Assignment -3

Assignment Date	05 November 2022
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Maximum Marks	2 Marks

Question :

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

Solution code:

```
#include <WiFi.h>//library for wifi

#include <PubSubClient.h>//library for MQtt

#define ORG "q1wscz”

#define DEVICE_E "sampledevice"

#define DEVICE_D "24052002

#define TOKEN "K9)lI1C@tX6yO(J6L1"

const int T_PIN = 5;

const int E_PIN = 4;

//-------- Customise the above values --------

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name

char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send

char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING

char authMethod[] = "use-token-auth";// authentication method

char token[] = TOKEN;

char clientId[] = "d:" ORG ":" DEVICE_E ":" DEVICE_D;//client id

//-------------------------------------------------------------

WiFiClient wifiClient; // creating the instance for wificlient

PubSubClient client(server, 1883, wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential
void setup() {
```

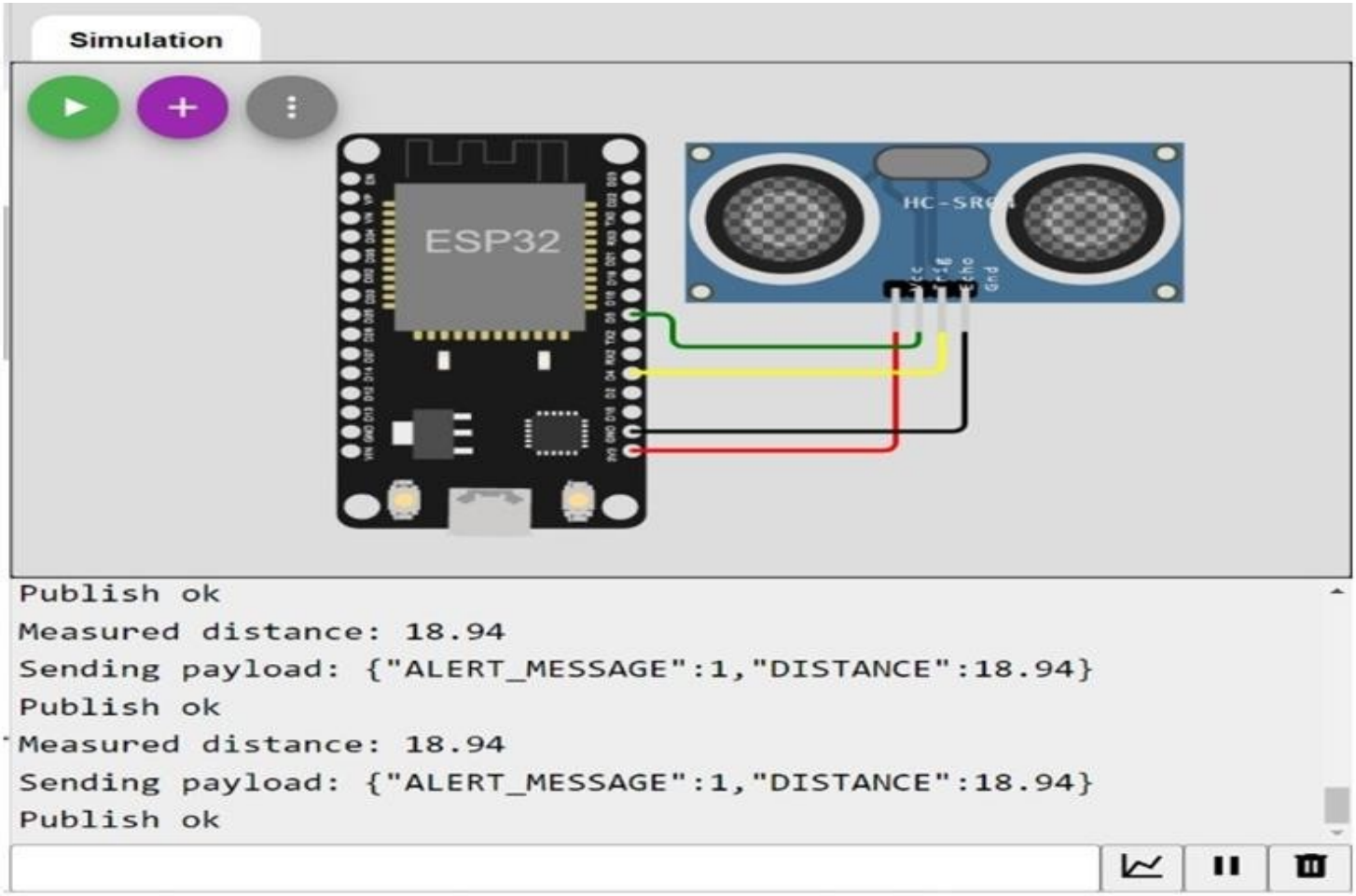
```
  Serial.begin(115200);
  pinMode(T_PIN, OUTPUT);
  pinMode(E_PIN, INPUT);
  wificonnect();
  mqttconnect();
}
float readDistanceCM() {
  digitalWrite(T_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(T_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(T_PIN, LOW);
  int duration = pulseIn(E_PIN, HIGH);
  return duration * 0.034 / 2;
}
void loop() {
  float distance = readDistanceCM();
  Serial.print("Measured distance: ");
  Serial.println(distance);
  if(distance<=100){
  PublishData(distance);
  }
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}
void PublishData(float distance) {
  mqttconnect();//function call for connecting to ibm
  /*
     creating the String in in form JSon to update the data to ibm cloud
  */
  bool status=true;
  String payload = "{\"ALERT_MESSAGE\":";
  payload += status;
  payload += "," "\"DISTANCE\":";
```

```
  payload += distance;
  payload += "}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish ok");// if it sucessfully upload data on the cloud then it will print
publish ok in Serial monitor or else it will print publish failed
  } else {
    Serial.println("Publish  failed");
  }
}
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");

  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the
connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
```

```
  Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
```

Output:


Simulation
ESP32
HC-SR04
Vcc
Trig
Echo
Gnd
Publish ok
Measured distance: 18.94
Sending payload: {"ALERT_MESSAGE":1,"DISTANCE":18.94}
Publish ok
Measured distance: 18.94
Sending payload: {"ALERT_MESSAGE":1,"DISTANCE":18.94}
Publish ok