#### **ASSIGNMENT-4**

Date	22 October 2022
TeamID	PNT2022TMID38378
Name	E. ANANDHI
MaximumMarks	2Marks

#### **Question1:**

Write code and connections in work for the ultrasonic sensor. Whenever the distance is less than 100cms sendad'alert" to the IBM cloud and display in the device recent events.

#### CODE:

```
### sinclude capital.by/library for wifi

### sinclude capitals of IBM Accounts.....

### define ORG "Ahmajo"/IBM ORGANITION ID

### define ORG "Compton Designate Designation of Ibm Accounts.....

### define ORG "Ahmajo"/IBM ORGANITION ID

### define ORG "Through Organization of Ibm Accounts.....

### define ORG "Ahmajo"/IBM ORGANITION ID

### define ORG "Ahmajo"/IBM
```

```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt •
                                                 Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

'''

String object;

if (dist 100)

digitalWrite(LED,HIGH);

sersal.println("object is near");

object = "Near";

else

digitalWrite(LED,LOW);

sersal.println("no object found");

object = "No";

String payload = "(\"distance\":";

payload += dist;

payload += object;

payload += "\"')";

serial.println(payload);

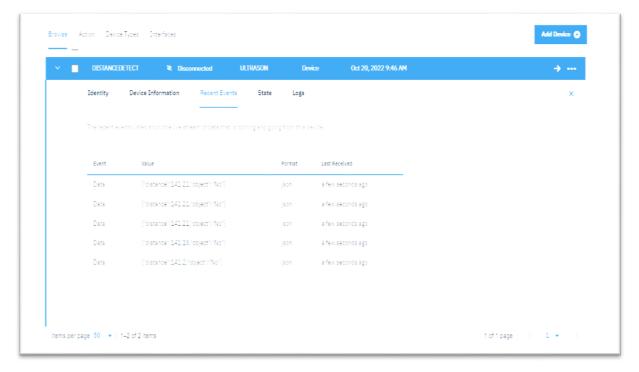
serial.println(payload);
```

```
dagramjson • ibraies to • Library Manager •

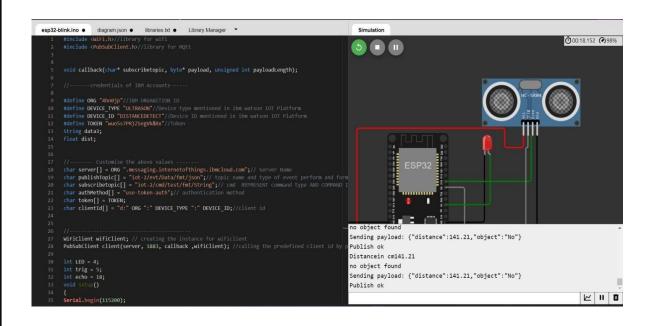
| f (client.publish(publishTopic, (char*) payload.c_str())) {
| serial.println("Publish ok"); // if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed |
| else {
| serial.println("Publish failed"); |
| yould matterconnect() {
| if (client.connected()); |
| serial.println("Bublish failed"); |
| serial.println("Reconnecting client to "); |
| serial.println("seconnecting client to "); |
| serial.println("seconnect(); |
| serial.println("); |
| delay(See); |
| initWanagedDevice(); |
| serial.println(); |
| serial.println("connecting to "); |
| serial.print("connecting to "); |
| serial.println("istatus() |= M_CONNECTED) {
| delay(See); |
| serial.println("isticonnected"); |
| serial.println("is
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt ●
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

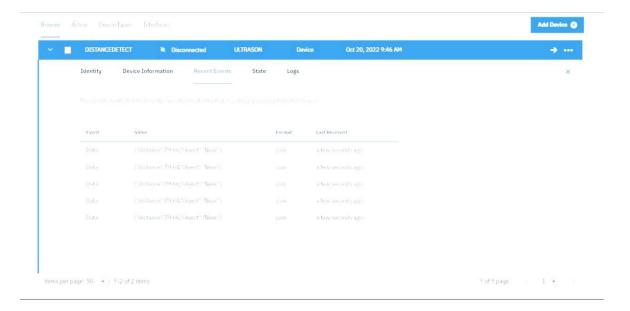
### **OUTPUT**:



Data send to the IBM cloud device when the objectics far



# Data sent to the IBMCloud Device when the objectis near



## When objectics near to the ultrasonicsensor

