## V.S.B ENGINEERING COLLEGE,KARUR-639111 ASSIGNMENT-4

Name: Dharani S

Project Title: Smart Farmer- IoT Enabled Smart Farming Application

**Project Domain:** Internet of Things

1.Write Code and connections in wok Wi for ultrasonic sensor. whatever distance is less than 100 CMS send "Alert" to IBM cloud and display in device recent events.

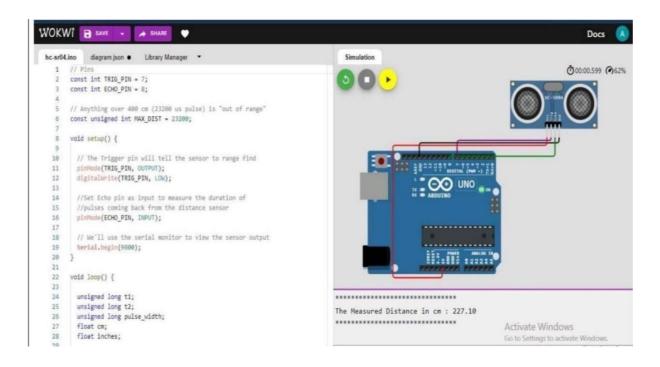
```
Solution:
//Pins
const int TRIG PIN = 7;
const int ECHO PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX DIST = 23200;
void setup() {
// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG PIN, LOW);
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO PIN, INPUT );
// We'll use the serial monitor to view the sensor output
Serial.begin(9600)
```

```
}
  void loop()
  { unsigned long
  t1;
  unsigned long t2;
  unsigned long pulse_width;
  float cm;
  float inches;
  // Hold the trigger pin high for at least 10 us
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
  // Wait for pulse on echo pin
  while (digitalRead( ECHO_PIN )==0 );
  // Measure how long the echo pin was held high (pulse width)
  // Note: the micros() counter will overflow after-70 min
  t1= micros ();
   while (digitalRead(ECHO PIN) == 1);
   t2= micros ();
   pulse_width = t2-t1;
  // Calculate distance in centimeters and inches. The constants
  //are found in the datasheet, and calculated from the assumed speed
  // of sound in air at sea level (- 340m/s)
  cm=pulse_Width / 58;
  inches = pulse width/148.0;
```

```
// Print out results
if (pulse_width >MAX _
DIST ){Serial.println("Out of
range");
} else
{ Serial.println("*********************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if( cm < 100){
   //while(true){
   Serial.println("Alert!!");
   //}
}
Serial.print("*********************************);
}
//wait at least 1000ms before next measurement
Delay(1000);
}
```

## **Output:**

1. If the distance is less than 100 CMS ,italert



## 2. Simulation and code execution:

