ASSIGNMENT-4

Assignment Date	15 October2022
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Project Name	Smart Farmer - IoT Enabled Smart Farming
	Application
Maximum marks	2 marks

Question: Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

PROGRAM:

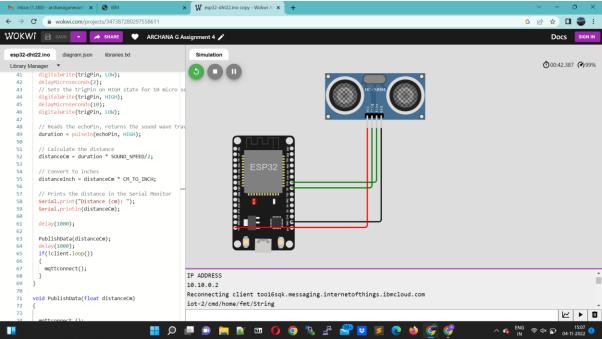
```
#include <WiFi.h>
#include<PubSubClient.h>
#include <ArduinoJson.h>
void callback(char* subscribetopic,byte* payload,unsigned int payloadLength);
#define ORG "o16sqk"
#define DEVICE_TYPE "NodeMCU"
#define DEVICE ID "12345"
#define TOKEN "715519106004"
#define SOUND SPEED 0.034
#define CM_TO_INCH 0.393701
const int trigPin = 5;
const int echoPin = 18;
long duration;
float distanceCm;
float distanceInch;
String data;
char server[]=ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/event 1/fmt/json";
char subscribeTopic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] =TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);
void setup() {
Serial.begin(115200); // Starts the serial communication
 pinMode(trigPin, OUTPUT); // Sets the trigPin as an Output
 pinMode(echoPin, INPUT); // Sets the echoPin as an Input
 wificonnect();
```

```
mqttconnect();
}
void loop() {
 // Clears the trigPin
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 // Sets the trigPin on HIGH state for 10 micro seconds
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 // Reads the echoPin, returns the sound wave travel time in microseconds
 duration = pulseIn(echoPin, HIGH);
 // Calculate the distance
 distanceCm = duration * SOUND SPEED/2;
 // Convert to inches
 distanceInch = distanceCm * CM_TO_INCH;
 // Prints the distance in the Serial Monitor
 Serial.print("Distance (cm): ");
 Serial.println(distanceCm);
 delay(1000);
 PublishData(distanceCm);
 delay(1000);
 if(!client.loop())
  mqttconnect();
void PublishData(float distanceCm)
{
 mqttconnect ();
 String payload;
 if(distanceCm<100.0)
  payload = "{\"Alert\":";
  payload += distanceCm;
  payload += "}";
 else
  payload = "{\"distanceCm\":";
  payload += distanceCm;
```

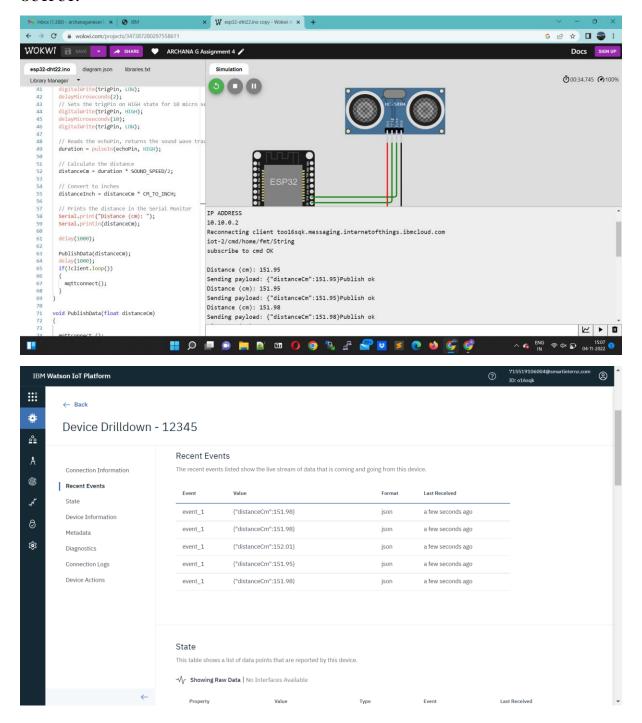
```
payload += "}";
 Serial.print("Sending payload: ");
 Serial.print(payload);
 if(client.publish(publishTopic , (char*) payload.c_str())){
 Serial.println("Publish ok");}
 { Serial.println("Publish failed");
}
void mqttconnect()
{
if(!client.connected())
Serial.print("Reconnecting client to");
Serial.println(server);
while(!!!client.connect(clientId, authMethod, token))
{
Serial.print(",");
delay(500);
}
initManagedDevice();
Serial.println();
void wificonnect()
{
 Serial.println();
 Serial.print("Connecting to");
 WiFi.begin("Wokwi-GUEST","",6);
 while(WiFi.status() != WL_CONNECTED)
  delay(500);
  Serial.print(".");
 Serial.println("");
 Serial.println("WiFi connected");
 Serial.println("IP ADDRESS");
```

```
Serial.println(WiFi.localIP());
}
void initManagedDevice()
 if(client.subscribe(subscribeTopic))
  Serial.println((subscribeTopic));
  Serial.println("subscribe to cmd OK");
 else
 {
  Serial.println("subscribe to cmd Failed");
}
void callback(char* subscribetopic,byte* payload,unsigned int payloadLength)
{
 Serial.print("callback invoked for topic:");
 Serial.println(subscribetopic);
 /*for(int i=0;i<payloadLength;i++)
  data +=(char)payload[i];
 Serial.println("data: "+data);
 if(data>(char)100)
  Serial.println("Alert!");
 }*/
```

CIRCUIT:



OUTPUT:



LINK: https://wokwi.com/projects/347387280297558611