Assignment -4 31 October 2022 **Assignment Date** Student Name Sridhar B Student Roll Number 611219106072 **Maximum Marks** 2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cm send "alert" to IBM cloud and display in device recent events.

WOWKI LINK:

https://wokwi.com/projects/347013031284179538

```
Solution:
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
const int trigPin = 5;
const int echoPin = 18;
//define sound speed in cm/uS
#define SOUND_SPEED 0.034
#define CM_TO_INCH 0.393701
long duration;
float distanceCm;
float distanceInch;
void callback(char* subscribetopic, byte*
payload, unsigned int payloadLength);
//----credentials of IBM Accounts-----
#define ORG "13d3kw"//IBM ORGANITION ID
#define DEVICE_TYPE "Assignment-4"//Device
type mentioned in ibm watson IOT Platform
#define DEVICE ID "SridharID"//Device ID
mentioned in ibm watson IOT Platform
#define TOKEN "-
5kdS4xnWYJKUPWDL!" //Token
String data3;
//----- Customise the above values ------
char server[] = ORG
".messaging.internetofthings.ibmcloud.com";//
Server Name
char publishTopic[] = "iot-
2/evt/Data/fmt/json";// topic name and type
of event perform and format in which data to
```

```
be send
char subscribetopic[] = "iot-
2/cmd/test/fmt/String";// cmd REPRESENT
command type AND COMMAND IS TEST OF FORMAT
STRING
char authMethod[] = "use-token-auth";//
authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE
":" DEVICE_ID;//client id
WiFiClient wifiClient; // creating the
instance for wificlient
PubSubClient client(server, 1883, callback
,wifiClient);
void setup() {
 Serial.begin(115200); // Starts the serial
communication
 pinMode(trigPin, OUTPUT); // Sets the
trigPin as an Output
 pinMode(echoPin, INPUT); // Sets the
echoPin as an Input
 Serial.println();
 wificonnect();
 mqttconnect();
}
void loop() {
 // Clears the trigPin
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 // Sets the trigPin on HIGH state for 10
micro seconds
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 // Reads the echoPin, returns the sound
wave travel time in microseconds
 duration = pulseIn(echoPin, HIGH);
 // Calculate the distance
 distanceCm = duration * SOUND_SPEED/2;
  // Convert to inches
 distanceInch = distanceCm * CM_TO_INCH;
 // Prints the distance in the Serial
Monitor
 Serial.print("Distance (cm): ");
 Serial.println(distanceCm);
```

```
Serial.print("Distance (inch): ");
  Serial.println(distanceInch);
 PublishData(distanceCm);
 delay(1000);
  if (!client.loop()) {
    mqttconnect();
}
 void PublishData(float Cm) {
 mqttconnect();//function call for
connecting to ibm
     creating the String in in form JSon to
update the data to ibm cloud
  */
  String payload = "{\"Distance (cm)\":";
  payload += Cm;
  payload += "}";
 Serial.print("Sending payload: ");
 Serial.println(payload);
  if (client.publish(publishTopic, (char*)
payload.c_str())) {
    Serial.println("Publish ok");// if it
sucessfully upload data on the cloud then it
will print publish ok in Serial monitor or
else it will print publish failed
  } else {
    Serial.println("Publish failed");
  }
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId,
authMethod, token)) {
      Serial.print(".");
     delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
void wificonnect() //function defination for
wificonnect
```

```
Serial.println();
 Serial.print("Connecting to ");
 WiFi.begin("Wokwi-GUEST", "", 6);//passing
the wifi credentials to establish the
connection
 while (WiFi.status() != WL CONNECTED) {
   delay(500);
    Serial.print(".");
  }
  Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP address: ");
 Serial.println(WiFi.localIP());
}
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else
 {
    Serial.println("subscribe to cmd
FAILED");
  }
}
void callback(char* subscribetopic, byte*
payload, unsigned int payloadLength)
 Serial.print("callback invoked for topic:
");
 Serial.println(subscribetopic);
 for (int i = 0; i < payloadLength; i++) {</pre>
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
}
```

