

## Assignment -4

### WOKWI SIMULATION

Assignment Date	23 October 2022
Student Name	B.ABISHEK
Student Roll Number	211419104002
Maximum Marks	2 Marks

#### **Question-1:**

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an alert to the ibm cloud and display in the device recent events.

#### **Code:**

link: [projecta - Wokwi Arduino and ESP32 Simulator](#)

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}

void loop() {
  float distance = readDistanceCM();

  bool isNearby = distance < 100;
```

```

digitalWrite(LED_BUILTIN, isNearby);

Serial.print("Measured distance: ");
Serial.println(readDistanceCM());

delay(100);
}

```

## DIAGRAM.JSON:

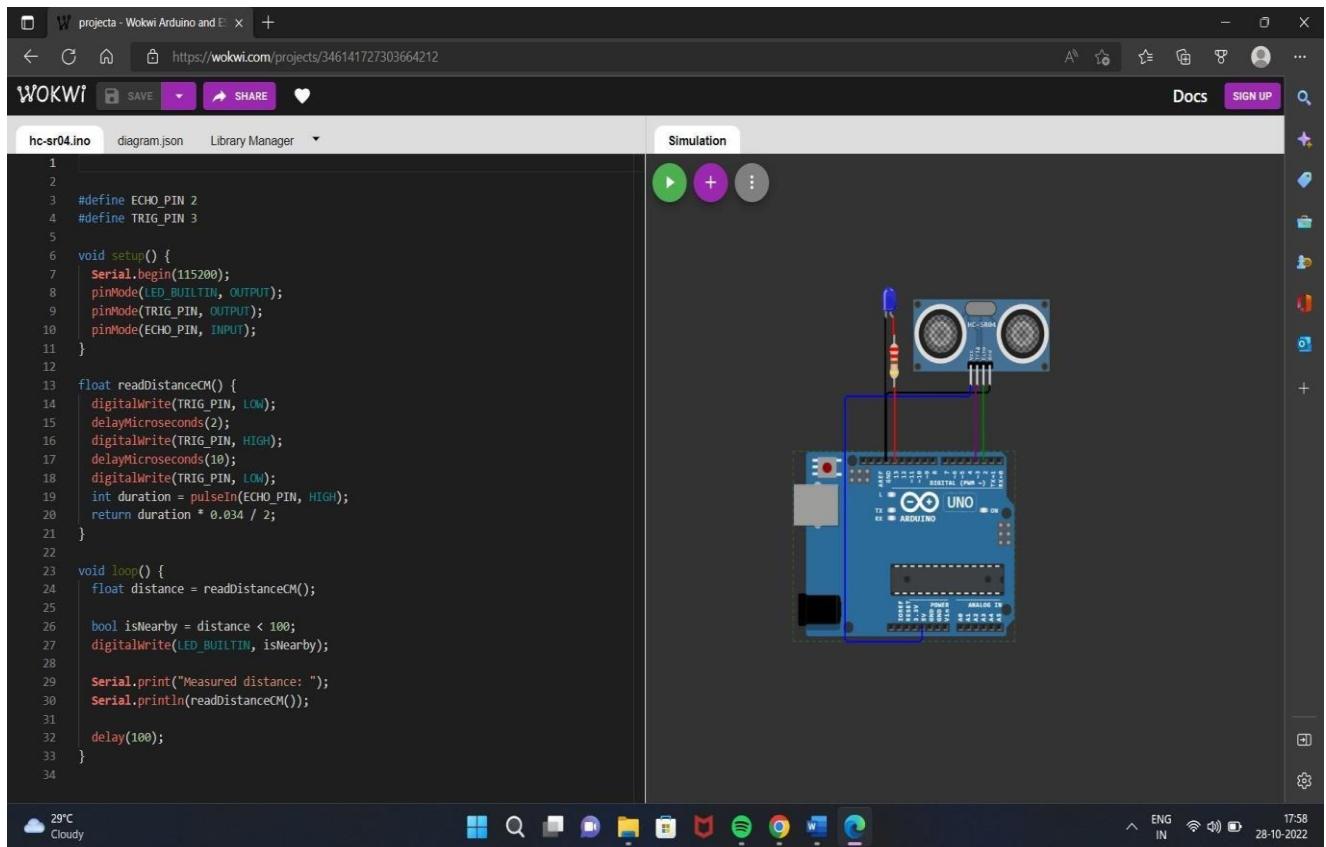
```
{
  "version": 1,
  "author": "sindhuja",
  "editor": "wokwi",
  "parts": [
    {
      "type": "wokwi-arduino-uno",
      "id": "uno",
      "top": 275.99,
      "left": 47.73,
      "rotate": 0,
      "hide": false,
      "attrs": {}
    },
    {
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 165.87,
      "left": 142.81,
      "rotate": 90,
      "hide": false,
      "attrs": { "value": "220" }
    },
    {
      "type": "wokwi-led",
      "id": "led",
      "top": 87.29,
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": { "color": "blue" }
    },
    {
      "type": "wokwi-hc-sr04",
      "id": "ultrasonic",
      "top": 10.0,
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": {}
    }
  ]
}
```

```

        "top": 108.43,
        "left": 196.5,
        "rotate": 0,
        "hide": false,
        "attrs": { "distance": "180" }
    }
],
"connections": [
    [ "uno:GND.1", "ultrasonic:GND", "black", [ "v-8", "*", "v8" ] ],
    [ "uno:2", "ultrasonic:ECHO", "green", [ ] ],
    [ "uno:3", "ultrasonic:TRIG", "purple", [ "*", "v4" ] ],
    [ "uno:5V", "ultrasonic:VCC", "blue", [ "v16", "h-96", "*", "v12" ] ],
    [ "uno:GND.1", "led:C", "black", [ ] ],
    [ "r1:1", "led:A", "red", [ ] ],
    [ "uno:13", "r1:2", "red", [ ] ]
]
}

```

## OUTPUT:



projecta - Wokwi Arduino and +

https://wokwi.com/projects/346141727303664212

WOKWI SAVE SHARE ♥ Docs SIGN UP

hc-sr04.ino diagram.json Library Manager

```
1
2
3 #define ECHO_PIN 2
4 #define TRIG_PIN 3
5
6 void setup() {
7   Serial.begin(115200);
8   pinMode(LED_BUILTIN, OUTPUT);
9   pinMode(TRIG_PIN, OUTPUT);
10  pinMode(ECHO_PIN, INPUT);
11 }
12
13 float readDistanceCM() {
14   digitalWrite(TRIG_PIN, LOW);
15   delayMicroseconds(2);
16   digitalWrite(TRIG_PIN, HIGH);
17   delayMicroseconds(10);
18   digitalWrite(TRIG_PIN, LOW);
19   int duration = pulseIn(ECHO_PIN, HIGH);
20   return duration * 0.034 / 2;
21 }
22
23 void loop() {
24   float distance = readDistanceCM();
25
26   bool isNearby = distance < 100;
27   digitalWrite(LED_BUILTIN, isNearby);
28
29   Serial.print("Measured distance: ");
30   Serial.println(readDistanceCM());
31
32   delay(100);
33 }
```

Simulation

00:06.794 92%

Measured distance: 177.24  
Measured distance: 177.16  
Measured distance: 177.26  
Measured distance: 177.16  
Measured distance: 177.26  
Measured distance: 177.16  
Measured distance: 177.26

29°C Cloudy ENG IN 17:58 28-10-2022