# PROJECT DEVELOPMENT DELIVERY OF SPRINT - 4

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Project Name	Smart Farmer – IOT Enabled Smart Farming Application

## Receiving commands from IBM cloud using Python

## program

import time

import sys

import ibmiotf.application

import ibmiotf.device

import random

## #Provide yourIBM Watson Device Credentials

organization = " nicw4y"

deviceType = " NodeMCU"

deviceId = "12345"

authMethod = "token"

authToken = "123456"

#### # Initialize GPIO

def myCommandCallback(cmd):

```
print("Command received: %s" %
cmd.data['command']) status=cmd.data['command']
if status=="motoron": print ("motor is on")
elif
status == "motoroff": print("motor is off")
else:
    print ("please send proper command")
try:
       deviceOptions = {"org": organization, "type": deviceType, "id":
deviceId, "auth-method": authMethod, "auth-token": authToken}
deviceCli = ibmiotf.device.Client(deviceOptions)
      #.....
except Exception as e:
      print("Caught exception connecting device: %s" % str(e))
sys.exit()
# Connect and send a datapoint "hello" with value "world" into the cloud as an
event of type "greeting" 10 times deviceCli.connect()
while True:
    #Get Sensor Data from DHT11
temp=random.randint(90,110)
Humid=random.randint(60,100)
Mois=random. Randint(20,120)
  data = { 'temp' : temp, 'Humid': Humid,
'Mois': Mois}
    #print data def
```

## myOnPublishCallback():

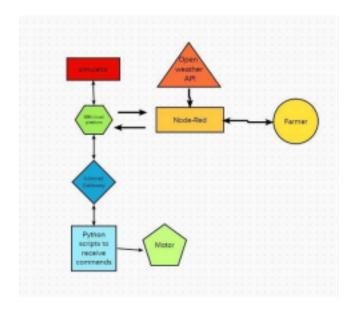
print ("Published Temperature = %s C" % temp, "Humidity = %s %%" % Humid, "Moisture = %s deg c" % Mois "to IBM Watson")

success = deviceCli.publishEvent("IoTSensor", "json", data,
qos=0, on\_publish=myOnPublishCallback) if not success:
 print("Not connected to IoTF")

time.sleep(10)

deviceCli.commandCallback = myCommandCallback #
Disconnect the device and application from the cloud
deviceCli.disconnect()

#### **Flow Chart**



#### **Observations & Results**

