IOT BASED SMART CROP PROTECTION SYSTEMFOR AGRICULTURE

Team ID: PNT2022TMID33482

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INTRODUCTION

PROJECT OVREVIEW:

Crops in farms are many times ravagedby local animalslike buffaloes, cows, goats, birds etc. this leads to huge losses for the farmers. It is not possible for farmers tobarricade entire fields or stay on field 24 hours and guard it.so here we proposeautomatic crop protection system from animals. This is a microcontroller based system using PIC family microcontroller. The microcontroller now sound an alarm to woo the animal away from the field as well as sends SMS to the farmer so that he may about the issue and come to the spot in case the animal don't turn away by the alarm. This ensures complete safetyof crop from animals thus protecting farmers loss.

PURPOSE:

Our main purpose of the project is to develop intruder alert to the farm, to avoid losses due to animal and fire. These intruder alert protect the crop that damaging that indirectly increase yield of the crop. The develop system will not harmful and injurious to animal as well as human beings. Theme of project is to design a intelligent security system for farm protecting by using embedded system.

LITERATURE SURVEY

EXISTING PROBLEM:

The existing system mainly provide the surveillance functionality. Also these system don't provide protection from wild animals, especially in such an application area. They also need to take actions based on the type of animal that tries to enter the area, as different methods are adopted to prevent different animals from entering restricted areas. The other commonly used method by farmer in order to prevent the crop vandalization by animals include building physical barriers, use of electric fences andmanual surveillance and various such exhaustive and dangerous method.

REFERENCES:

- Mr.Pranav shitap, Mr.Jayesh redij, Mr.Shikhar Singh, Mr.Durvesh Zagade, Dr. Sharada Chougule. Department of ELECTRONICS AND TELECOMMUNICATION ENGINEERING, Finolex Academy of Management and technology, ratangiri, India.
- ii. N.Penchalaiah, D.Pavithra, B.Bhargavi, D.P.Madhurai, K.EliyasShaik,S.Md.sohaib.Assitant Professor, Department of CSE, AITS, Rajampet, India UG Student. Department of CSE, AITS, Rajampet, India.
- iii. Mr.P.Venkateswara Rao, Mr.Ch Shiva Krishna ,MR M Samba Siva ReddyLBRCE,LBRCE,LBRCE.
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College of engineering, Nagpur head of dept., Electrical engineering, Government College of engineering, Nagpur.

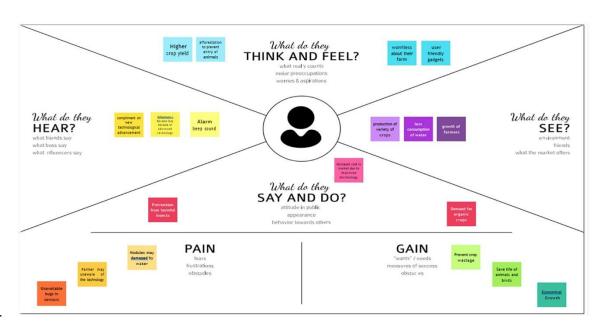
PROBLEM STATEMENT DEFINITION STATEMENT:

In the world economyof many Countrydependent upon the agriculture.

In spite of economic development agriculture is the backbone of the economy. Crops in forms are many times ravaged by local animals like buffaloes, cows, goats, birds and fire etc. this leads to huge loss for the farmers it is not possible for farmers to blockade to entire fields or stay 24 hours and guard it. Agriculture meets food requirements of the people and produces several raw materials for industries. But because of animal interference and fire in agricultural lands, there will be huge loss of crops. Crops will be totally getting destroyed.

