

ASSIGNMENT – 1

Build a smart home in Tinker cad with 2 sensors, an Led, buzzer and submit it.

CODE:

```
int inches = 0;
int cm = 0;
long rudc(int triggerPin, int echoPin)
{
    pinMode(6, OUTPUT);
    pinMode(triggerPin, OUTPUT); // Clear the trigger
    digitalWrite(triggerPin, LOW);
    delayMicroseconds(2);
    // Sets the trigger pin to HIGH state for 10 microseconds
    digitalWrite(triggerPin, HIGH);
    delayMicroseconds(10);
    digitalWrite(triggerPin, LOW);
    pinMode(echoPin, INPUT);
    // Read the echo pin, and returns the sound wave travel time in
    microseconds
    return pulseIn(echoPin, HIGH);
}
```

```
void setup()
```

```
{
```

```
  pinMode(3, OUTPUT);
```

```
  Serial.begin(9600);
```

```
}
```

```
void loop()
```

```
{
```

```
  // measure the ping time in cm
```

```
  cm = 0.01723 * rudc(7, 7);
```

```
  // convert to inches by dividing by 2.54
```

```
  inches = (cm / 2.54);
```

```
  Serial.print(inches);
```

```
  Serial.print("in, ");
```

```
  Serial.print(cm);
```

```
  Serial.println("cm");
```

```
  delay(100); // Wait for 100 millisecond(s)
```

```
{
```

```
  if (cm<90)
```

```
    digitalWrite(6,HIGH);
```

```
  else
```

```
    digitalWrite(6,LOW);
```

```
}
```

```
int a = digitalRead(2);
Serial.println(a);
pinMode(3,OUTPUT);
if(a==HIGH)
{
    Serial.println("motion detected!!");
    digitalWrite(3,HIGH);
    delay(1000);
}
else
{
    Serial.println("motion not detected!!");
    digitalWrite(3,LOW);
    delay(1000);
}
}
```