ASSIGNMENT-

4

DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
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Student Roll Number	820419106026
Maximum Marks	2 Marks

Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

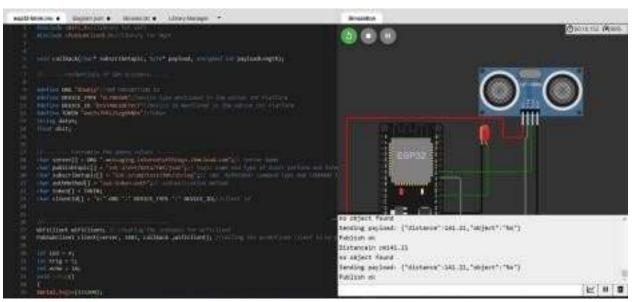
CODE:

```
esp32-blink ino • diagram json •
                                   libraries bit .
                                                  Library Manager *
       pinMode(trig, DUTTOUT);
       pinHode(echo, IMBT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void Toop()// Recursive Function
        digitalwrite(trig, ....);
         digitalWrite(trig, wind);
         delayMicroseconds(10);
         digitalwrite(trig, | cm);
         float dur = pulsein(echo, Hins);
         float dist - (dur * 0.0343)/2;
         Serial.print ("Distancein on");
         Serial.printin(dist);
         PublishData(dist);
         dellay(1000);
         IF (!client. ()) {
           mqttconnect();
       void PublishData(float dist) (
         mqttconnect();//function call for connecting to ibm
```

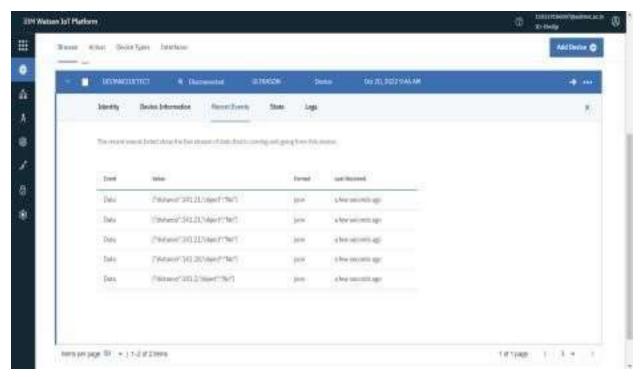
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esp32-blink.ino .
                 diagram json ...
                                   kbraries.txt ●
                                                Library Manager *
         wiFl.begin("sexwi-GDEST", "", b);//passing the wifl (redentials to establish the connection
         while (WiFi.status() !- NL_COMMECTED) (
           delay(506);
           Serial.print(". );
         Serial println("");
         Serial.println("Wifi connected");
         Serial println("IP address: );
         Serial.println(WiFi.localIP());
       void initManagedDevice() (
        if (client.subscribe(subscribetopic)) (
           Serial.printin((subscribetopic));
           Serial.println("subscribe to cad OK");
           serial.println( subscribe to end FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payload.ength)
         Serial.print("callback invoked for topic: ");;
         Serial.println(subscribetopic);
 148
         for (int i = 0; i < payloadtength; i++) {
           data3 += (char)payload[i];
```

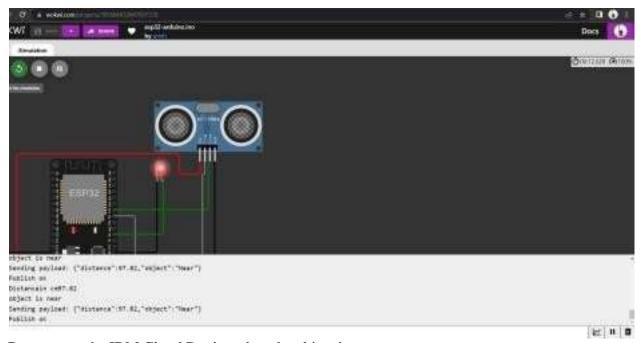
OUTPUT:



Data send to the IBM cloud device when the object is far



When object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

