## **Develop a python script**

Team ID	PNT2022TMID33576
Project Name	Smart waste management system for
	metropolitan cities

Step 1: Open python idle

Step2: Type the program Step

3: Then click on file and save the document Step

4: Thenclick on Run then Run Module Step

5: output will be appeared in the idle window

## **Python script**

```
import requests import
json import
ibmiotf.application import
ibmiotf.device import time
import random import sys
# watson device details
organization
"4yi0vc"
          devicType =
"BIN1"
          deviceId
"BIN1ID"
            authMethod=
"token"
             authToken=
"123456789"
#generate random values for randomo variables (temperature&humidity)
  def
myCommandCallback(cmd):
```

```
global a print("command recieved:%s"
%cmd.data['command'])
control=cmd.data['command'] print(control)
try:
```

```
deviceOptions={"org": organization, "type": devicType, "id": deviceId, "auth-
method":authMethod, "authtoken":authToken} deviceCli = ibmiotf.device.Client(deviceOptions) except
Exception as e:
        print("caught exception connecting device %s" %str(e))
sys.exit()
#connect and send a datapoint "temp" with value integer value into the cloud as a type of event for every 10 seconds
deviceCli.connect()
 while
True:
     distance= random.randint(10,70)
loadcell= random.randint(5,15)
                                   data=
{'dist':distance,'load':loadcell}
          if loadcell < 13 and loadcell
> 15:
        load = "90 %"
elif loadcell < 8 and loadcell > 12:
          load = "60 %"
elif loadcell < 4 and loadcell > 7:
          load = "40 %"
else:
          load = "0 %"
if distance < 15:
          dist = 'Risk warning:' 'Dumpster poundage getting high, Time to collect :) 90 %'
                              elif
distance < 40 and distance >16:
          dist = 'Risk warning:' 'dumpster is above 60%'
                     elif distance < 60
and distance > 41:
                             dist =
'Risk warning:' '40 %'
                           else:
          dist = 'Risk warning:' '17 %'
                                      if
load == "90 %" or distance == "90 %":
          warn = 'alert :' ' Dumpster poundage getting high, Time to collect :)'
```

```
elif load == "60 %" or
distance == "60 %":
                           warn = 'alert :'
'dumpster is above 60%'
                           else :
         warn = 'alert :' 'No need to collect right now '
def myOnPublishCallback(lat=10.678991,long=78.177731):
        print("Gandigramam, Karur")
                                      print("published distance = %s " %distance, "loadcell:%s "
%loadcell, "lon = %s " %long, "lat = %s" %lat)
                                                     print(load)
                                                                         print(dist)
                                                                                             print(warn)
   time.sleep(10)
            success=deviceCli.publishEvent ("IoTSensor","json",warn,qos=0,on publish=
                            success=deviceCli.publishEvent
myOnPublishCallback)
("IoTSensor", "json", data, qos=0, on_publish= myOnPublishCallback)
          if not success:
print("not connected to ibmiot")
time.sleep(30)
deviceCli.commandCallback=myCommandCallback
#disconnect the device deviceCli.disconnect
```

## **Screenshots Python script:**