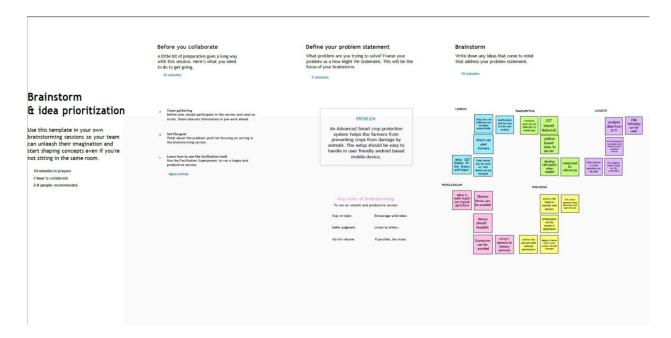
IDEATION AND PROPOSED SOLUTION

EMPATHY MAP CANVAS:



a

IDEATION AND BRAINSTORMING:



Group ideas

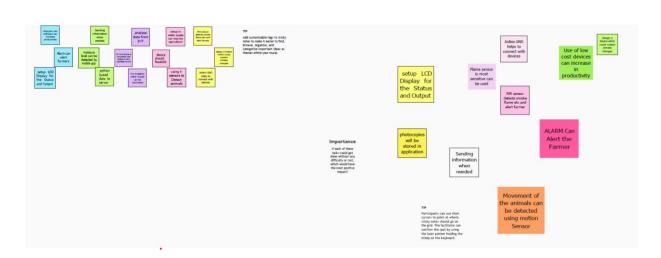
Take turns sharing your ideas while clustering similar or related notes as you go. Once all sticky notes have been grouped, give each cluster a sentence-like label. If a cluster is bigger than six sticky notes, try and see if you and break it up into smaller sub-groups.

20 minut

Prioritize

Your team should all be on the same page about what's important moving forward. Place your ideas on this grid to determine which ideas are important and which are feasible.

20 minute



PROPOSED SOLUTION:

S.NO.	Parameter	Description
1.	Problem Statement. (Problem to be solved)	 ✓ Crops are not irrigated properly due to insufficient labour forces. ✓ Improper maintenance of crops against various environmental factors such as temperature climate, topography and soil quantity which results in crop destruction. ✓ Requires protecting crops from wild animals attacks birds and pests.
2.	Idea /Solution Description.	 ✓ Moisture sensor is interfaced with Arduino Microcontroller to measure the moisture level in soil and relay is used to turn ON & OFF the motor pump for managing the excess water level. It will be updated to authorities through IOT. ✓ Temperature sensor connected to microcontroller is used to monitor the temperature in the field. ✓ Image processing techniques with IOT is followed for crop protection against animal attack.
3.	Novelty / Uniqueness.	✓ Automatic crop maintenance and protection using embedded and IOT Technology.
4.	Social Impact / Customer satisfaction.	✓ This proposed system provides many facilities which helps the farmers to maintain the crop field without much loss.
5.	Business Model (Revenue Model).	✓ This prototype can be developed as product with minimum cost with high performance.
6.	Scalability of the solution	✓ This can be developed to a scalable product by using solution sensors and transmitting the data through Wireless Sensor Network and Analysing the data in cloud and operation is performed using robots.

a.

PROBLEM SOLUTIONFIT:

Title:IOT Based Smart Crop Protection System for Agriculture	Project DesignPhase-I.SolutionFit	TeamID:PNT2022TMID20130
CUSTOMER SEGMENT(S) Farmers who trying to protect crops from various problems	6. CUSTOMER LIMITATIONS EC. BUDGET, DEVICES Limited Supervision. Limited financial constrains. Lack of manpower.	5. AVAILABLE SOLUTIONS PLUSES & MINUSES *Automation in imgation. •CCTV camera tomonitor and nsupervise thebcrops. • Alarmosystem to give alert while animals attacks the crops.
2. PROBLEMS / PAINS + ITS FREQUENCY • Cropsarenotirigatedproperly. • Improper maintenance of crops. • Lack of knowledge among farmers inusage offertilizers and hence crops are affected. • Requires protecting crops from Wild animals attacks, birds and pests.	9. PROBLEM ROOT / CAUSE *Due to in sufficient labourforces. Due to various environmental factors such as temperature climate, to pography and soliquality which results incrop destruction. *Due to high ammonia, urea, potassium and highPHlevel fertilizers.	*Asks suggestions from surrounding peoples and implement there cent technologies. * Consumes more time in cropland. * Searching for an alternative solution for an existing solution.
3. TRIGGERS TO ACT • By seeing surrounding cropland with installing machineries. • Hearing aboutinnovativetechnologies and effective solutions. 4. EMOTIONS REFORE / AFTER • Mentalinustrations due to insufficient production of crops. • Felt smart enough to follow the available technologies with minimum cost.	Moisture sensor interfaced withAnduinoMicrocontroller to measure the moisture level in soil and riday issued totum ON and OFF the motorpump for managing the excess waterlevel. It will be updated to authorities through IOT. Temperature sensor connected to microcontroller issued to monitor the temperature in the field. The optimum	8. CHANNELS of BEHAVIOR ONLING Usingdifferentplatforms/socialmedia to describe the working and uses of smart crop protection device. OFFLINE Giving awarenes among farmers about the application of the device.

REQUIREMENT ANALYSIS

FUNCTIONAL REQUIREMENT:

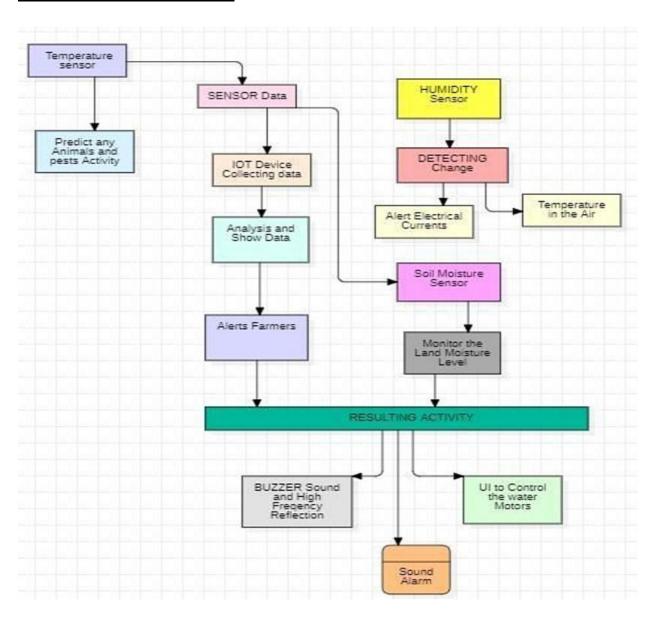
S.NO.	Functional Requirement.	Sub Requirement.
1.	User Visibility	Sense animals nearing the crop field & sounds alarm to woo them away as well as sends SMS to farmer using cloud service.
2.	User Reception	The Data like values of Temperature, Humidity, Soil moisture Sensors are received via SMS.
3.	User Understanding	Based on the sensor data value to get the information about the present of farming land.
4.	User Action	The User needs take action like destruction of crop residues, deep plowing, crop rotation, fertilizers, strip cropping, scheduled planting operations.

NON FUNCTINAL REQUIREMENT:

S.NO.	Non-Functional Requirement.	Description.
1.	Usability	Mobile Support Users must be able to interact in the same roles & tasks on computers & mobile devices where practical, given mobile capabilities.
2.	Security	Data requires secure access to must register and communicate securely on devices and authorized users of the system who exchange information must be able to do.
3.	Reliability	It has a capacity to recognize the disturbance near the field and doesn't give a false caution signal.
4.	Performance	Must provide acceptable response times to users regardless of the volume of data that is stored and the analytics that occurs in background. Bidirectional, near real-time communications must be supported. This requirement is related to the requirement to support industrial and device protocols at the edge.
5.	Availability	IOT Solutions and domains demand highly available systems for 24 x 7 operations. Isn't a critical production application, which means that operations or productiondon't go down if the IOT solution is down.
6.	Scalability	System must handle expanding load & data retention needs that are based on the upscaling of the solution scope, such as extra manufacturing facilities and extra buildings.

PROJECT DESIGN

DATA FLOW DIAGRAM:



SOLUTION AND TECHNICAL ARCHITECTURE:

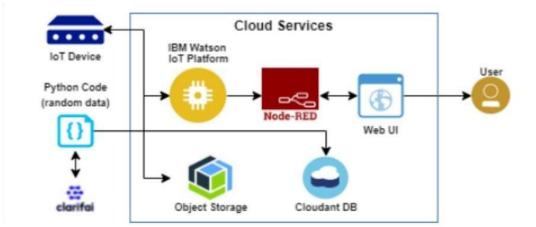


TABLE-1:

a.

sno	components	description	Technology
1	User interface	Interacts with iot	Html,css,angular js etc
		device	
2	Application logic-1	Logic for a process	Python
		in the application	
3	Application logic-2	Logic for process in Clarifai	
		the application	
4	Application logic-3	Logic for process in	IBM Waston Iot
		the application	platform
5	Application logic-4	logic for the process Node red app service	
6	User friendly	Easily manage the	Web uI
İ		net screen appliance	Activate V

TABLE-2: APPLICATION AND CHARACTERISTICS

sno	sno Characteristics Description		Technology
1	Open source framework	Open source framework used	Python
2	Security implementations	Authentication using encryption	Encryptions
3	Scalable architecture	The scalability of architecture consists of 3 models	Web UI Application server- python, clarifai Database server-ibm cloud services.
4	Availability	It is increased by cloudant database	IBM cloud services

USER STORIES:

SPRINT		NCTIONAL QUIREMENT	ST	ER ORY MBER	US	ER STORY/TASK	POINT	rs I	PRIORITY
Sprint-1			US-		ser bei	eate the IBM Cloud vices which are ng used in this ject.	7	1	high
Sprint-1			US	-2	Cre ser bei	eate the IBM Cloud vices which are ng used in this eject.	7	1	high
Sprint-2			US	-3	pla me we dev IBI	M Watson IoT tform acts as the diator to connect the b application to IoT vices, so create the M Watson IoT tform.	5	1	medium
Sprint-2			US	-4	In of Io'll clo in to pla	order to connect the fidevice to the IBM ud, create a device the IBM Watson IoT tform and get the vice credentials	6	1	high
Sprint-3			US	-1	Co cor cre use ser	nfigure the nection security and ate API keys that are d in the Node-RED vice for accessing IBM IoT Platform.	10	1	high
Sprint-3			US	-3	Cre	eate a Node-RED vice	8	1	high
Sprint-3			US	-2	De to p	velop a python script publish random	6	1	medium
						sensor data such as temperature, moistur soil and humidity to IBM IoT platform			
Spri	nt-3			US-1		After developing python code, commands are receiv just print the stateme which represent the control of the device	red nts	8	high
Spri	nt-4			US-3		Publish Data to The IBM Cloud		5	high
Spri	nt-4			US-2		Create Web UI in Node- Red		8	high
Spri	nt-4			US-1		Configure the Node- RED flow to receive data from the IBM Io platform and also use Cloudant DB nodes to store the received sensor data in the cloudant DB	т	6	high

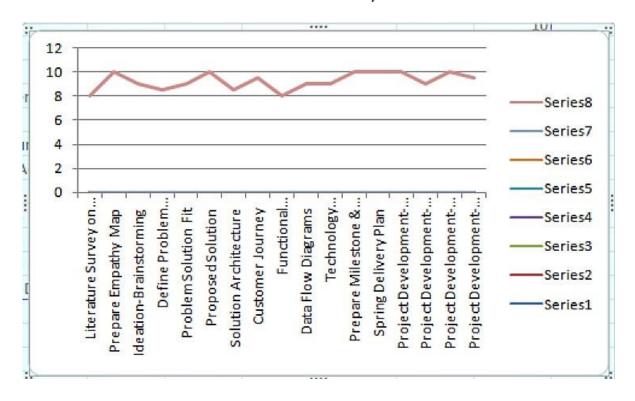
PROJECT PLANNINGAND SCHEDULING **SPRINT PLANNINGAND ESTIMATION:**

Sprint	Total Story Points	Duration	Sprint Start Date	Sprint End Date (Planned)	Story Points Completed (as on Planned End Date)	Sprint Release Date (Actual)
Sprint-1	20	6 Days	24 Oct 2022	29 Oct 2022	20	29 Oct 2022
Sprint-2	20	6 Days	31 Oct 2022	05 Nov 2022	20	05 Nov 2022
Sprint-3	20	6 Days	07 Nov 2022	12 Nov 2022	20	12 Nov 2022
Sprint-4	20	6 Days	14 Nov 2022	19 Nov 2022	20	19 Nov 2022

Velocity:

Imagine we have a 10-day sprint duration, and the velocity of the team is 20 (points per sprint). Let's calculate the team's average velocity iteration unit (story points per day)

$$AV = \frac{sprint\ duration}{velocity} = \frac{20}{10} = 2$$



CODING AND SOLUTIONING

FEATURE-1

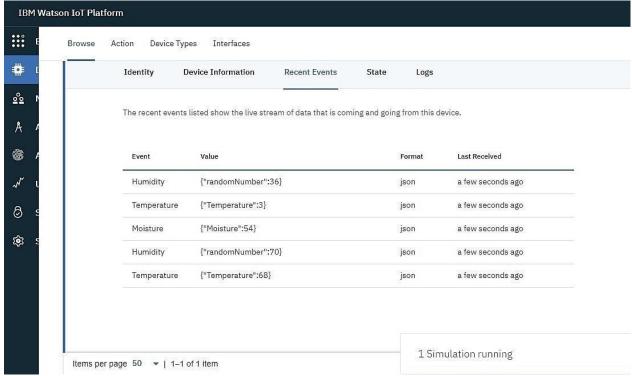
import random import ibmiotf.application import ibmiotf.device from time import sleep import sys #IBM Watson Device Credentials. organization = "op701j" deviceType = "Lokesh" deviceId = "Lokesh89" authMethod = "token" authToken = "1223334444" def myCommandCallback(cmd): print("Command received: %s" % cmd.data['command']) status=cmd.data['command'] if status=="sprinkler_on": print ("sprinkler is ON") print ("sprinkler is OFF") #print(cmd)

```
deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "auth-method": authMethod, "auth-token": authToken}
deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
 print("Caught exception connecting device: %s" % str(e))
#Connecting to IBM watson.
deviceCli.connect()
while True:
#Getting values from sensors.
temp sensor = round( random.uniform(0,80),2)
PH sensor = round(random.uniform(1,14),3)
camera = ["Detected","Not Detected","Not Detected","Not Detected","Not Detected","
camera reading = random.choice(camera)
flame = ["Detected","Not Detected","Not Detected","Not Detected","Not Detected","Not Detected","
flame_reading = random.choice(flame)
moist_level = round(random.uniform(0,100),2)
water_level = round(random.uniform(0,30),2)
#storing the sensor data to send in json format to cloud.
temp_data = { 'Temperature' : temp_sensor }
PH_data = { 'PH Level' : PH_sensor }
camera_data = { 'Animal attack' : camera_reading}
flame_data = { 'Flame' : flame_reading }
moist_data = { 'Moisture Level' : moist_level}
water_data = { 'Water Level' : water_level}
# publishing Sensor data to IBM Watson for every 5-10 seconds.
success = deviceCli.publishEvent("Temperature sensor", "json", temp_data, qos=0)
sleep(1)
if success:
 print (" ......publish ok .....")
print ("Published Temperature = %s C" % temp_sensor, "to IBM Watson")
success = deviceCli.publishEvent("PH sensor", "json", PH data, qos=0)
sleep(1)
if success:
 print ("Published PH Level = %s" % PH_sensor, "to IBM Watson")
success = deviceCli.publishEvent("camera", "json", camera_data, qos=0)
sleep(1)
if success:
 print ("Published Animal attack %s " % camera_reading, "to IBM Watson")
success = deviceCli.publishEvent("Flame sensor", "json", flame_data, qos=0)
sleep(1)
if success:
 print ("Published Flame %s " % flame reading, "to IBM Watson")
success = deviceCli.publishEvent("Moisture sensor", "json", moist_data, qos=0)
sleep(1)
if success:
  print ("Published Moisture Level = %s " % moist level, "to IBM Watson")
```

try:

```
success = deviceCli.publishEvent("Water sensor", "json", water_data, qos=0)
 sleep(1)
 if success:
   print ("Published Water Level = %s cm" % water_level, "to IBM Watson")
 print ("")
 #Automation to control sprinklers by present temperature an to send alert message to IBM Watson.
 if (temp sensor > 35):
   print("sprinkler-1 is ON")
 success = deviceCli.publishEvent("Alert1", "json", { 'alert1' : "Temperature(%s) is high, sprinkerlers are turned ON" %temp_sensor }
, qos=0)
 sleep(1)
if success:
   print( 'Published alert1: ', "Temperature(%s) is high, sprinkerlers are turned ON" %temp_sensor, "to IBM Watson")
 print("")
 print("sprinkler-1 is OFF")
 print("")
 #To send alert message if farmer uses the unsafe fertilizer to crops.
 if (PH sensor > 7.5 or PH sensor < 5.5):
   success = deviceCli.publishEvent("Alert2", "json", \{'alert2': "Fertilizer PH | level(%s) is not safe, use other fertilizer" \ \%PH\_sensor \}, alert2': "Fertilizer PH | level(%s) is not safe, use other fertilizer" \ \%PH\_sensor \}, alert2': "Fertilizer PH | level(%s) | lev
qos=0)
sleep(1)
 if success:
   print('Published alert2:', "Fertilizer PH level(%s) is not safe, use other fertilizer" %PH_sensor, "to IBM Watson")
 print("")
 #To send alert message to farmer that animal attack on crops.
 if (camera_reading == "Detected"):
   success = deviceCli.publishEvent("Alert3", "json", {'alert3': "Animal attack on crops detected"}, qos=0)
 sleep(1)
 if success:
   print('Published alert3:', "Animal attack on crops detected", "to IBM Watson", "to IBM Watson")
 #To send alert message if flame detected on crop land and turn ON the splinkers to take immediate action.
 if (flame reading == "Detected"):
    print("sprinkler-2 is ON")
 success = deviceCli.publishEvent("Alert4", "json", { 'alert4' : "Flame is detected crops are in danger, sprinklers turned ON" }, qos=0)
 sleep(1)
 if success:
   print( 'Published alert4: ', "Flame is detected crops are in danger, sprinklers turned ON", "to IBM Watson")
 #To send alert message if Moisture level is LOW and to Turn ON Motor-1 for irrigation.
 if (moist_level < 20):
   print("Motor-1 is ON")
 success = deviceCli.publishEvent("Alert5", "json", { 'alert5' : "Moisture level(%s) is low, Irrigation started" %moist_level }, qos=0)
 sleep(1)
 if success:
   print('Published alert5:', "Moisture level(%s) is low, Irrigation started" %moist_level, "to IBM Watson")
 print("")
 #To send alert message if Water level is HIGH and to Turn ON Motor-2 to take water out.
```

```
if (water_level > 20):
    print("Motor-2 is ON")
success = deviceCli.publishEvent("Alert6", "json", { 'alert6' : "Water level(%s) is high, so motor is ON to take water out "
%water_level }, qos=0)
sleep(1)
if success:
    print('Published alert6:', "water level(%s) is high, so motor is ON to take water out " %water_level,"to IBM Watson")
    print("")
#command recived by farmer
deviceCli.commandCallback = myCommandCallback
# Disconnect the device and application from the cloud
deviceCli.disconnect()
```



Features

Output: Digital pulse high (3V) when triggered (motion detected) digital low when idle (no motion detected). Pulse lengths are determined by resistors and capacitors on the PCB and differ from sensor to sensor. Power supply: 5V-12V input voltage for most modules (they have a 3.3V regulator), but 5V is ideal in case the regulator has different specs.

BUZZER

Specifications

RatedVoltage: 6V DC

Operating Voltage: 4 to 8V DC

- Rated Current*: ≤30mA
- SoundOutput at 10cm*: ≥85dB
- Resonant Frequency: 2300 ±300Hz
- Tone: Continuous A buzzer is a loud noise maker.

Most modern ones are civil defense or air- raid sirens, tornado sirens, or the sirens on emergency service vehiclessuch as ambulances, police cars and fire trucks. There are two general types, pneumatic and electronic.

FEATURE-2:

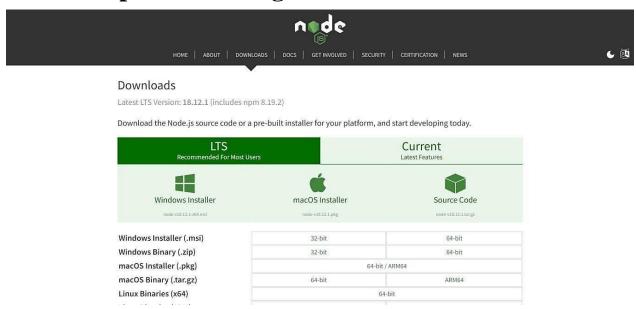
- i. Goodsensitivity to Combustible gas in wide range.
- ii. Highsensitivity to LPG, Propane and Hydrogen .
- iii. Longlife and low cost.
- iv. Simpledrive circuit.

