ASSIGNMENT 4

Date	03 Nov 2022
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Project Name	SmartFarmer – IoT Enabled Smart Farming
	Application

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Upload document with wokwi share link and images of ibm cloud

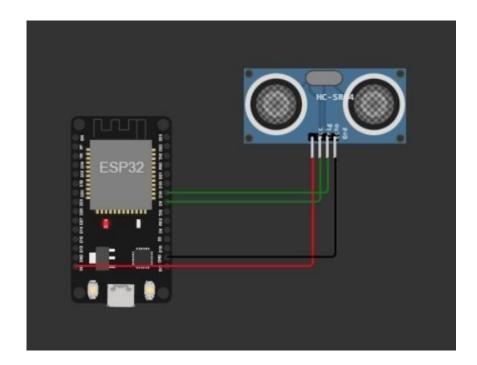
CODE:

```
#include <WiFi.h>
#include <PubSubClient.h> WiFiClient
wifiClient;
#define ORG "nhpwjc"
#define DEVICE_TYPE "NodeMCU"
#define DEVICE_ID "USE YOUR ID"
#define TOKEN "USE YOUR TOKEN"
#define speed 0.034
 char server[] =
ORG
".messaging.internetofthings.ibmcloud.com"; char publishTopic[]
= "iot-2/evt/Data/fmt/json"; char topic[] = "iot-
2/cmd/home/fmt/String"; char authMethod[] = "use-tokenauth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient); void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long
duration;
float dist;
setup()
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
```

```
pinMode(echopin, INPUT); wifiConnect();
 mqttConnect();
} void loop() { publishData();
  delay(500);
 if (!client.loop()) { mqttConnect(); }
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6); while (WiFi.status() !=
 WL_CONNECTED) { delay(500);
   Serial.print("."); }
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
void mqttConnect() { if
  (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server); while
    (!client.connect(clientId, authMethod, token)) { Serial.print("."); delay(500);
    } initManagedDevice(); Serial.println();
 } }
void initManagedDevice() { if
  (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic)); Serial.println("subscribe
                                                                                  \mathsf{cmd}
   OK");
 } else {
    Serial.println("subscribe to cmd FAILED"); } yoid
publishData()
{ digitalWrite(trigpin,LOW); digitalWrite(trigpin,HIGH);
```

```
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2; if(dist<100){
   String payload = "{\"Alert distance\":";
   payload += dist; payload += "}";
   Serial.print("\n");
   Serial.print("Sending payload: "); Serial.println(payload);
   if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
   } else {
        Serial.println("Publish FAILED"); }
}</pre>
```

CONNECTIONS:



OUTPUT:

