

Assignment -4 WOKWI SIMULATION

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|---------------------|-----------------|
| Assignment Date | 23 October 2022 |
| Student Name | B.ABISHEK |
| Student Roll Number | 211419104002 |
| Maximum Marks | 2 Marks |

Question-1:

Write code and connections in wokwi for the ultrasonic sensor.
Whenever the distance is less than 100cms send an alert to the ibm cloud and display in the device recent events.

Code:

link: [projecta - Wokwi Arduino and ESP32 Simulator](#)

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
  pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
  digitalWrite(TRIG_PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
}

void loop() {
  float distance = readDistanceCM();

  bool isNearby = distance < 100;
```

```

digitalWrite(LED_BUILTIN, isNearby);

Serial.print("Measured distance: ");
Serial.println(readDistanceCM());

delay(100);
}

```

DIAGRAM.JSON:

```

{
  "version": 1,
  "author": "sindhuja",
  "editor": "wokwi",
  "parts": [
    {
      "type": "wokwi-arduino-uno",
      "id": "uno",
      "top": 275.99,
      "left": 47.73,
      "rotate": 0,
      "hide": false,
      "attrs": {}
    },
    {
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 165.87,
      "left": 142.81,
      "rotate": 90,
      "hide": false,
      "attrs": { "value": "220" }
    },
    {
      "type": "wokwi-led",
      "id": "led",
      "top": 87.29,
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": { "color": "blue" }
    },
    {
      "type": "wokwi-hc-sr04",
      "id": "ultrasonic",

