ASSIGNMENT-4
DISTANCE DETECTION USING ULTRASONICSENSOR

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 centimetersit should send "alert" to IBM cloud and display in device recent events

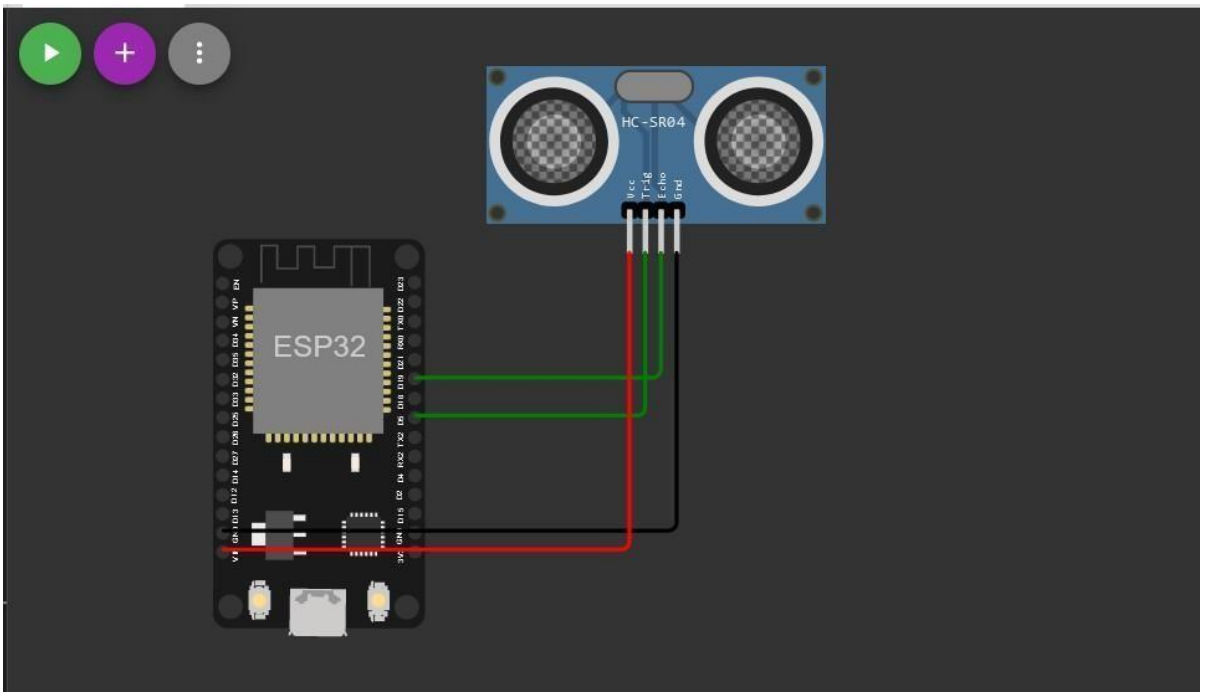
Code:

```
#include <WiFi.h>
#include
<PubSubClient.h>
#include <ArduinoJson.h>
WiFiClient wifiClient;


#define ORG "9tg03j"


#define DEVICE_TYPE "RaspberryPi"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
#define speed 0.034

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/status1/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

PubSubClient client(server, 1883, wifiClient);
void publishData();

const int trigpin=5;
```

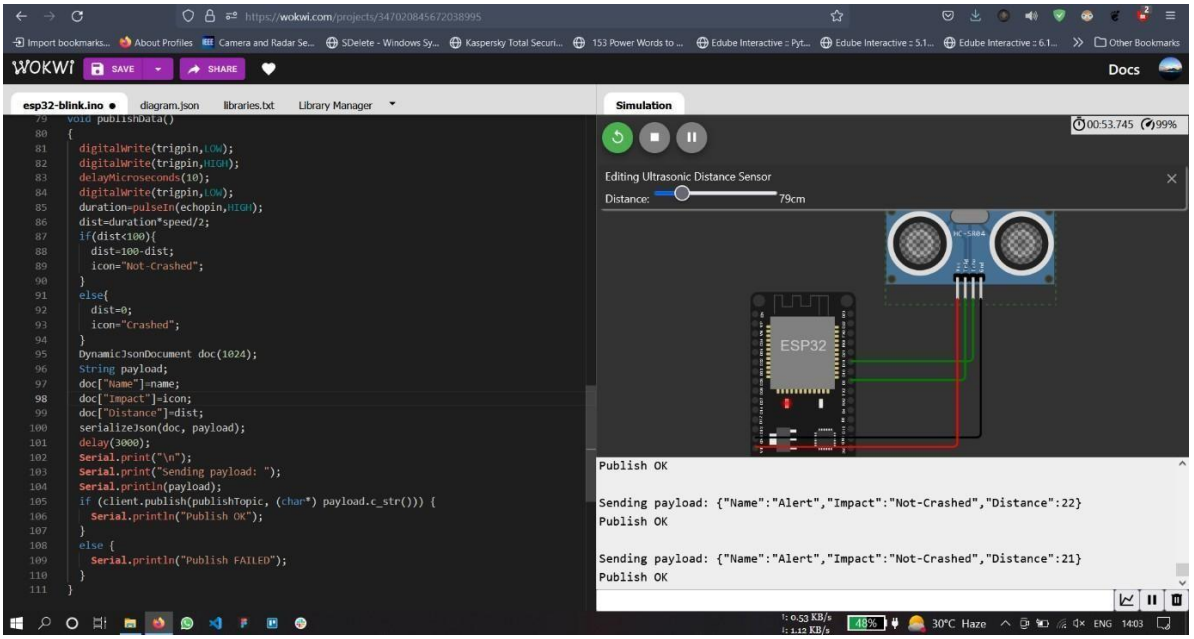
```
const int echopin=19;
String command;
String  data="";
String name="Alert";
String icon="";
long duration;
int dist;
void setup()
{
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
void loop() {
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to ");
  Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
    Serial.print(".");
      Serial.print("*");
      delay(1000);
    }
    initManagedDevice();
    Serial.println();
  }
}

void initManagedDevice() {
```

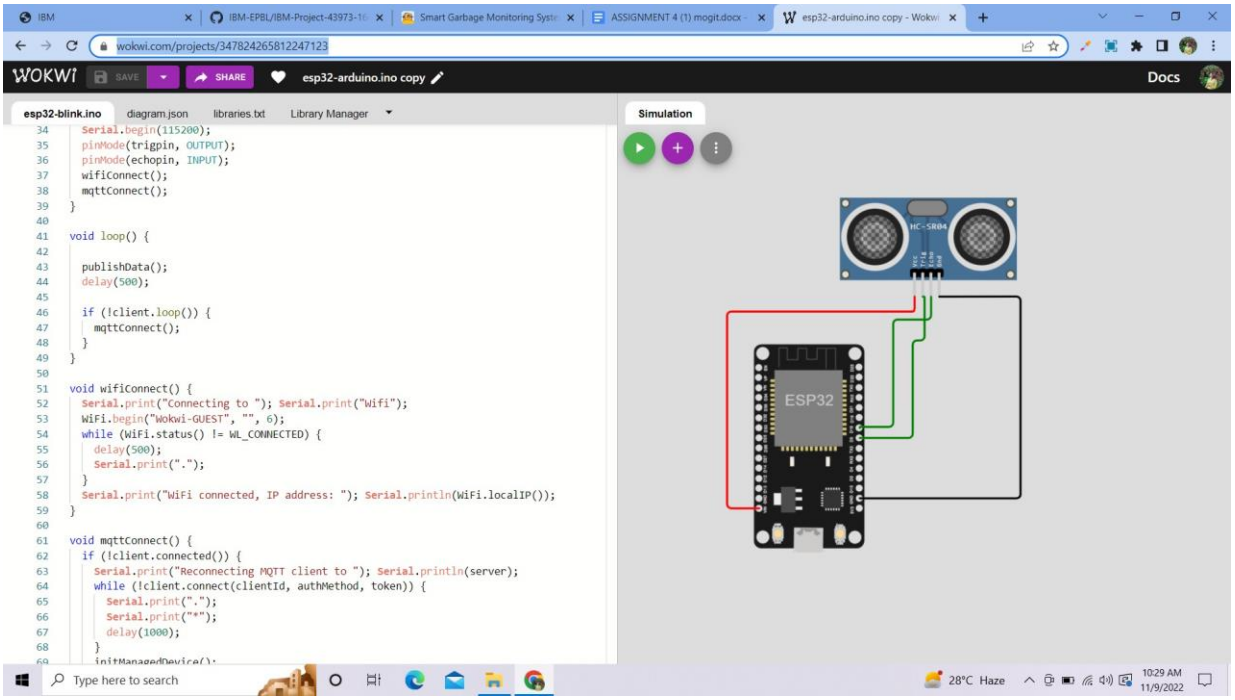
```
  if (client.subscribe(topic)) {
    Serial.println(client.subscribe(topic));
    Serial.println("subscribe to cmd OK");
  }
  else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    dist=100-dist;
    icon="Not-Crashed";
  }
  else{
    dist=0;
    icon="Crashed";
  }
  DynamicJsonDocument doc(1024);
  String payload;
  doc["Name"]=name;
  doc["Impact"]=icon;
  doc["Distance"]=dist;
  serializeJson(doc, payload);
  delay(3000);
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
  }
  else {
    Serial.println("Publish FAILED");
  }
}
```

DIAGRAM:

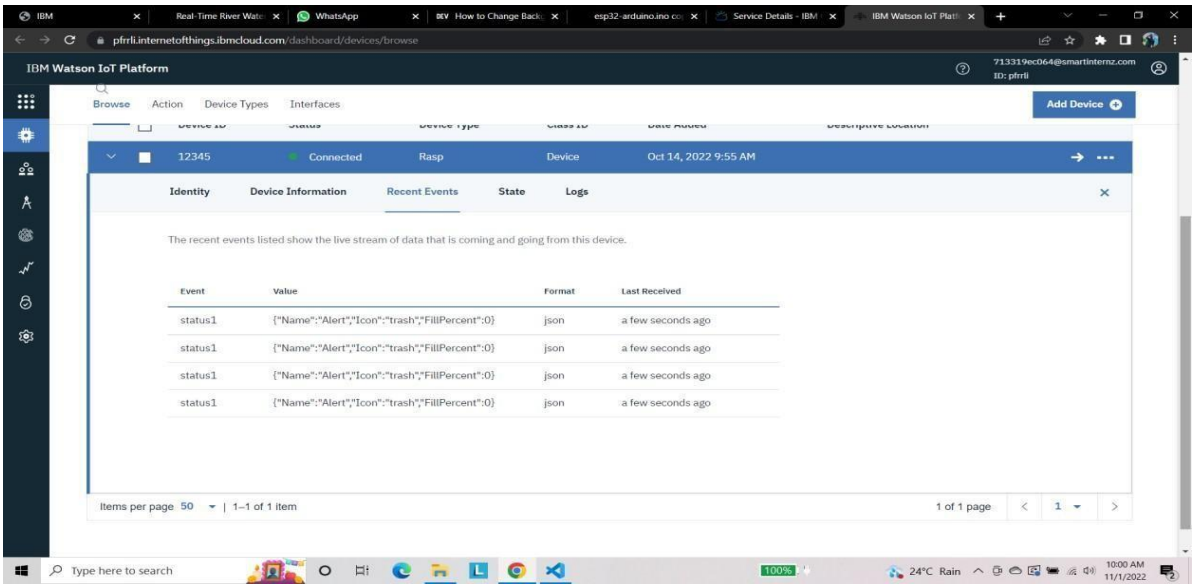


OUTPUT:





Data uploaded to Iot Watson Platform



https://wokwi.com/projects/347824265812247123