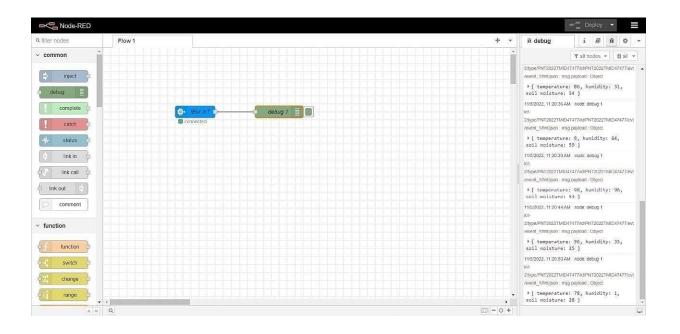
TESTING

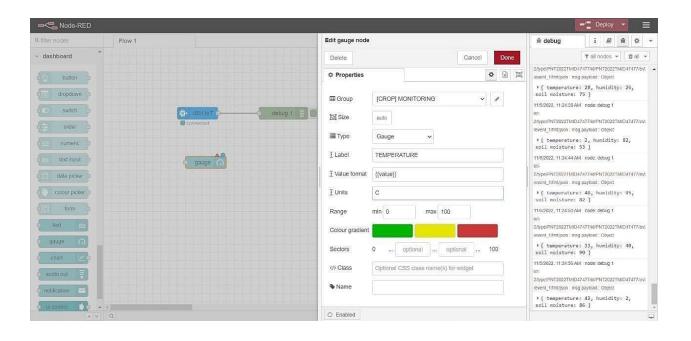
TEST CASES:

sno	parameter	Values	Screenshot
1	Model summary	-	
2	accuracy	Training	
		accuracy-	
		95%	
		Validation	
		accuracy-	
		72%	
3	Confidence score	Class	
		detected-	
		80%	
		Confidence	
		score-80%	

User Acceptance Testing:









RESULTS

The problem of crop vandalization by wild animals and fire has become a major social problem in current time.

It requires urgent attention as no effective solution exists till date for this problem. Thus this project carries a great social relevance as it aims to address this problem. This project willhelp farmers in protecting their orchards and fields and save them from significant financial losses and will save them from the unproductive efforts that they endure for the protection their fields. This will also help them in achieving better crop yields thus leading to their economic wellbeing.

ADVANTAGES AND DISADVANTAGES

Advantage:

Controllable food supply. you might have droughts or floods, but if you are growing the crops and breeding them to be hardier, you have a better chanceof not straving. It allows farmers to maximize yields using minimum resources such as water, fertilizers.

Disadvantage:

The main disadvantage is the time it can take to process the information.in order to keep feeding people as the population grows you have to radically change theenvironment of the planet

CONCLUSION:

A IoT Web Application is built for smart agricultural system using Watson IoT platform, Watsonsimulator, IBM cloud and Node-RED

FUTURE SCOPE

In the future, there will be very large scope, this project can be made based on Image processing in which wild animaland fire can be detected by cameras and if it comes towards farmthen system will be directly activated through wireless networks. Wild animals can also be detected by using wireless networks such as laser wireless sensors and by sensing this laser or sensor's security system will beactivated.

APPENDIX

SOURCE CODE

import time importsys import ibmiotf.application # toinstallpip install ibmiotf importibmiotf.device

```
# Provide your IBM Watson Device Credentials organization = "8gyz7t" #
  replace the ORG ID deviceType = "weather monitor" #replace the Device
  type deviceId = "b827ebd607b5" # replace Device ID authMethod = "token"
  authToken = "LWVpQPaVQ166HWN48f" # Replace the authtoken
  def myCommandCallback(cmd): # function for Callbackif
    cm.data['command'] == 'motoron':
 print("MOTOR ON IS RECEIVED")
elif cmd.data['command'] == 'motoroff':print("MOTOR OFF IS RECEIVED")
if cmd.command == "setInterval":
 else:
if 'interval' not in cmd.data:
  print("Error - command is missing requiredinformation: 'interval'")
  interval = cmd.data['interval']
  elif cmd.command == "print":
 if 'message' not in cmd.data:
           print("Error - commandis missing requiredinformation: 'message'")
           else:output = cmd.data['message']
           print(output)
```

```
try:

deviceOptions = {"org": organization, "type": deviceType, "id": deviceId, "authmethod": authMethod,

"auth-token": authToken} deviceCli

ibmiotf.device.Client(deviceOptions)#

exceptException as e:

print("Caught exception connecting device: %s" % str(e))sys.exit()

# Connect and send a datapoint "hello" with value "world" into the cloud as an event oftype "greeting" 10 times

deviceCli.connect()

while True:

deviceCli.commandCallback = myCommandCallback
```

