

TEAM ID: B5-5M1E
ROLL NO: CITC1904077
NAME: GOKUL.R

CODE:

```
int t=2;
int e=3;
void setup()
{
  Serial.begin(9600);
  pinMode(t,OUTPUT);
  pinMode(e,INPUT);
  pinMode(12,OUTPUT);
}

void loop()
{
  //ultrasonic sensor
  digitalWrite(t,LOW);
  digitalWrite(t,HIGH);
  delayMicroseconds(10);
  digitalWrite(t,LOW);
  float dur=pulseIn(e,HIGH);
  float dis=(dur*0.0343)/2;
  Serial.print("Distance is: ");
  Serial.println(dis);

  //LED ON
  if(dis>=100)
```

```
    //LED ON
    if(dis>=100)
    {
      digitalWrite(8,HIGH);
      digitalWrite(7,HIGH);
    }

    //Buzzer For ultrasonic Sensor
    if(dis>=100)
    {
      for(int i=0; i<=30000; i=i+10)
      {
        tone(12,i);
        delay(1000);
        noTone(12);
        delay(1000);
      }
    }

    //Temperate Sensor
    double a= analogRead(A0);
```

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```
//Temperate Sensor
double a= analogRead(A0);
double t=((a/1024)*5)-0.5)*100;
Serial.print("Temp Value: ");
Serial.println(t);
delay(1000);
```

```
//LED ON
if(t>=100)
{
    digitalWrite(8,HIGH);
    digitalWrite(7,HIGH);
}
```

```
//Buzzer for Temperature Sensor
if(t>=100)
{
    for(int i=0; i<=30000; i=i+10)
    {
        tone(12,i);
        delay(1000);
        noTone(12);
        delay(1000);
```

```
    }
}
```

```
//LED OFF
if(t<100)
{
    digitalWrite(8,LOW);
    digitalWrite(7,LOW);
}
}
```

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OUTPUT:

