PROGRAM;
 Float x, y;
Void setup ()
{
 pinMode(8, INPUT);
 pinMode (7, OUTPUT);
 pinMode (A5, INPUT);
 Serial. Begin (9600);
}
Void loop ()
{
 x=digitalRead(8);
 y= analogRead(A5);
 Serial.println(x);
 Serial.println(y);
 if((x>0) && (y<550))

```
  {
   digitalWrite(5, HIGH);
   delay(6000);
  }
else
  DigitalWrite(5,0);
```