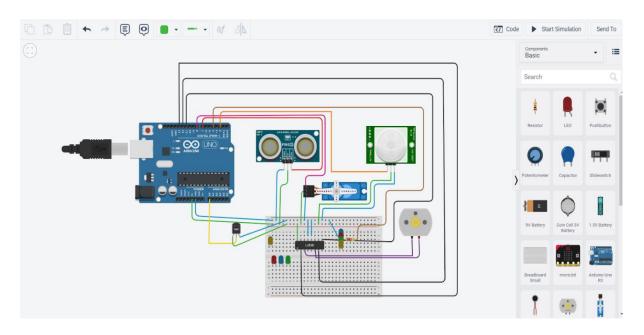
NALAIYA THIRAN

ASSIGNMENT-1

USER CASE: PERSONAL ASSISTANCE FOR SENIORS WHO ARE SELF RELIANT

BY TEAM MEMBER 3: KAMAL RAJ.R

Make a Smart Home in Tinkercad using 2+ sensors, LED, Buzzer in single code and circuit.



CODE:

```
#include<Servo.h>
const int pingPin = 7;
int servoPin = 8;
Servo servol;
void setup() {
// initialize serial communication:
Serial.begin(9600);
servol.attach(servoPin);
pinMode(2,INPUT);
pinMode(4,OUTPUT);
pinMode(11,OUTPUT);
pinMode(12,OUTPUT);
pinMode(13,OUTPUT);
pinMode(A0,INPUT);
digitalWrite(2,LOW);
digitalWrite(11,HIGH);
void loop() {
long duration, inches, cm;
pinMode(pingPin, OUTPUT);
 digitalWrite(pingPin, LOW);
 delayMicroseconds(2);
 digitalWrite(pingPin, HIGH);
delayMicroseconds(5);
digitalWrite(pingPin, LOW);
// The same pin is used to read the signal from the PING))): a HIGH pulse
// whose duration is the time (in microseconds) from the sending of the ping
// to the reception of its echo off of an object.
```

```
pinMode(pingPin, INPUT);
duration = pulseIn(pingPin, HIGH);
// convert the time into a distance
inches = microsecondsToInches(duration);
cm = microsecondsToCentimeters(duration);
//Serial.print(inches);
//Serial.print("in, ");
//Serial.print(cm);
//Serial.print("cm");
//Serial.println();
//delay(100);
 servol.write(0);
 if(cm < 40)
  servol.write(90);
  delay(2000);
}
else
{
  servol.write(0);
}
// PIR with LED starts
int pir = digitalRead(2);
if(pir == HIGH)
  digitalWrite(4,HIGH);
  delay(1000);
else if(pir == LOW)
  digitalWrite(4,LOW);
//temp with fan
float value=analogRead(A0);
float temperature=value*0.48;
Serial.println("temperature");
Serial.println(temperature);
if(temperature > 20)
  digitalWrite(12,HIGH);
  digitalWrite(13,LOW);
}
else
  digitalWrite(12,LOW);
  digitalWrite(13,LOW);
}
}
long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
```