

VSB ENGINEERING COLLEGE , KARUR
ELECTRONICS AND COMMUNICATION ENGINEERING
ASSIGNMENT - I

TITLE : Industry Specific Intelligent Fire Management
System

NAME : Gunavathi S

DOMAIN NAME : Internet Of Things

MENTOR NAME : Janani S

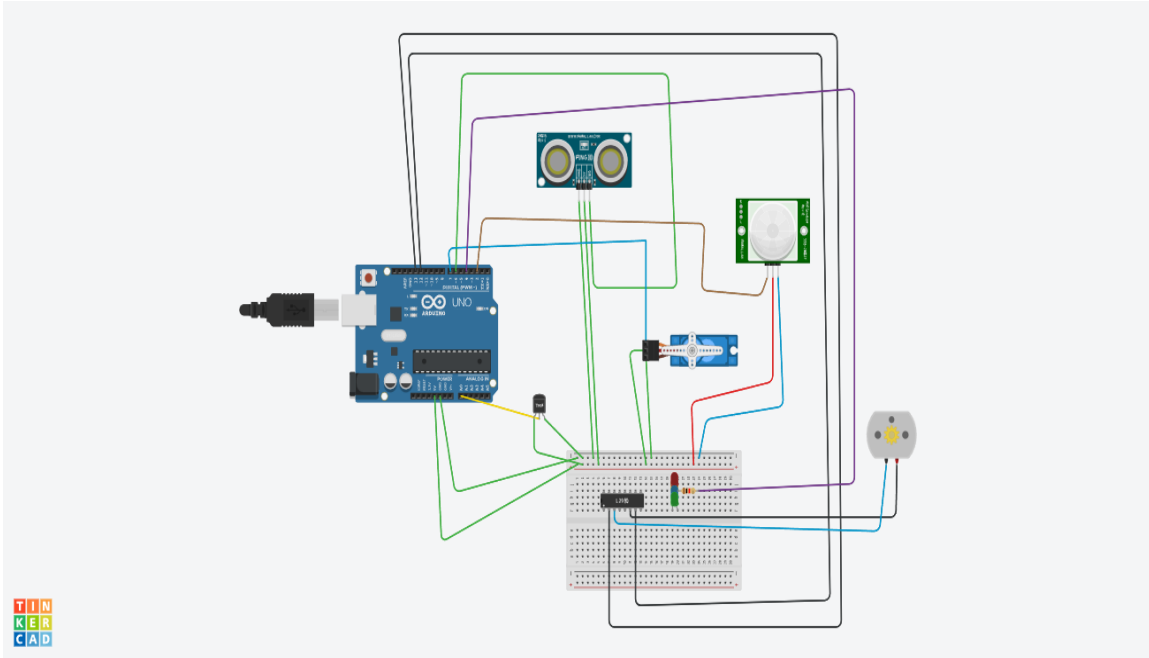
Assignment Topic :

Make a Smart Home in Tinkercad using 2+ sensors,LED,Buzzer
in the single code and Circuit .

Required Materials :

- ❖ Arduino UNO R3
- ❖ Ultrasonic Distance Sensor
- ❖ PIR Sensor
- ❖ DC Motor
- ❖ Micro Servo
- ❖ LED
- ❖ Breadboard

Circuit Design :



Code :

```
#include<Servo.h>
int us = 6;
int servo = 7;

Servo servo1;

void setup() {
  Serial.begin(9600);
  servo1.attach(servo);
  pinMode(2,INPUT);
  pinMode(4,OUTPUT);
}
```

```
pinMode(11,OUTPUT);
pinMode(12,OUTPUT);
pinMode(13,OUTPUT);
pinMode(A0,INPUT);
digitalWrite(2,LOW);
digitalWrite(11,HIGH);

}

void loop() {

    long duration, inches, cm;

    pinMode(us, OUTPUT);
    digitalWrite(us, LOW);
    delayMicroseconds(2);
    digitalWrite(us, HIGH);

    delayMicroseconds(5);

    digitalWrite(us, LOW);

    pinMode(us, INPUT);

    duration = pulseIn(us, HIGH);
    inches = microsecondsToInches(duration);
    cm = microsecondsToCentimeters(duration);

    servo1.write(0);
```

```
if(cm < 30)
{
  servo1.write(120);

  Serial.println("A Person Arrived, Door is Opening.....");
  delay(2000);
}
else
{
  servo1.write(0);
  Serial.println("Door is Closed.....");
}
```

```
int pir = digitalRead(2);
```

```
if(pir == HIGH)
{
  digitalWrite(4,HIGH);
  delay(3000);
}
else if(pir == LOW)
{
  digitalWrite(4,LOW);
}
```

```
float value=analogRead(A0);
```

```
float temp=(((value/1024)*5.0199)-0.5)*100;
```

```
Serial.print("temp is ");  
Serial.println(temp);  
delay(3000);
```

```
if(temp > 20)  
{  
    digitalWrite(12,HIGH);  
    digitalWrite(13,LOW);  
}  
else  
{  
    digitalWrite(12,LOW);  
    digitalWrite(13,LOW);  
}  
}
```

```
long microsecondsToInches(long microseconds) {  
    return microseconds / 74 / 2;  
}
```

```
long microsecondsToCentimeters(long microseconds) {  
    return microseconds / 29 / 2;  
}
```

OUTPUT :

tinkercad.com/things/4MWgyn12rSD-fabulous-vihelmo-borwo/editel?tenant=circuits

Assignment 1

Saving...

Simulator time: 00:00:20.347

Code Stop Simulation Send To

1 (Arduino Uno R3)

```
1 // C++ code
2 //
3 #include<Servo.h>
4 int us = 6;
5 int servo = 7;
6
7 Servo servol;
8
9 void setup() {
10   Serial.begin(9600);
11   servol.attach(servo);
12   pinMode(2, INPUT);
13   pinMode(4, OUTPUT);
14   pinMode(11, OUTPUT);
15   pinMode(12, OUTPUT);
16   pinMode(13, OUTPUT);
17   pinMode(A0, INPUT);
18   digitalWrite(2, LOW);
19   digitalWrite(11, HIGH);
20
21 }
22
```

Serial Monitor

A Person Arrived, Door is Opening.....
temp is -50.00
A Person Arrived, Door is Opening.....
temp is -50.00
A Person Arrived, Door is Opening.....
temp is -50.00
A Person Arrived, Door is Opening.....
temp is -50.00

Send Clear

