

ASSIGNMENT-4

**Name:** Divya A

**Project Title:** Smart Farmer- IoT Enabled Smart Farming Application

**Project Domain:** Internet of Things

**1. Write Code and connections in Wok Wi for ultrasonic sensor. whatever distance is less than 100 CMS send "Alert" to IBM cloud and display in device recent events.**

**Solution:**

```
//Pins
```

```
const int TRIG_PIN = 7 ;
```

```
const int ECHO_PIN = 8;
```

```
//Anything over 400 cm (23200 us pulse) is "out of range"
```

```
const unsigned int MAX_DIST = 23200;
```

```
void setup() {
```

```
// The Trigger pin will tell the sensor to range find
```

```
  Pin Mode(TRIG_PIN, OUTPUT);
```

```
  digital Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the duration of
```

```
//pulses coming back from the distance sensor
```

```
  pinMode(ECHO_PIN, INPUT ) ;
```

```
// We'll use the serial monitor to view the sensor output
```

```
  Serial.begin(9600)
```

```

}

void loop()
{ unsigned long
t1;

unsigned long t2;

unsigned long pulse_width;

float cm;

float inches;

// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);


// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )==0 );


// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after 70 min
t1= micros ();

while (digitalRead(ECHO_PIN) == 1);

t2= micros ();

pulse_width = t2-t1;


// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58 ;

inches = pulse_width/148.0;

```

```

// Print out results
if (pulse_width > MAX _
DIST ){Serial.println("Out of
range");
} else
{ Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

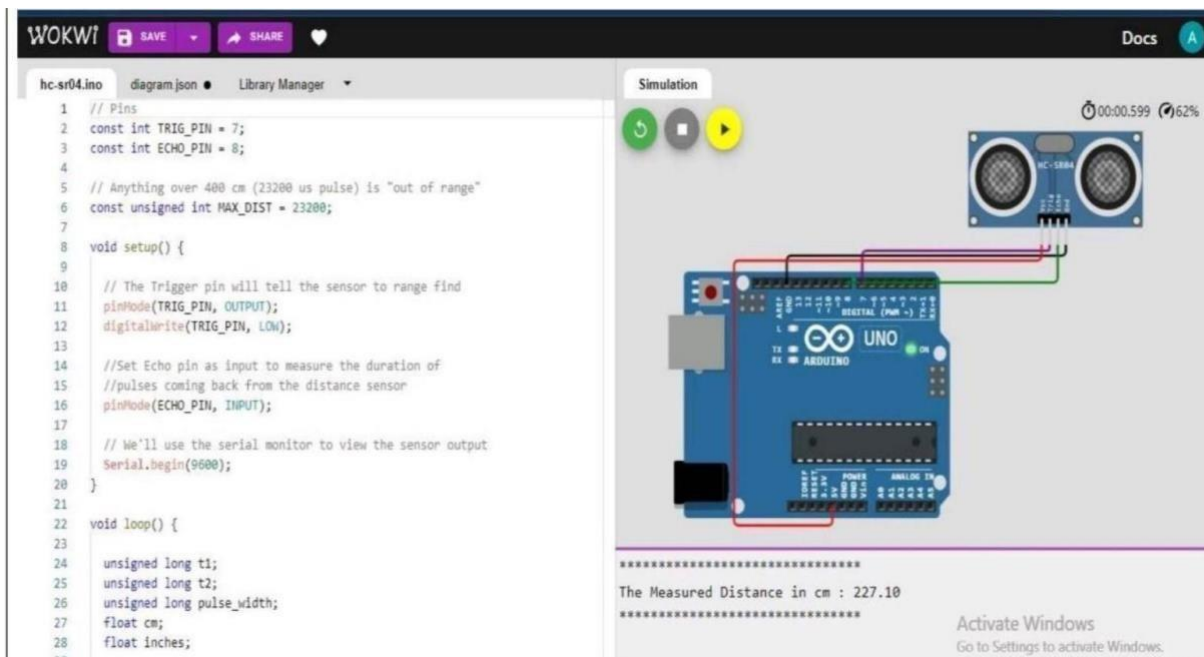
if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
        //}
}
Serial.print("*****");
}

//wait at least 1000ms before next measurement
Delay(1000);
}

```

## Output:

1. If the distance is less than 100 CMS ,italert



## 2.Simulation and code execution:

