### **NALAIYA THIRAN**

### **ASSIGNMENT-4**

USER CASE: PERSONAL ASSISTANCE FOR SENIORS WHO ARE SELF RELIANT BY TEAM MEMBER 1: ISHRATH BEGUM.I

Write a code and connection in wokwi for the Ultrasonic sensor. Whenever the distance is less than 100cm send an "Alert" to the IBM cloud and display in the device recent events.

## **CODE:**

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "3eqctu"
#define DEVICE TYPE "ESP32"
#define DEVICE ID "0000"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/shreedharen/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
```

```
{
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin,OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
bool isNearby = dist < 100;</pre>
digitalWrite(led, isNearby);
publishData();
delay(500);
if (!client.loop())
{mqttConnect();
}
}
void wifiConnect() {
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
if (!client.connected()) {
Serial.print("Reconnecting MQTT client to ");
```

```
Serial.println(server); while (!client.connect(clientId,
authMethod, token))
{
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic))
{
Serial.println("IBM subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH)
;dist=duration*speed/2;
if(dist<100){
String payload = "{\"Alert Distance\":";
payload +=
dist;payload +=
"}";
Serial.print("\n");
```

```
Serial.print("Sending payload:");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c str()))
{Serial.println("Publish OK");
}
}
if(dist>100){
String payload =
"{\"Distance\":";payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload:");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}else {
Serial.println("Publish FAILED");
}
}}
```

# **OUTPUT:**

# LINK: https://wokwi.com/projects/348038026125902419



