

## CODE:

```
int t=2;
int e=3;
void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT);
  pinMode(e,INPUT);
  pinMode(12,OUTPUT);
}
void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(10);
  digitalWrite(t,LOW);
  float dur=pulseIn(e,HIGH);
  float dis= (dur* 0.0343)/2;
  Serial.print("Distance is: ");
  Serial.println(dis);

  //LED ON
  if(dis>=100)
  (
    digitalWrite(8,HIGH);
    digitalWrite(7,HIGH);
  }

  //Buzzer For ultrasonic Sensor
```

```
if(dis>=100)
{
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
delay(1000);
}
}
```

```
//Temperate Sensor
double a= analogRead(A0);
double t=((a/1024)*5)-0.5)*100;
Serial.print("Temp Value:");
Serial.println(t);
delay(1000);
//LED ON
if(t>=100)
{
digitalWrite(8,HIGH);
digitalWrite(7,HIGH);
}
//Buzzer for Temperature Sensor
if(t>=100)
{
for(int i=0; i<=30000; i=i+10)
{
tone(12,i);
delay(1000);
noTone(12);
```

```
delay(1000);  
}  
}  
//LED OFF  
if(t<100)  
{  
digitalWrite(8,LOW);  
digitalWrite(7,LOW);  
}  
}
```