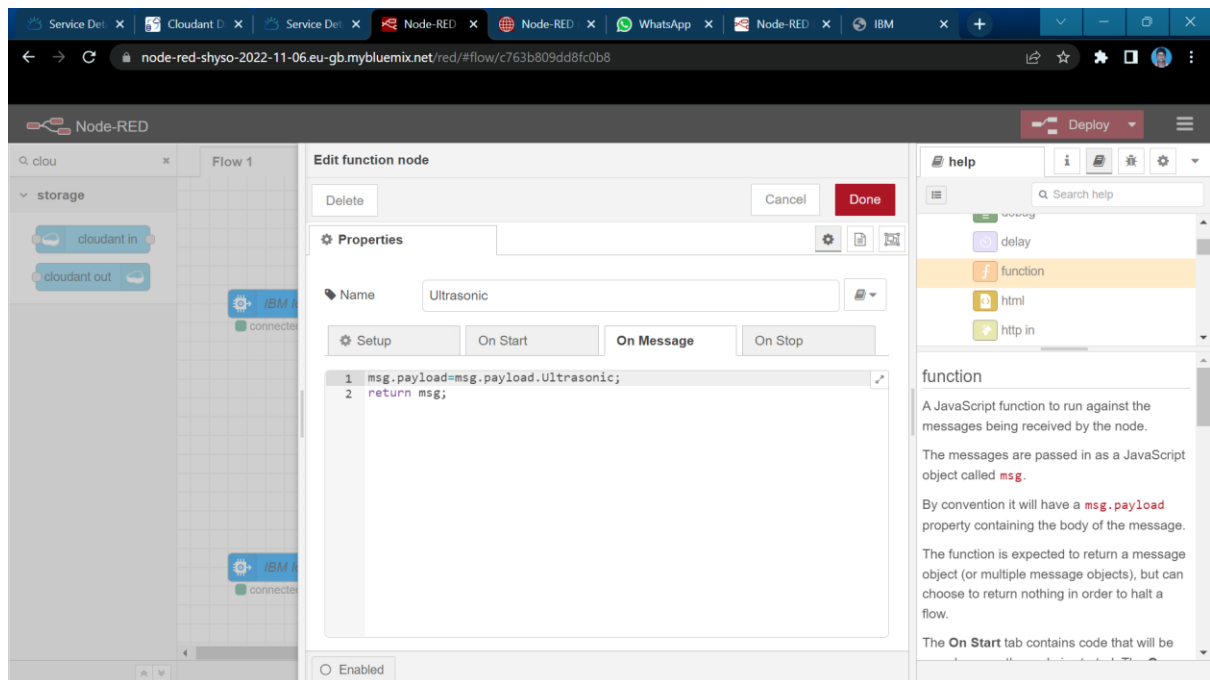
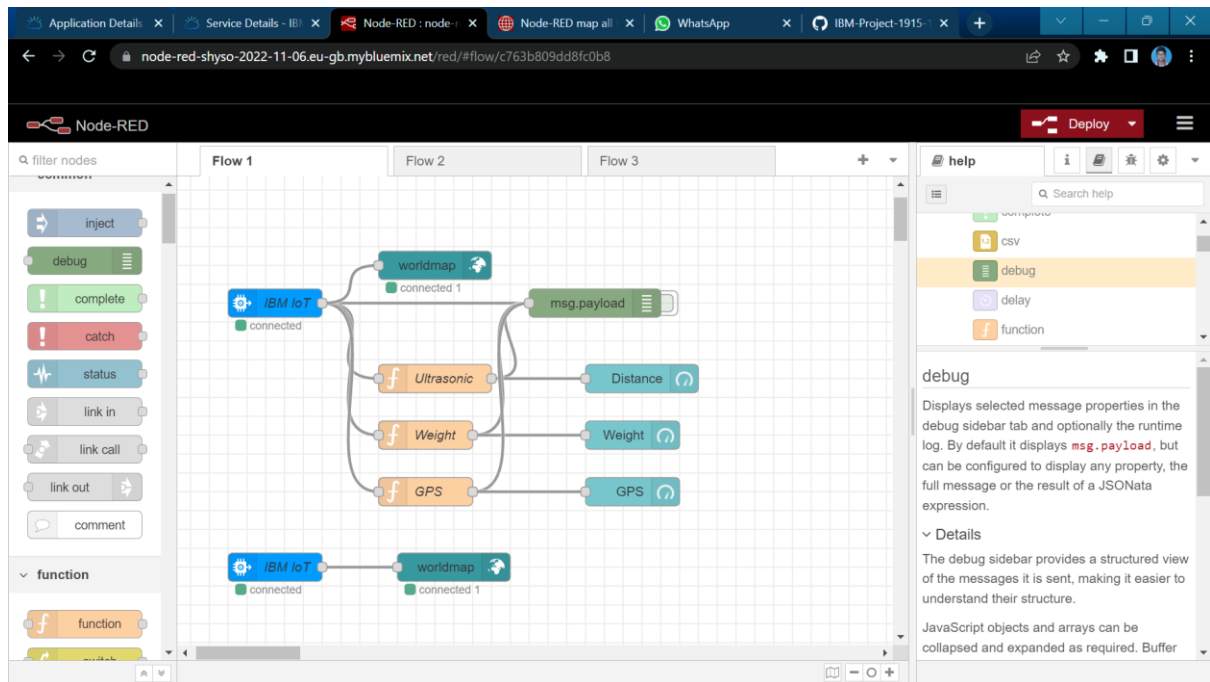


DEVELOP THE WEB APPLICATION USING NODE RED

Date	14 November 2022
Team ID	PNT2022TMID25449
Project Name	SMART WASTE MANAGEMENT SYSTEM
Maximum Marks	2 Marks

NODE RED APPLICATION



Service Det. x Cloudant D. x Service Det. x Node-RED x Node-RED x WhatsApp x Node-RED x IBM x

node-red-shyso-2022-11-06.eu-gb.mybluemix.net/red/#flow/c763b809dd8fc0b8

Node-RED

clou

storage

cloudant in

cloudant out

IBM IoT

connected

IBM IoT

connected

Edit function node

Delete Cancel Done

Properties

Name Weight

Setup On Start On Message On Stop

```
1 msg.payload=msg.payload.Weight;
2 return msg;
```

Enabled

help

Search help

delay

function

html

http in

function

A JavaScript function to run against the messages being received by the node.

The messages are passed in as a JavaScript object called **msg**.

By convention it will have a **msg.payload** property containing the body of the message.

The function is expected to return a message object (or multiple message objects), but can choose to return nothing in order to halt a flow.

The **On Start** tab contains code that will be

Service Det. x Cloudant D. x Service Det. x Node-RED x Node-RED x WhatsApp x Node-RED x IBM x

node-red-shyso-2022-11-06.eu-gb.mybluemix.net/red/#flow/c763b809dd8fc0b8

Node-RED

clou

storage

cloudant in

cloudant out

IBM IoT

connected

IBM IoT

connected

Edit worldmap node

Delete Cancel Done

Properties

Group [Smart Waste Monitoring] Default

Size auto

Start Latitude Longitude Zoom 1 - 18

Map list 7 selected

Base map OpenStreetMap Greyscale

Overlays 5 selected

Cluster when zoom level is less than 0 (0, off - 19)

Max age Remove markers after 600 seconds

Enabled

help

Search help

ibmiot out

node-red-contrib-web-worldmap

worldmap

worldmap

worldmap in

worldmap

Plots "things" on a map in Node-RED Dashboard. Needs an internet connection.

It is possible to instantiate multiple worldmap nodes but each one must be given a unique path. Worldmap-in nodes are matched to worldmap nodes by having exactly the same path.

Shortcut - **⌘m** - ctrl-shift-m to jump to the default Map (/worldmap).

The minimum **msg.payload** must contain **name**, **lat** and **lon** properties, e.g.

Node-RED interface showing a flow with IBM IoT nodes and a gauge node configuration panel.

Edit gauge node

Properties:

- Group: [Smart Waste Monitoring] Default
- Size: auto
- Type: Level
- Label: Weight
- Value format: {{value}}
- Units: Kg
- Range: min 0 max 1000
- Class: Optional CSS class name(s) for widget
- Name:
- Enabled: ☐

Help panel:

gauge

Adds a gauge type widget to the user interface.

The `msg.payload` is searched for a numeric value and is formatted in accordance with the defined **Value Format**, which can then be formatted using [Angular filters](#).

For example: `{{value | number:1}}%` will round the value to one decimal place and append a % sign.

The colours of each of 3 sectors can be specified and the gauge will blend between them. The colours should be specified in hex

Node-RED interface showing a flow with IBM IoT nodes and a gauge node configuration panel.

Edit gauge node

Properties:

- Group: [Smart Waste Monitoring] Default
- Size: auto
- Type: Gauge
- Label: GPS
- Value format: {{value}}
- Units: Km
- Range: min 0 max 100
- Colour gradient:
- Sectors: 0 ... optional ... optional ... 100
- Enabled: ☐

Help panel:

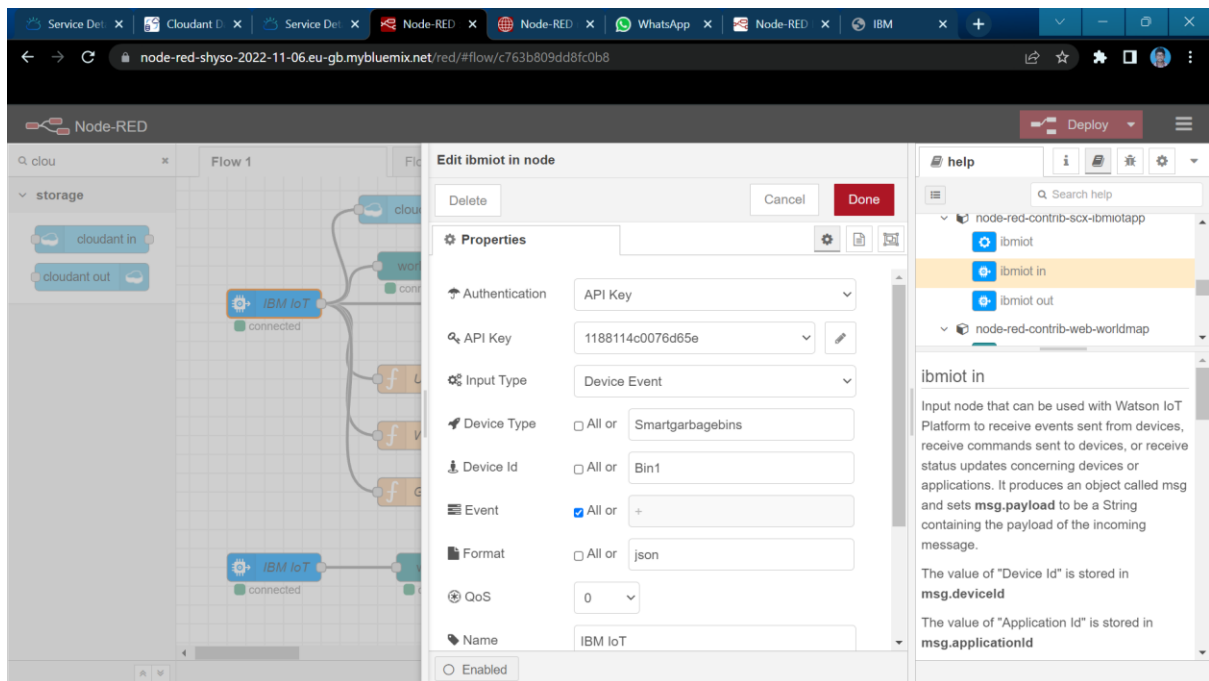
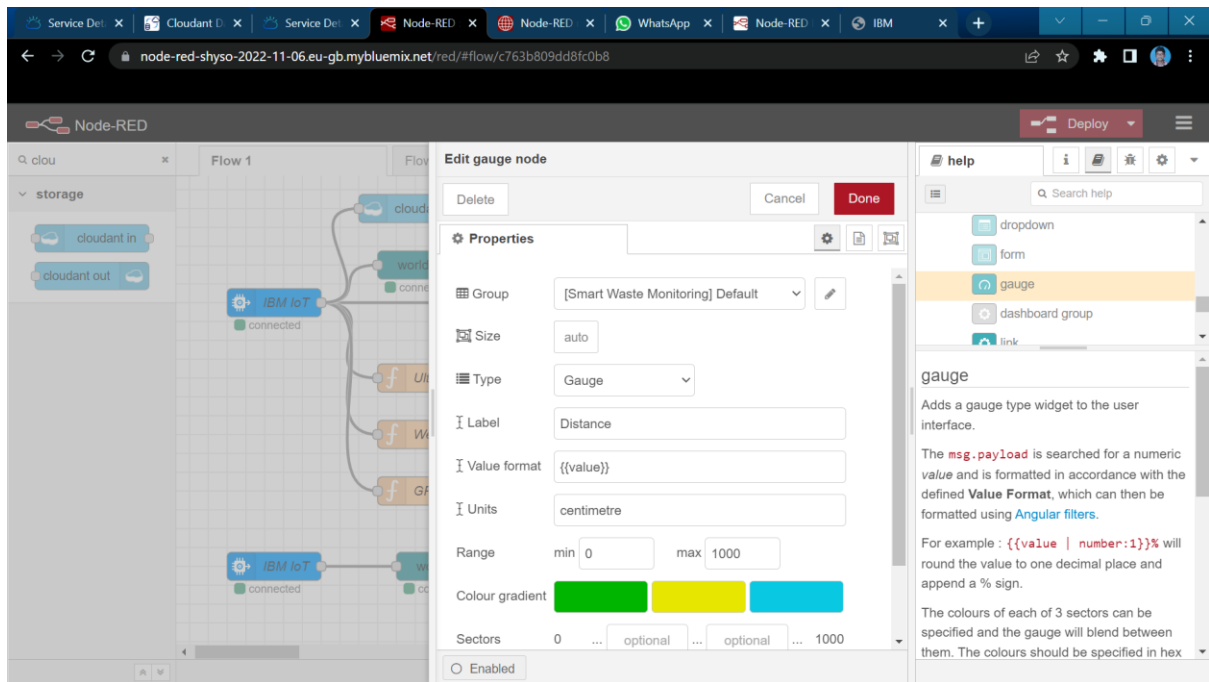
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CODE:

```
import time
```

```
import sys
```

```
import ibmiotf.application
```

```
import ibmiotf.device
```

```
import random
```

```

import sys

#Provide your IBM Watson Device Credentials

organization = "a7mbs7"

deviceType = "Smartgarbagebins"

deviceId = "Bin1"

authMethod = "token"

authToken = "Sakthi@2001"

# Initialize GPIO

def myCommandCallback(cmd):

    print("Command received: %s" % cmd.data['command'])

    status=cmd.data['command']

