

Develop a python script

Date	16 NOV 2022
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Project Name	Project - Smart Waste Management System For Metropolitan Cities

Step 1: Open python idle

Step2: Type the program

Step 3: Then click on file and save the document

Step 4: Then click on Run then Run Module

Step 5: output will be appeared in the idle window

Python script

```
import requests
import json
import ibmiotf.application
import ibmiotf.device
import time
import random
import sys

# watson device details

organization = "o1z9pr"
devicType = "12345"
deviceId = "12345678"
authMethod= "token"
authToken= "123456789"

#generate random values for randomo variables
(temperature&humidity)
```

```

def myCommandCallback(cmd):
    global a
    print("command recieved:%s" %cmd.data['command'])
    control=cmd.data['command']
    print(control)

try:
    deviceOptions={"org": organization, "type":
devicType,"id":
deviceId,"auth-method":authMethod,"auth
token":authToken}
    deviceCli = ibmiotf.device.Client(deviceOptions)
except Exception as e:
    print("caught exception connecting device %s" %str(e))
    sys.exit()

#connect and send a datapoint "temp" with value integer
value into the cloud as a type of event for every 10
seconds deviceCli.connect()

while True:

    distance= random.randint(10,70)
    loadcell= random.randint(5,15)
    data= {'dist':distance,'load':loadcell}

    if loadcell < 13 and loadcell > 15:
        load = "90 %"

    elif loadcell < 8 and loadcell > 12:
        load = "60 %"

    elif loadcell < 4 and loadcell > 7:
        load = "40 %"
    else:
        load = "0 %"

    if distance < 15:
        dist = 'Risk warning:'
'Dumpster poundage getting high,
Time to collect :) 90 %'

```

```
elif distance < 40 and distance >16:  
dist = 'Risk warning:' 'dumpster is above 60%'
```

```
elif distance < 60 and distance > 41:  
dist = 'Risk warning:' '40 %'  
else:  
dist = 'Risk warning:' '17 %'
```

```
if load == "90 %" or distance == "90 %":  
warn = 'alert :' ' Dumpster poundage getting high, Time to collect  
:).'
```

```
elif load == "60 %" or distance == "60 %":
```

```
warn = 'alert :' 'dumpster is above 60%'  
else :  
warn = 'alert :' 'No need to collect right now '  
def myOnPublishCallback(lat=10.678991,long=78.177731):  
print("Gandigramam, Karur")  
print("published distance = %s "  
%distance,"loadcell:%s " %loadcell,"lon = %s "  
%long,"lat = %s" %lat) print(load)  
print(dist)  
print(warn)
```

```
time.sleep(10)
```

```
success=deviceCli.publishEvent  
("IoTSensor","json",warn,qos=0,on_publish= myOnPublishCallback)
```

```
success=deviceCli.publishEvent  
("IoTSensor","json",data,qos=0,on_publis  
h= myOnPublishCallback)
```

```
if not success:  
print("not connected to ibmiot")  
time.sleep(30)
```

deviceCli.disconnect

Screenshots Python script:

