### **ASSIGNMENT4**

# **WOKWI PROGRAM**

ASSIGNMNET DATE	23 OCTOBER 2022
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MAXIMUM NUMBER	2 MARKS
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### **CODE:**

```
#include <WiFi.h>
#include < PubSubClient.h>
void callback(char* subscribetopic,byte* payload, unsigned int payloadLength);
#define ORG "ry71x7"
#define DEVICE_TYPE "sheeba"
#define DEVICE_ID "1123"
#define TOKEN "BHERCtutP(LXnhH2(9"
String data3;
char server[]= ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[]="iot-2/evt/sheeba/fmt/json";
char subscribeTopic[]="iot-2/cmd/test/fmt/String";
char authMethod[]="use-token-auth";
char token[]=TOKEN;
char clientID[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
```

```
WiFiClientwifiClient;
PubSubClient client(server,1883,callback,wifiClient);
#define ECHO PIN 12
#define TRIG_PIN 13
#define led 14
void setup() {
// put your setup code here, to run once:
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
wificonnect();
mqttconnect();
float readDistanceCM() {
digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2);
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
 int duration=random(1,200);
```

```
//Serial.println(duration);
 //duration = pulseIn(ECHO_PIN, HIGH);
 return duration;
 //Serial.println(duration);
}
void loop() {
 float distance = readDistanceCM();
 //Serial.println(distance);
 bool isNearby = distance < 100;
digitalWrite(led, isNearby);
Serial.print("Measured distance: ");
Serial.println(distance);
 if(distance<100){
  PublishData2(distance);
}else{
  PublishData1(distance);
 //PublishData(distance);
```

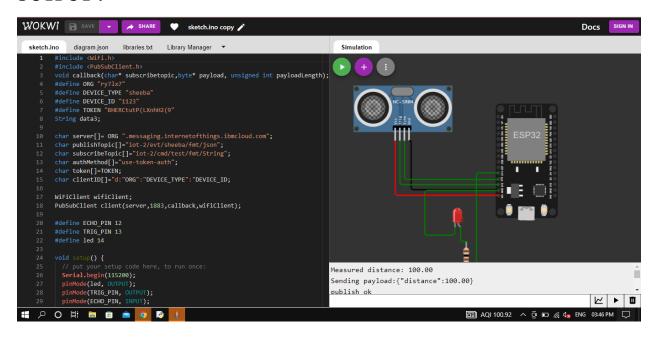
```
delay(1000);
 if(!client.loop()){
mqttconnect();
 }
 //delay(2000);
void PublishData1(float dist){
mqttconnect();
 String payload= "{\"distance\":";
 payload += dist;
 payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);
 if(client.publish(publishTopic,(char*)payload.c_str())){
Serial.println("publish ok");
} else{
Serial.println("publish failed");
 }
void PublishData2(float dist){
mqttconnect();
```

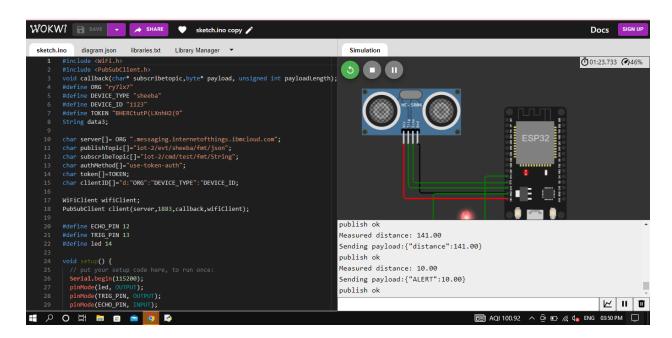
```
String payload= "{\"ALERT\":";
 payload += dist;
 payload+="}";
Serial.print("Sending payload:");
Serial.println(payload);
 if(client.publish(publishTopic,(char*)payload.c_str())){
Serial.println("publish ok");
 } else{
Serial.println("publish failed");
}
void mqttconnect(){
 if(!client.connected()){
Serial.print("Reconnecting to");
Serial.println(server);
while(!!!client.connect(clientID, authMethod, token)){
Serial.print(".");
delay(500);
  }
initManagedDevice();
Serial.println();
```

```
}
void wificonnect(){
Serial.println();
Serial.print("Connecting to");
WiFi.begin("Wokwi-GUEST","",6);
while(WiFi.status()!=WL_CONNECTED){
delay(500);
Serial.print(".");
 }
Serial.println("");
Serial.println("WIFI CONNECTED");
Serial.println("IP address:");
Serial.println(WiFi.localIP());
}
void initManagedDevice(){
 if(client.subscribe(subscribeTopic)){
Serial.println((subscribeTopic));
Serial.println("subscribe to cmd ok");
}else{
Serial.println("subscribe to cmd failed");
 }
```

```
}
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){</pre>
  data3 += (char)payload[i];
 }
Serial.println("data:"+ data3);
 if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
}else{
Serial.println(data3);
digitalWrite(led,LOW);
 data3="";
```

#### **OUTPUT:**





ir address: 10.10.0.2 Reconnecting tory71x7.messaging.internetofthings.ibmcloud.com iot-2/cmd/test/fmt/String subscribe to cmd ok Measured distance: 104.00 Sending payload:{"distance":104.00} publish ok Measured distance: 19.00 Sending payload:{"ALERT":19.00} publish ok Measured distance: 177.00 Sending payload:{"distance":177.00} publish ok Measured distance: 108.00 Sending payload:{"distance":108.00} publish ok Measured distance: 99.00 Sending payload:{"ALERT":99.00} publish ok 29°C Sunny ∧ @ 🖅 🦟 🕻 ENG 02:15 PM 🖟

# **IBM CLOUD OUTPUT:**