    if status == "lighton":

        print("led in on")

    else :

        print ("led is off")

try:

    deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-
method":authMethod, "auth-token": authToken}

    deviceCli = ibmiotf.device.Client(deviceOptions)

#.....

except Exception as e:

    print("Caught exception connecting device: %s" % str(e))

    sys.exit()

#Connect and send a datapoint "hello" with value "world" into the cloud as an event of type
"greeting" 10 times

deviceCli.connect()

while True:

    #Get Sensor Data from DHT11

    time.sleep(5)

    Ultrasonic=random.randint(0,80)

    Weight=random.randint(0,100)

    lat = round(random.uniform(11.03, 11.50), 6)

```

```

long = round(random.uniform(76.80, 76.90), 6)
GPS = str(lat) + str(',') + str(long)
myData = {'Ultrasonic' : Ultrasonic, 'Weight' : Weight , 'GPS' : GPS}
#print data
def myOnPublishCallback():
    print ("Published Ultrasonic = %s Cm" %Ultrasonic, "Weight:%s kg " %Weight, "GPS: %s"%GPS)
success = deviceCli.publishEvent("IoTSensor", "json", data=myData, qos=0,
on_publish=myOnPublishCallback)
if not success:
    print("Not connected to IoT")
time.sleep(1)
deviceCli.commandCallback = myCommandCallback
# Disconnect the device and application from the cloud
deviceCli.disconnect()

```

RESULT:

Thus the node-red application is successfully developed