Disconnect the device and application from the cloud deviceCli.disconnect()

SENSOR.PY

import time import sysimport ibmiotf.application importibmiotf.device import random

Provide your IBM Watson Device Credentials organization = "8gyz7t" # replace the ORG ID deviceType = "weather_monitor" #replace the Device type deviceId = "b827ebd607b5" # replace Device ID authMethod = "token" authToken = "LWVpQPaVQ166HWN48f" # Replace the authtoken

```
def myCommandCallback(cmd):
     print("Command received: %s" % cmd.data['command'])
  print(cmd)
try:
           deviceOptions = {"org": organization, "type": deviceType, "id": deviceId,
  "auth-method": authMethod, "auth-token": authToken}
  deviceCli = ibmiotf.device.Client(deviceOptions)
           #.....
exceptException as e:
         print("Caught exception connecting device: %s" % str(e))sys.exit()
 # Connect and send a datapoint "hello" with value "world" into the cloud as an event oftype "greeting"
  10 times
deviceCli.connect()
while True:
       temp=random.randint(0,1
  00)
  pulse=random.randint(0,100)
       soil=random.randint(0,100)
       data = { 'temp' : temp, 'pulse': pulse ,'soil':soil}
       #print data
                           def
  myOnPublishCallback():
          print ("Published Temperature = %s C" % temp, "Humidity = %s %%" %pulse, "Soil
  Moisture = %s %%" % soil, "to IBM Watson")
       success = deviceCli.publishEvent("IoTSensor", "json", data, qos=0,
  on publish=myOnPublishCallback)
                                                  if not success:
  print("Not connected to
       IoTF")time.sleep(1)
```

Disconnect the device and application from the cloud deviceCli.disconnect()

Node-RED FLOW:

```
[
"id":"625574ead9839b34
"type":"ibmiotout", "z":"630c8601c5ac3295",
"authentication": "apiKey",
"apiKey":"ef745d48e395ccc0",
"outputType":"cmd",
"deviceId": "b827ebd607b5",
"deviceType":"weather_monitor",
"eventCommandType":"data",
"format":"json",
"data":"data",
"qos":0,
"name":"IBM IoT",
"service":"registere
d","x":680,
"y":220,
"wires":[]
},
"id":"4cff18c3274cccc4","type":"ui_button",
"z":"630c8601c5ac3295",
"name":"",
"group":"716e956.00eed6c",
"order":2,
"width":"0",
"height":"0",
```

```
"passthru":false,
"label":"MotorON",
"tooltip":"",
"color":"",
"bgcolor":"",
"className":"",
"icon":"",
"payload":"{\"command\":\"motoron\"}",
"payloadType":"str",
"topic": "motoron",
"topicType":"s
tr","x":360,
"y":160, "wires":[["625574ead9839b34"]]},
{
"id":"659589baceb4e0b0",
"type":"ui_button", "z":"630c8601c5ac3295",
"name":"",
"group":"716e956.00eed6c",
"order":3,
"width":"0",
"height":"0",
"passthru":true,
"label":"MotorOF
F",
"tooltip":"",
"color":"",
"bgcolor":"",
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Moisture",
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  "outputs":1,
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"z":"03acb6ae05a0c712",
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  "outputs":1,
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```
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"name": "httpfunction",
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"collapse":f
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"className
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},
{
"id":"1f4cb829.2fdee8",
"type":"ui_tab",
"name":"Home",
"icon":"dashboard
","order":3,
"disabled":false,
"hidden":false }
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GitHub & Project Demo Link

https://github.com/IBM-EPBL/IBM-Project-16401-1659613469

