ASSIGNMENT 4

ASSIGNMENT QUESTION:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

CODE:

```
esp32-blink.ino •
                    diagram.json •
                                     libraries.txt ●
                                                     Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
         digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
          delayMicroseconds(10);
          digitalWrite(trig,LOW);
          float dur = pulseIn(echo,HIGH);
          float dist = (dur * 0.0343)/2;
Serial.print ("Distancein cm");
          Serial.println(dist);
          PublishData(dist);
          delay(1000);
          if (!client.loop()) {
            mqttconnect();
        void PublishData(float dist) {
          mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

//

//

String object;
if (dist <100)

{
    digitalWrite(LED,HIGH);
    serial.println("object is near");
    object = "Near";
}

else
{
    digitalWrite(LED,LOM);
    serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\":";
    payload += dist;
    payload += ", "\"object\":\"";
    payload += "," "\"object\":\"";
    payload += "\"};

Serial.println(payload);

Serial.println(payload);
</pre>
```

```
dagmanjson  bbranestd  Livray Manager  

general printin("hublish (publishfopub), (char") payload.c_str())) {

general printin("hublish ot"); // if it sucessfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed");

general printin("hublish failed");

general printin("Reconnectic()) {

if (client.connected()) {

inithanagedovice();

serial.printin();

inithanagedovice();

serial.printin();

if (client.connected()) {

inithanagedovice();

serial.printin();

inithanagedovice();

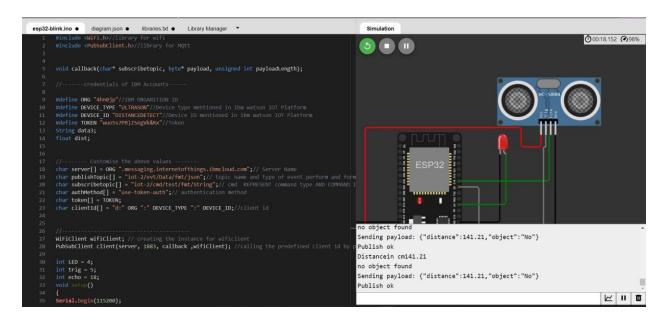
serial.printin();

if (client.connected()) {

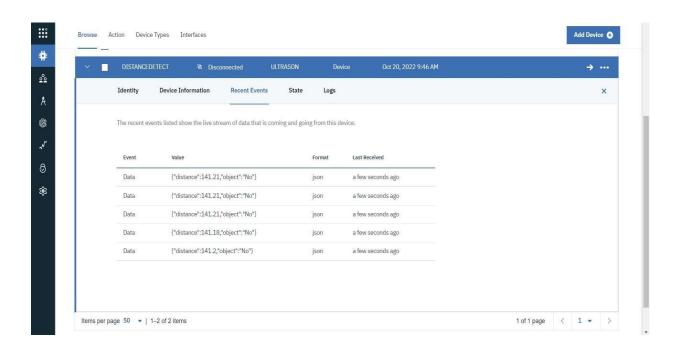
inithanagedovice(
```

```
Library Manager *
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

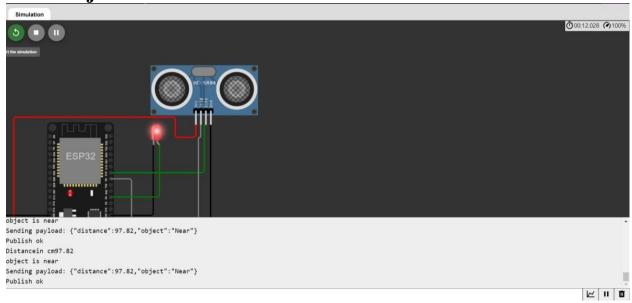
OUTPUT:



Data send to the IBM cloud device when the object is far



When object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near

