ASSIGNMENT-

4

DISTANCE DETECTION USING ULTRASONIC SENSOR

| Date | 20 October 2022 |
|------------------------|------------------|
| Team ID | PNT2022TMID32971 |
| Name | AISHWARYA.K |
| Student Roll Number | 820419106004 |
| Maximum Marks | 2 Marks |

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

CODE:

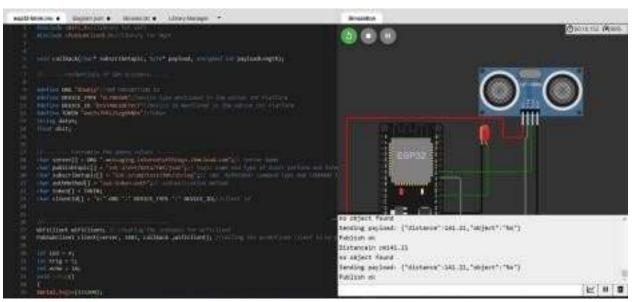
```
# signifies and materials and plants of the project of the project
```

```
esp32-blink ino • diagram json •
                                   libraries bit .
                                                  Library Manager *
       pinMode(trig, DUTTOUT);
       pinHode(echo, IMBT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void Toop()// Recursive Function
        digitalwrite(trig, ....);
         digitalWrite(trig, wind);
         delayMicroseconds(10);
         digitalwrite(trig, | cm);
         float dur = pulsein(echo, Hins);
         float dist - (dur * 0.0343)/2;
         Serial.print ("Distancein on");
         Serial.printin(dist);
         PublishData(dist);
         dellay(1000);
         IF (!client. ()) {
           mqttconnect();
       void PublishData(float dist) (
         mqttconnect();//function call for connecting to ibm
```

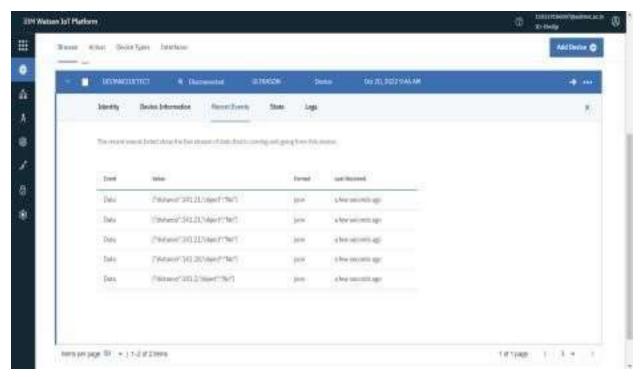
```
septCollect * degree on * therenic * therenic * therenic *
special reduction to the product of the production of th
```

```
esp32-blink.ino .
                 diagram json ...
                                   kbraries.txt ●
                                                Library Manager *
         wiFl.begin("sexwi-GDEST", "", b);//passing the wifl (redentials to establish the connection
         while (WiFi.status() !- NL_COMMECTED) (
           delay(506);
           Serial.print(". );
         Serial println("");
         Serial.println("Wifi connected");
         Serial println("IP address: );
         Serial.println(WiFi.localIP());
       void initManagedDevice() (
        if (client.subscribe(subscribetopic)) (
           Serial.printin((subscribetopic));
           Serial.println("subscribe to cad OK");
           serial.println( subscribe to end FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payload.ength)
         Serial.print("callback invoked for topic: ");;
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadtength; i++) {
           data3 += (char)payload[i];
```

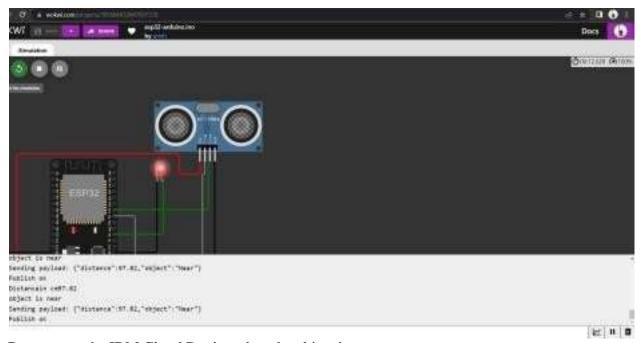
OUTPUT:



Data send to the IBM cloud device when the object is far



When object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

