TEST CASE REPORT

Team ID	PNT2022TMID51107 Smart Waste Management System for Metropolitan Cities - IOT					
Project Name						
Maximum Marks	4 marks					

Test case	Feature Type- Bin Level	Component	Test Case Scenario	Pre- Requisite	Availability	Test Condition	Expected Result	Actual Result	Status	Comments	Accessed By
Test case 1	Empty	Ultrasonic Sensor	When Bin is empty	Ultrasoncic sensor PIR Motion Sensor Garbage Bins	Bin is accessible to users	Bin Level == 0	Displays Bin level and space left	Working as expected	Pass		MUGESH M
Test case 2	Accessible	Ultrasonic Sensor	When bin level is below 50 %	Ultrasoncic sensor, PIR Motion Sensor, Garbage Bins	Bin is accessible to users	Bin Level < 50	Displays Bin level and space left	Working as expected	Pass		SAI VISHNU L
Test case 3	Accessible	Ultrasonic Sensor	When bin level is above 50	Ultrasoncic sensor, PIR Motion sensor, Garbage Bins	Bin is accessible to users and the admin gets warning about the bin level	Bin Level > 50	Displays Bin level and space left	Working as expected	Pass		MANOJKUMAR R
Test case 4	Accessible	Ultrasonic Sensor	When bin level is below 75 %	Ultrasoncic sensor, PIR Motion sensor, Garbage Bins	Bin is accessible to users and the admin gets warning about the bin level	Bin Level < 75	Displays Bin level and space left	Working as expected	Pass		NHIDHEES LAKSH KUMAR K.B
Test case 5	Limit exceeded	Ultrasonic Sensor	When bin level is above 75 %	Ultrasoncic sensor , PIR Motion sensor , Garbage Bins	Bin is not accessible to the users, the admin recieves High alert and seals the the bin to avoid overflow.	Bin Level > 75	Displays Bin is FULL and Seals the bin.	Working as expected	Pass	The system starts to sense the level once the Bin is emptied partially or fully	MANOJKUMAR R