial.println("Out
of range");
} else
{ Serial.println("*****");
  Serial.print("The Measured Distance in cm: ");
  Serial.println(cm);

if( cm < 100 ){
  //while(true){
    Serial.println("Alert!!");
  //}

```

```

}

Serial.print("*****");

}

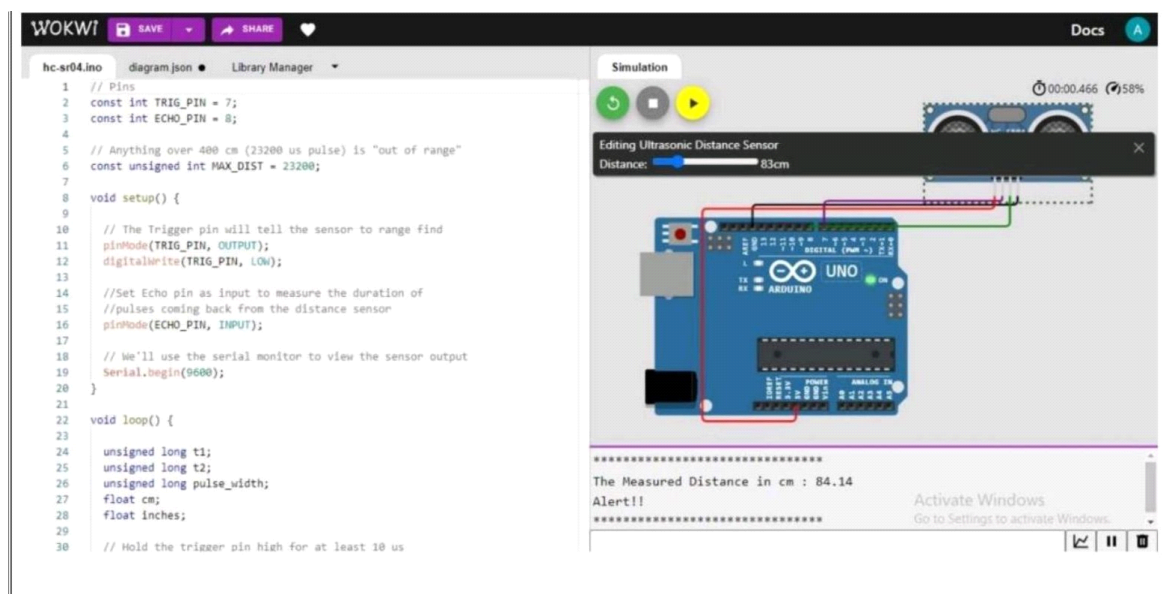
//wait at least 1000ms before next
measurement Delay(1000);

}

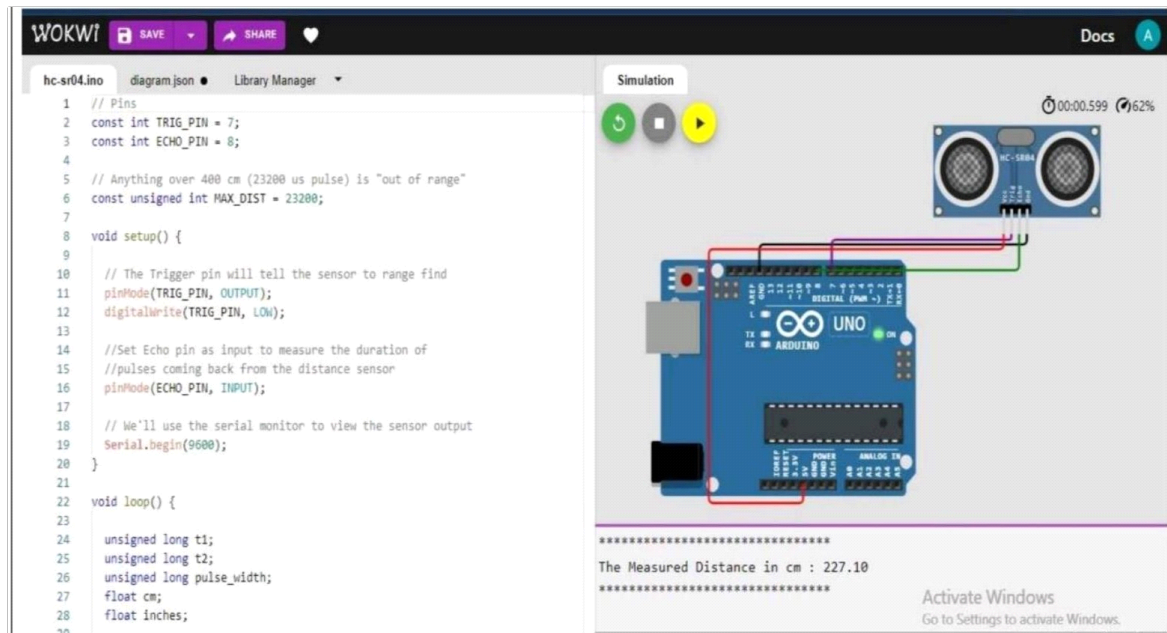
```

## Output:

- If the distance is less than 100 cms ,it alerts.



- If the distance is more than 100 cms,it won't alert



- Simulation and code execution

