

# **EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES**

## **VIDEO ANALYSIS**

### **OPEN CV FOR VIDEO PROCESSING**

<b>Date</b>	07 November 2022
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<b>Project Name</b>	Emerging Methods for Early Detection of Forest Fires

#### ***Importing The ImageDataGenerator Library***

```
import keras
from keras.preprocessing.image import ImageDataGenerator
```

#### ***Define the parameters/arguments for ImageDataGenerator class***

```
train_datagen=ImageDataGenerator(rescale=1./255,shear_range=0.2,rotation_range=180,zoom_range=0.2, horizontal_flip=True)
test_datagen=ImageDataGenerator(rescale=1./255)
```

#### ***Applying ImageDataGenerator functionality to trainset***

```
x_train=train_datagen.flow_from_directory(r'/content/drive/MyDrive/Dataset/train_set',target_size=(128,128),batch_size=32,
class_mode='binary')
```

Found 436 images belonging to 2 classes.

### ***Applying ImageDataGenerator functionality to testset***

```
x_test=test_datagen.flow_from_directory(r'/content/drive/MyDrive  
/ Dataset/test_set',target_size=(128,128),batch_size=32,  
class_mode='binary')
```

Found 121 images belonging to 2 classes.

### ***Import model building libraries***

```
#To define Linear initialisation import Sequential  
from keras.models import Sequential  
#To add layers import Dense  
from keras.layers import Dense  
#To create Convolution kernel import Convolution2D  
from keras.layers import Convolution2D  
#import Maxpooling layer  
from keras.layers import MaxPooling2D  
#import flatten layer  
from keras.layers import Flatten  
import warnings  
warnings.filterwarnings('ignore')
```

### ***Initializing the model***

```
model=Sequential()
```

### ***Add CNN Layer***

```
model.add(Convolution2D(32,  
(3,3),input_shape=(128,128,3),activation='relu'))  
#add maxpooling layer  
  
model.add(MaxPooling2D(pool_size=(2,2)))  
#add flatten layer  
model.add(Flatten())
```

### ***Add Hidden Layer***

```
#add hidden layer
model.add(Dense(150,activation='relu'))
#add output layer
model.add(Dense(1,activation='sigmoid'))
)
```

### ***Configure the learning process***

```
model.compile(loss='binary_crossentropy',optimizer="adam",metrics=[
"accuracy"])
```

### ***Train the model***

```
model.fit_generator(x_train,steps_per_epoch=14,epochs=10,validation_
data=x_test,validation_steps=4)
```

Epoch 1/10

14/14 [=====] - 97s 7s/step - loss: 1.3060 -

accuracy: 0.7775 - val\_loss: 0.5513 - val\_accuracy: 0.8512

Epoch 2/10

14/14 [=====] - 26s 2s/step - loss: 0.3178 -

accuracy: 0.8807 - val\_loss: 0.1299 - val\_accuracy: 0.9421

Epoch 3/10

14/14 [=====] - 26s 2s/step - loss: 0.2226 -

accuracy: 0.9106 - val\_loss: 0.1311 - val\_accuracy: 0.9421

Epoch 4/10

14/14 [=====] - 31s 2s/step - loss: 0.1836 -

accuracy: 0.9174 - val\_loss: 0.1129 - val\_accuracy: 0.9339

Epoch 5/10

14/14 [=====] - 30s 2s/step - loss: 0.1675 -

accuracy: 0.9243 - val\_loss: 0.0925 - val\_accuracy: 0.9669  
Epoch 6/10  
14/14 [=====] - 26s 2s/step - loss: 0.1884 -  
accuracy: 0.9289 - val\_loss: 0.1287 - val\_accuracy: 0.9339  
Epoch 7/10  
14/14 [=====] - 28s 2s/step - loss: 0.1724 -  
accuracy: 0.9335 - val\_loss: 0.0926 - val\_accuracy: 0.9752  
Epoch 8/10  
14/14 [=====] - 26s 2s/step - loss: 0.1510 -  
accuracy: 0.9404 - val\_loss: 0.0757 - val\_accuracy: 0.9752  
Epoch 9/10  
14/14 [=====] - 26s 0.173 -  
2s/step - loss: 2  
accuracy: 0.9174 - val\_loss: 0.0537 - val\_accuracy: 0.9835  
Epoch 10/10  
14/14 [=====] - 26s 0.154 -  
2s/step - loss: 6  
accuracy: 0.9312 - val\_loss: 0.0573 - val\_accuracy: 0.9835  
<keras.callbacks.History at 0x7f05d66a9c90>

## ***Save The Model***

```
model.save("forest1.h5")
```

## ***Predictions***

```
#import load_model
from keras.model from
keras.models import
load_model #import
image class from keras
from tensorflow.keras.preprocessing import image #import
numpy
import numpy as np
#import cv2
import cv2
```

*#load the saved model*

```
model = load_model("forest1.h5")
```

```
img=image.load_img(r'/content/drive/MyDrive/Dataset/test_set/forest/ 0.48007200_1530881924_final_forest.jpg')
```

```
x=image.img_to_array(img)
```

```
res = cv2.resize(x, dsize=(128, 128),  
interpolation=cv2.INTER_CUBIC)
```

*#expand the image shape*

```
x=np.expand_di
```

```
ms(res,axis=0)
```

```
pred=
```

```
model.predict(x)
```

```
1/1 [=====] - 0s
```

```
126ms/step
```

```
pred
```

```
array([[0.]], dtype=float32)
```

## ***OpenCV For Video Processing***

pip install twilio

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: twilio in

/usr/local/lib/python3.7/dist-packages (7.15.1)

Requirement already satisfied: pytz in /usr/local/lib/python3.7/dist-packages (from twilio) (2022.5)

Requirement already satisfied: requests>=2.0.0 in

/usr/local/lib/python3.7/dist-packages (from twilio) (2.23.0)

Requirement already satisfied: PyJWT<3.0.0,>=2.0.0 in

/usr/local/lib/python3.7/dist-packages (from twilio) (2.6.0) Requirement

already satisfied: urllib3!=1.25.0,!1.25.1,<1.26,>=1.21.1 in

/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (1.24.3)

Requirement already satisfied: certifi>=2017.4.17 in

/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2022.9.24)

Requirement already satisfied: idna<3,>=2.5 in

/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2.10)

Requirement already satisfied: chardet<4,>=3.0.2 in

/usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (3.0.4)

pip install playsound

Looking in indexes: <https://pypi.org/simple>, <https://us-python.pkg.dev/colab-wheels/public/simple/>

Requirement already satisfied: playsound in

/usr/local/lib/python3.7/dist-packages (1.3.0)

*#import opencv library*

import cv2

*#import numpy*

import numpy as np

*#import image function from keras*

from keras.preprocessing import

```
image #import load_model from  
keras  
from keras.models import load_model  
#import client from twilio API  
from twilio.rest import Client  
#import playsound package  
from playsound import playsound
```

WARNING:playsound:playsound is relying on another python subprocess. Please use `pip install pygobject` if you want playsound to run more efficiently.

```
#load the saved model  
model=load_model("forest1.h  
5") #define video  
video=cv2.VideoCapture(0)  
#define the features  
name=['forest','with fire']
```