

ASSIGNMENT: ULTRASONIC ALARM SYSTEM USING LED, ULTRASONIC SENSOR(HC-SR04) AND A BUZZER

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CODE:

```
#include <WiFi.h>
#include <PubSubClient.h>

WiFiClient wifiClient;
String data3;

#define ORG "3yngh"
#define DEVICE_TYPE "Assignment"
#define DEVICE_ID "1234"
#define TOKEN "234567890"
#define speed 0.034 #define led 14 char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/shreedharen/fmt/json"; char topic[] = "iot-
2/cmd/led/fmt/String"; char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient); const int
trigpin=5; const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
```

```
Serial.begin(115200);  
pinMode(led, OUTPUT);  
pinMode(trigpin, OUTPUT);  
pinMode(echopin, INPUT);  
wifiConnect();  
mqttConnect();  
}
```

```
void loop() {  bool isNearby  
= dist < 100;  
digitalWrite(led, isNearby);
```

```
    publishData();  
    delay(500);
```

```
    if (!client.loop()) {  
mqttConnect();  
    }  
}
```

```
void wifiConnect() {  
    Serial.print("Connecting to "); Serial.print("Wifi");  
    WiFi.begin("Wokwi-GUEST", "", 6);  while  
(WiFi.status() != WL_CONNECTED) {  
        delay(500);  
        Serial.print(".");  
    }  
    Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP()); }
```

```

void mqttConnect() { if
(!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print("."); delay(500);
    }
    initManagedDevice();
    Serial.println();
}
}

```

```

void initManagedDevice() {
if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
} else {
    Serial.println("subscribe to cmd FAILED");
}
}

```

```

void publishData()
{
    digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10); digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2; if(dist<100){

    String payload = "{\"Alert Distance\":\"";
payload += dist; payload += "}";
}
}

```

```
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
}

}

if(dist>100){
    String payload = "{\"Distance\": ";
payload += dist;    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);

    if(client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }else {
        Serial.println("Publish FAILED");
    } } }
```

OUTPUT:

Simulation