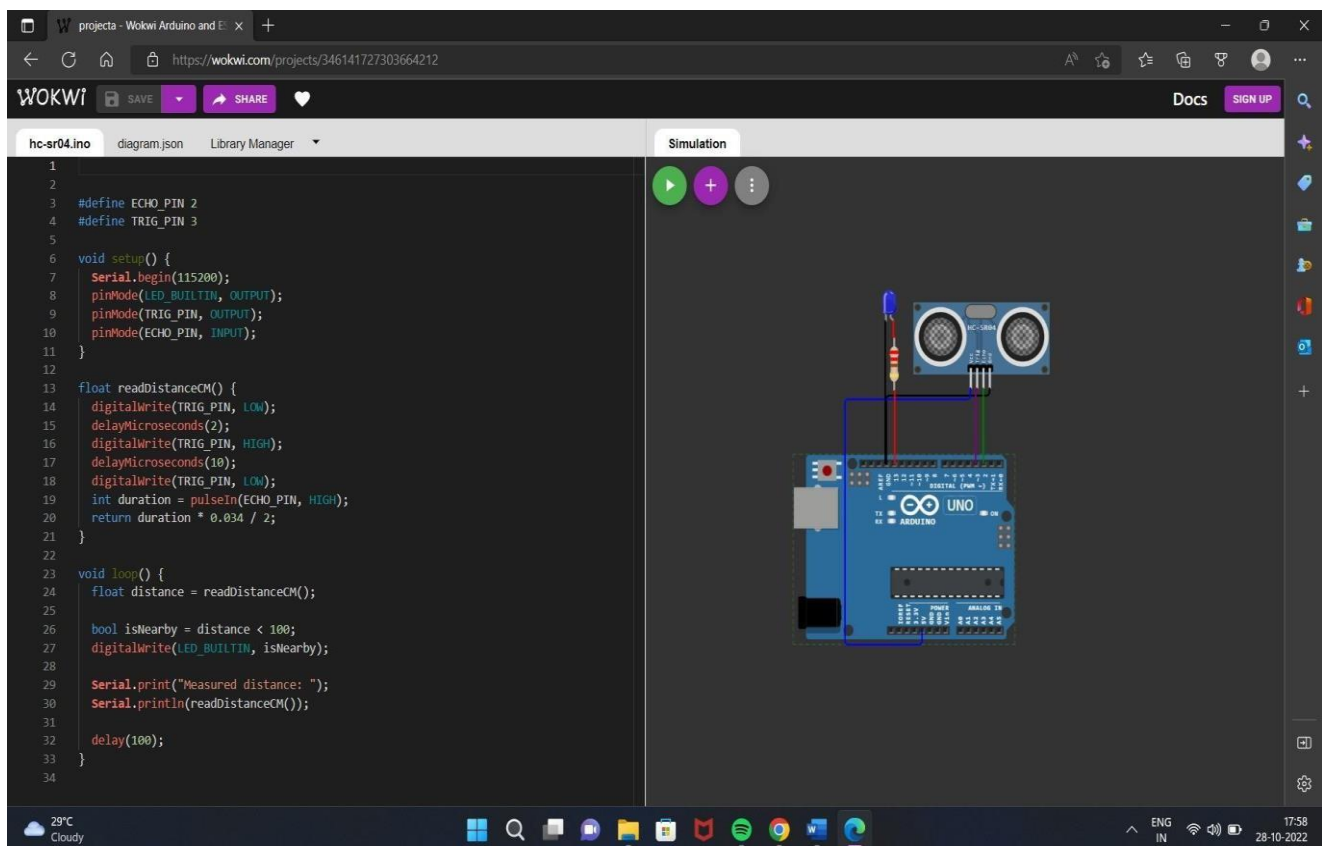
```

```

    "top": 108.43,
    "left": 196.5,
    "rotate": 0,
    "hide": false,
    "attrs": { "distance": "180" }
  }
],
"connections": [
  [ "uno:GND.1", "ultrasonic:GND", "black", [ "v-8", "*", "v8" ] ],
  [ "uno:2", "ultrasonic:ECHO", "green", [ ] ],
  [ "uno:3", "ultrasonic:TRIG", "purple", [ "*", "v4" ] ],
  [ "uno:5V", "ultrasonic:VCC", "blue", [ "v16", "h-96", "*", "v12" ] ],
  [ "uno:GND.1", "led:C", "black", [ ] ],
  [ "r1:1", "led:A", "red", [ ] ],
  [ "uno:13", "r1:2", "red", [ ] ]
]
}

```

OUTPUT:



WOKWI

https://wokwi.com/projects/346141727303664212

SAVE SHARE

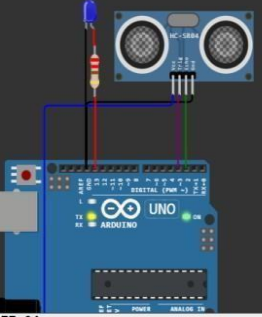
Docs SIGN UP

hc-sr04.ino diagram.json Library Manager

```
1
2
3 #define ECHO_PIN 2
4 #define TRIG_PIN 3
5
6 void setup() {
7   Serial.begin(115200);
8   pinMode(LED_BUILTIN, OUTPUT);
9   pinMode(TRIG_PIN, OUTPUT);
10  pinMode(ECHO_PIN, INPUT);
11 }
12
13 float readDistanceCM() {
14   digitalWrite(TRIG_PIN, LOW);
15   delayMicroseconds(2);
16   digitalWrite(TRIG_PIN, HIGH);
17   delayMicroseconds(10);
18   digitalWrite(TRIG_PIN, LOW);
19   int duration = pulseIn(ECHO_PIN, HIGH);
20   return duration * 0.034 / 2;
21 }
22
23 void loop() {
24   float distance = readDistanceCM();
25
26   bool isNearby = distance < 100;
27   digitalWrite(LED_BUILTIN, isNearby);
28
29   Serial.print("Measured distance: ");
30   Serial.println(readDistanceCM());
31
32   delay(100);
33 }
34
```

Simulation

00:06.794 92%



Measured distance: 177.24
Measured distance: 177.16
Measured distance: 177.26
Measured distance: 177.16
Measured distance: 177.26
Measured distance: 177.16
Measured distance: 177.26

29°C Cloudy

17:58 28-10-2022

WOKWI

https://wokwi.com/projects/346141727303664212

SAVE SHARE

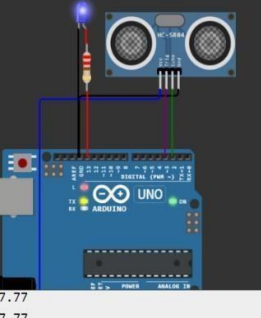
Docs SIGN UP

hc-sr04.ino diagram.json Library Manager

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23 void loop() {
24   float distance = readDistanceCM();
25
26   bool isNearby = distance < 100;
27   digitalWrite(LED_BUILTIN, isNearby);
28
29   Serial.print("Measured distance: ");
30   Serial.println(readDistanceCM());
31
32   delay(100);
33 }
34
```

Simulation

00:17.136 85%



Measured distance: 87.77
Measured distance: 87.77
Measured distance: 87.77
Measured distance: 87.77
Measured distance: 87.77
Measured distance: 87.67
Measured distance: 87.75

29°C Cloudy

17:58 28-10-2022