

# **V.S.B ENGINEERING COLLEGE, KARUR-639111**

## **ASSIGNMENT-4**

**Name** : Jegapriya P  
**Project Title** : Industry Specific- Intelligent Fire Management System  
**Project Domain**: Internet of Things

**1. Write Code and connections in wok Wi for ultrasonic sensor. whatever distance is less than 100 CMS send "Alert" to IBM cloud and display in device recent events.**

### **Solution:**

```
//Pins
const int TRIG_PIN = 7 ;
const int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG_PIN, LOW);

//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT ) ;

// We'll use the serial monitor to view the sensor output
```

```

Serial.begin(9600)
}

void loop()
{ unsigned long
t1;

unsigned long t2;

unsigned long pulse_width;

float cm;

float inches;

// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);


// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0 );


// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after ~70 min
t1= micros ();
while (digitalRead(ECHO_PIN) == 1);
t2= micros ();
pulse_width = t2-t1;


// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (~ 340m/s)
cm=pulse_Width / 58 ;

```

```

inches = pulse_width/148.0;

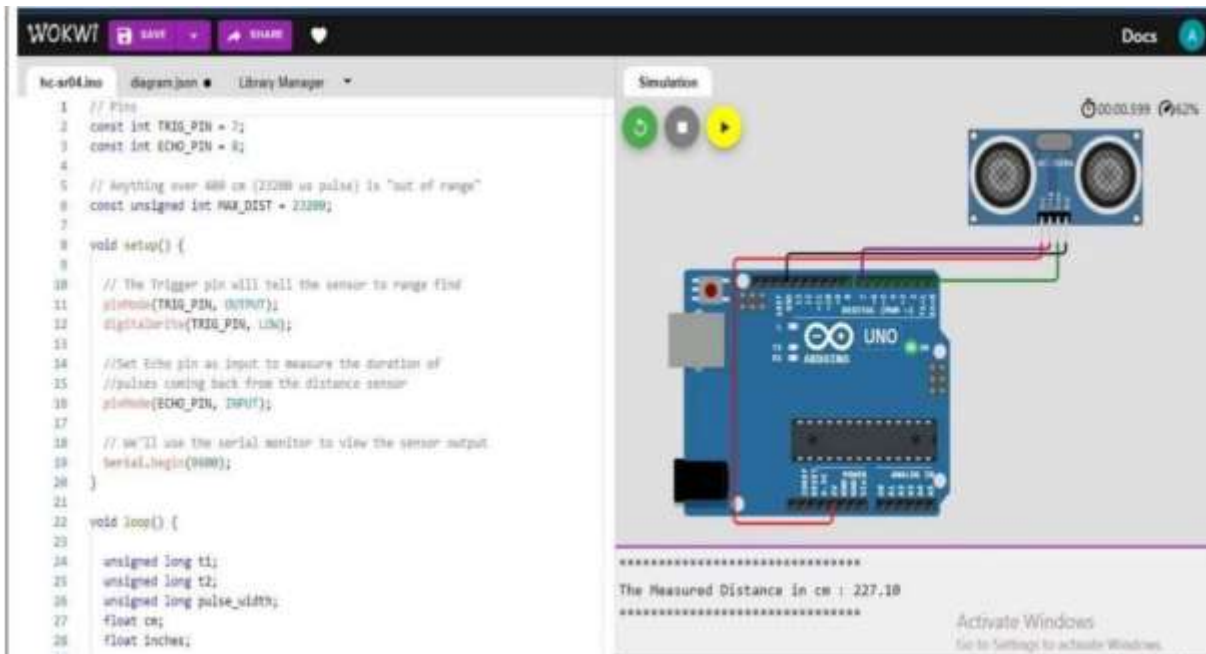
// Print out results
if (pulse_width > MAX _
DIST ){Serial.println("Out of
range");
} else
{ Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
        //}
}
Serial.print("*****");
}
//wait at least 1000ms before next measurement
Delay(1000);
}

```

## Output:

1.If the distance is less than 100 CMS ,it alert



## 2.Simulation and code execution:

