

Assignment -4

WOKWI SIMULATION

Assignment Date	23 October 2022
Student Name	M.BALA SUBRAMANIAN
Student Roll Number	211419104037
Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an alert to the ibm cloud anddisplay in the device recent events.

Code:

link: [projecta - Wokwi Arduino and ESP32 Simulator](#)

```
#define ECHO_PIN 2
#define TRIG_PIN 3

void setup() {
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);
}

float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    int duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

void loop() {
    float distance = readDistanceCM();

    bool isNearby = distance < 100;
```

```

digitalWrite(LED_BUILTIN, isNearby);

Serial.print("Measured distance: ");
Serial.println(readDistanceCM());

delay(100);
}

```

DIAGRAM.JSON:

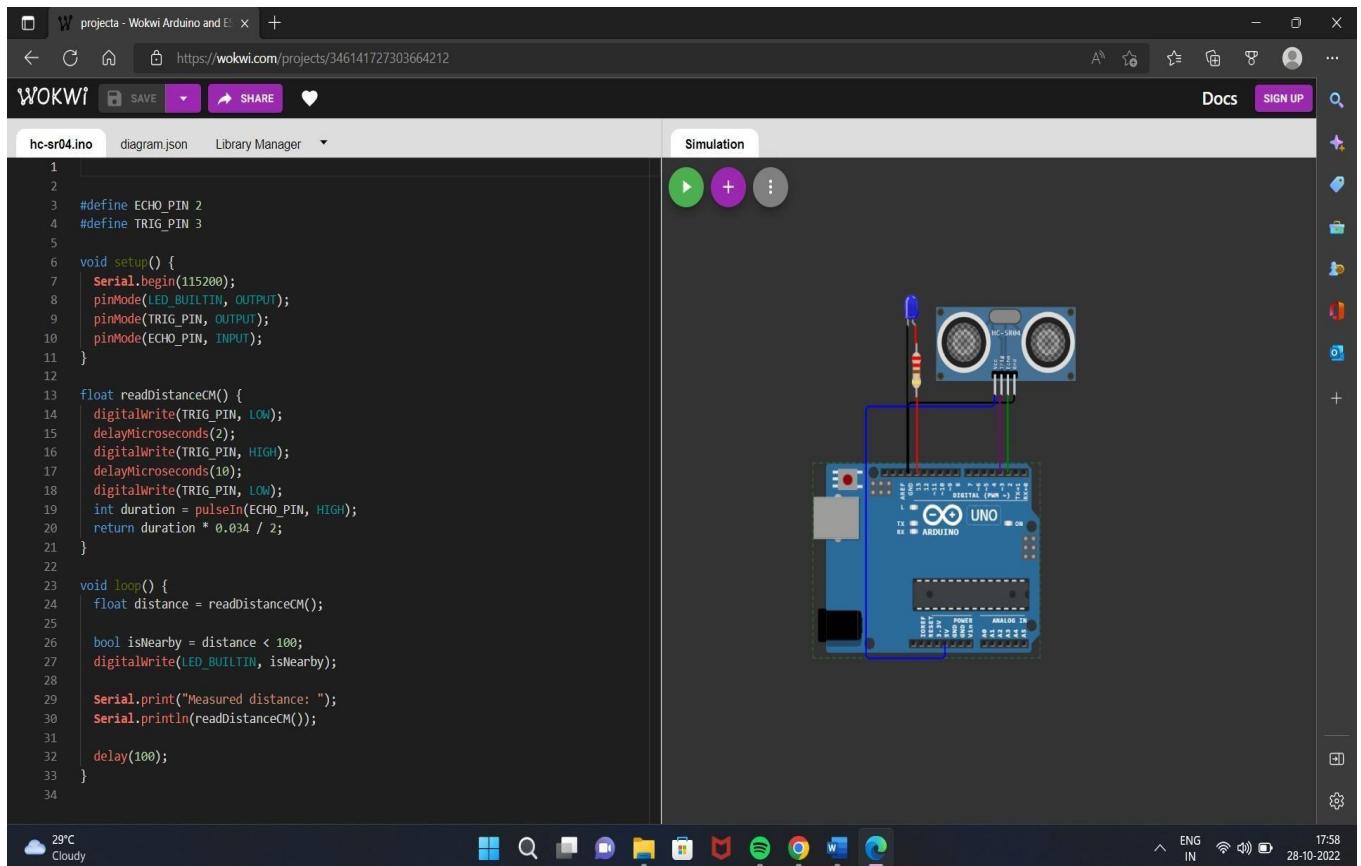
```
{
  "version": 1,
  "author": "sindhuja",
  "editor": "wokwi",
  "parts": [
    {
      "type": "wokwi-arduino-uno",
      "id": "uno",
      "top": 275.99,
      "left": 47.73,
      "rotate": 0,
      "hide": false,
      "attrs": {}
    },
    {
      "type": "wokwi-resistor",
      "id": "r1",
      "top": 165.87,
      "left": 142.81,
      "rotate": 90,
      "hide": false,
      "attrs": { "value": "220" }
    },
    {
      "type": "wokwi-led",
      "id": "led",
      "top": 87.29,
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": { "color": "blue" }
    },
    {
      "type": "wokwi-hc-sr04",
      "id": "ultrasonic",
      "top": 10.0,
      "left": 147.05,
      "rotate": 0,
      "hide": false,
      "attrs": {}
    }
  ]
}
```

```

        "top": 108.43,
        "left": 196.5,
        "rotate": 0,
        "hide": false,
        "attrs": { "distance": "180" }
    }
],
"connections": [
    [ "uno:GND.1", "ultrasonic:GND", "black", [ "v-8", "*", "v8" ] ],
    [ "uno:2", "ultrasonic:ECHO", "green", [ ] ],
    [ "uno:3", "ultrasonic:TRIG", "purple", [ "*", "v4" ] ],
    [ "uno:5V", "ultrasonic:VCC", "blue", [ "v16", "h-96", "*", "v12" ] ],
    [ "uno:GND.1", "led:C", "black", [ ] ],
    [ "r1:1", "led:A", "red", [ ] ],
    [ "uno:13", "r1:2", "red", [ ] ]
]
}

