# Model\_building

November 10, 2022

# 1 Project Development Phase

Date: 2 November 2022

Team ID: PNT2022TMID38414

Project Name: Intelligent Vehicle Damage Assessment & Cost Estimator for Insurance

Companies

#### MODEL BUILDING

## 1. Importing The Model Building Libraries

```
[]: import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda, Dense, Flatten
from tensorflow.keras.models import Model
from tensorflow.keras.applications.vgg16 import VGG16
from tensorflow.keras.applications.vgg19 import VGG19
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import ImageDataGenerator,load_img
from tensorflow.keras.models import Sequential
import numpy as np
from glob import glob
```

### 2. Loading The Model

```
[]: IMAGE_SIZE = [224, 224]

train_path = '/content/drive/MyDrive/Intelligent Vehicle Damage Assessment &

→Cost Estimator For Insurance Companies/Dataset/body/training'

valid_path = '/content/drive/MyDrive/Intelligent Vehicle Damage Assessment &

→Cost Estimator For Insurance Companies/Dataset/body/validation'
```

```
[]: vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', 

→include_top=False)
```

# 3. Adding Flatten Layer

```
[]: for layer in vgg16.layers:
layer.trainable = False
```

```
NameError
                                                   Traceback (most recent call
     →last)
           <ipython-input-3-e7d1e9f4fca8> in <module>
       ----> 1 for layer in vgg16.layers:
                   layer.trainable = False
           NameError: name 'vgg16' is not defined
[]: folders = glob('/content/drive/MyDrive/Intelligent Vehicle Damage Assessment &_
     →Cost Estimator For Insurance Companies/Dataset/body/training/*')
[]: folders
[]: ['/content/drive/MyDrive/Intelligent Vehicle Damage Assessment & Cost Estimator
    For Insurance Companies/Dataset/body/training/02-side',
     '/content/drive/MyDrive/Intelligent Vehicle Damage Assessment & Cost Estimator
    For Insurance Companies/Dataset/body/training/00-front',
     '/content/drive/MyDrive/Intelligent Vehicle Damage Assessment & Cost Estimator
    For Insurance Companies/Dataset/body/training/01-rear']
[]: x = Flatten()(vgg16.output)
[]: len(folders)
[]: 3
    4. Adding Output Layer
[]: prediction = Dense(len(folders), activation='softmax')(x)
    5. Creating A Model Object
[]: model = Model(inputs=vgg16.input, outputs=prediction)
[]: model.summary()
    Model: "model"
    Layer (type)
                             Output Shape
                                                       Param #
    ______
                               [(None, 224, 224, 3)]
     input_1 (InputLayer)
```

block1_conv1 (Conv2D)	(None, 224, 224, 64)	1792
block1_conv2 (Conv2D)	(None, 224, 224, 64)	36928
block1_pool (MaxPooling2D)	(None, 112, 112, 64)	0
block2_conv1 (Conv2D)	(None, 112, 112, 128)	73856
block2_conv2 (Conv2D)	(None, 112, 112, 128)	147584
block2_pool (MaxPooling2D)	(None, 56, 56, 128)	0
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168
block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808
block4_conv3 (Conv2D)	(None, 28, 28, 512)	2359808
block4_pool (MaxPooling2D)	(None, 14, 14, 512)	0
block5_conv1 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv2 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv3 (Conv2D)	(None, 14, 14, 512)	2359808
block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0
flatten (Flatten)	(None, 25088)	0
dense (Dense)	(None, 3)	75267

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Total params: 14,789,955 Trainable params: 75,267

Non-trainable params: 14,714,688

\_\_\_\_\_\_

# 6. Configure The Learning Process

```
[]: model.compile(
    loss='categorical_crossentropy',
    optimizer='adam',
    metrics=['accuracy']
)
```

#### 7. Train The Model

```
[]: r = model.fit_generator(
    training_set,
    validation_data=test_set,
    epochs=25,
    steps_per_epoch=len(training_set),
    validation_steps=len(test_set)
)
```

/usr/local/lib/python3.7/dist-packages/ipykernel\_launcher.py:6: UserWarning: `Model.fit\_generator` is deprecated and will be removed in a future version. Please use `Model.fit`, which supports generators.

```
Epoch 1/25
0.5649 - val_loss: 0.8292 - val_accuracy: 0.7076
Epoch 2/25
0.7467 - val_loss: 1.2482 - val_accuracy: 0.5965
Epoch 3/25
0.8039 - val_loss: 0.8174 - val_accuracy: 0.7193
Epoch 4/25
98/98 [============ ] - 601s 6s/step - loss: 0.3564 - accuracy:
0.8621 - val_loss: 0.9245 - val_accuracy: 0.6608
Epoch 5/25
0.8917 - val_loss: 1.9934 - val_accuracy: 0.5906
Epoch 6/25
0.9152 - val_loss: 0.9176 - val_accuracy: 0.6842
Epoch 7/25
0.9367 - val_loss: 0.9594 - val_accuracy: 0.7018
Epoch 8/25
98/98 [============ ] - 600s 6s/step - loss: 0.2184 - accuracy:
0.9122 - val_loss: 1.0329 - val_accuracy: 0.6784
Epoch 9/25
0.9581 - val_loss: 1.0539 - val_accuracy: 0.7135
```

```
Epoch 10/25
98/98 [============ ] - 599s 6s/step - loss: 0.1131 - accuracy:
0.9622 - val_loss: 1.2113 - val_accuracy: 0.6842
Epoch 11/25
0.9745 - val_loss: 0.9917 - val_accuracy: 0.7018
Epoch 12/25
0.9745 - val_loss: 1.0601 - val_accuracy: 0.7018
Epoch 13/25
98/98 [============ ] - 594s 6s/step - loss: 0.0695 - accuracy:
0.9816 - val_loss: 1.3700 - val_accuracy: 0.6433
Epoch 14/25
98/98 [=========== ] - 599s 6s/step - loss: 0.1414 - accuracy:
0.9653 - val_loss: 1.1607 - val_accuracy: 0.6667
Epoch 15/25
98/98 [============= ] - 600s 6s/step - loss: 0.0905 - accuracy:
0.9796 - val_loss: 1.4014 - val_accuracy: 0.6667
Epoch 16/25
0.9775 - val_loss: 1.6741 - val_accuracy: 0.6491
Epoch 17/25
0.9745 - val_loss: 1.2824 - val_accuracy: 0.6959
Epoch 18/25
98/98 [============ ] - 600s 6s/step - loss: 0.0831 - accuracy:
0.9785 - val_loss: 1.1667 - val_accuracy: 0.6901
Epoch 19/25
98/98 [=========== ] - 603s 6s/step - loss: 0.0826 - accuracy:
0.9704 - val_loss: 1.3747 - val_accuracy: 0.6374
Epoch 20/25
98/98 [=========== ] - 600s 6s/step - loss: 0.0536 - accuracy:
0.9837 - val_loss: 1.2074 - val_accuracy: 0.6550
Epoch 21/25
98/98 [============ ] - 597s 6s/step - loss: 0.0716 - accuracy:
0.9796 - val_loss: 1.5491 - val_accuracy: 0.6725
Epoch 22/25
0.9918 - val_loss: 1.2930 - val_accuracy: 0.7135
Epoch 23/25
0.9928 - val_loss: 1.2576 - val_accuracy: 0.6959
0.9908 - val_loss: 1.3347 - val_accuracy: 0.7193
Epoch 25/25
98/98 [=========== ] - 597s 6s/step - loss: 0.0597 - accuracy:
0.9826 - val_loss: 1.4728 - val_accuracy: 0.6725
```

### 8. Save The Model

```
[]: from tensorflow.keras.models import load_model

model.save('/content/drive/MyDrive/Intelligent Vehicle Damage Assessment & Cost

→Estimator For Insurance Companies/Model/body.h5')
```

#### 9. Test The Model

```
[]: from tensorflow.keras.models import load_model import cv2 from skimage.transform import resize
```

```
[]: model = load_model('/content/drive/MyDrive/Intelligent Vehicle Damage

→Assessment & Cost Estimator For Insurance Companies/Model/body.h5')
```

```
def detect(frame):
    img = cv2.resize(frame,(224,224))
    img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)

if(np.max(img)>1):
    img = img/255.0
    img = np.array([img])
    prediction = model.predict(img)
    label = ["front","rear","side"]
    preds = label[np.argmax(prediction)]
    return preds
```

```
[]: import numpy as np
```

```
[]: data = "/content/drive/MyDrive/Intelligent Vehicle Damage Assessment & Cost

→Estimator For Insurance Companies/Dataset/body/training/00-front/0005.JPEG"

image = cv2.imread(data)

print(detect(image))
```

```
1/1 [======] - 1s 638ms/step front
```