```

OUTPUT:



projecta - Wokwi Arduino and +

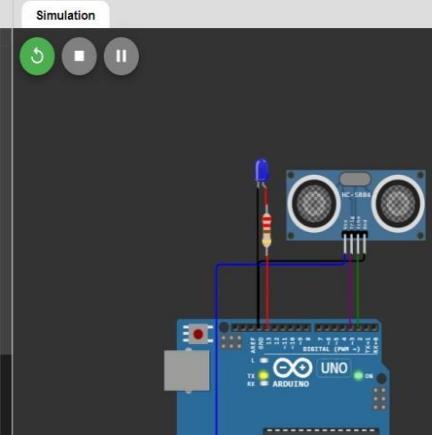
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hc-sr04.ino diagram.json Library Manager

Simulation 00:06.794 92%

```
1
2
3 #define ECHO_PIN 2
4 #define TRIG_PIN 3
5
6 void setup() {
7   Serial.begin(115200);
8   pinMode(LED_BUILTIN, OUTPUT);
9   pinMode(TRIG_PIN, OUTPUT);
10  pinMode(ECHO_PIN, INPUT);
11 }
12
13 float readDistanceCM() {
14   digitalWrite(TRIG_PIN, LOW);
15   delayMicroseconds(2);
16   digitalWrite(TRIG_PIN, HIGH);
17   delayMicroseconds(10);
18   digitalWrite(TRIG_PIN, LOW);
19   int duration = pulseIn(ECHO_PIN, HIGH);
20   return duration * 0.034 / 2;
21 }
22
23 void loop() {
24   float distance = readDistanceCM();
25
26   bool isNearby = distance < 100;
27   digitalWrite(LED_BUILTIN, isNearby);
28
29   Serial.print("Measured distance: ");
30   Serial.println(readDistanceCM());
31
32   delay(100);
33 }
```

Measured distance: 177.24
Measured distance: 177.16
Measured distance: 177.26
Measured distance: 177.16
Measured distance: 177.26
Measured distance: 177.16
Measured distance: 177.26



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Wokwi Arduino and Electronics

https://wokwi.com/projects/346141727303664212

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hc-sr04.ino diagram.json Library Manager

Simulation

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```
1
2
3 #define ECHO_PIN 2
4 #define TRIG_PIN 3
5
6 void setup() {
7     Serial.begin(115200);
8     pinMode(LED_BUILTIN, OUTPUT);
9     pinMode(TRIG_PIN, OUTPUT);
10    pinMode(ECHO_PIN, INPUT);
11 }
12
13 float readDistanceCM() {
14     digitalWrite(TRIG_PIN, LOW);
15     delayMicroseconds(2);
16     digitalWrite(TRIG_PIN, HIGH);
17     delayMicroseconds(10);
18     digitalWrite(TRIG_PIN, LOW);
19     int duration = pulseIn(ECHO_PIN, HIGH);
20     return duration * 0.034 / 2;
21 }
22
23 void loop() {
24     float distance = readDistanceCM();
25
26     bool isNearby = distance < 100;
27     digitalWrite(LED_BUILTIN, isNearby);
28
29     Serial.print("Measured distance: ");
30     Serial.println(readDistanceCM());
31
32     delay(100);
33 }
34 }
```

Measured distance: 87.77
Measured distance: 87.67
Measured distance: 87.75