

**1. Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.**

**Solution:**

```
//Pins
const int TRIG_PIN = 7 ;
const int ECHO_PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAX_DIST = 23200;
void setup() {
// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);
digital Write(TRIG_PIN, LOW);
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT ) ;
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() {
unsigned long t1; unsigned long t2;
unsigned long pulse_width;
float cm;
float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO_PIN )!=0 );
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min
```

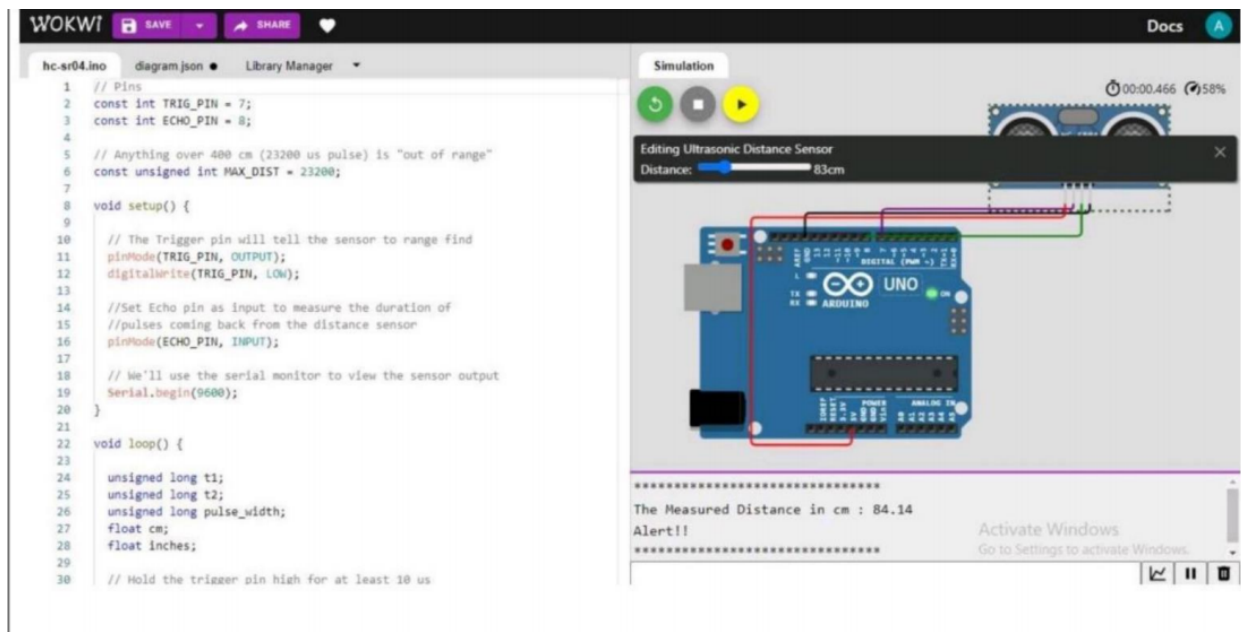
```

t1= micros ();
while (digitalRead(ECHO_PIN) == 1);
t2= micros ();
pulse_width = t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58 ;
inches = pulse_width/148.0;// Print out results
if (pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if( cm < 100 ){
//while(true){
Serial.println("Alert!!");
//}
}
Serial.print("*****");
}
//wait at least 1000ms before next measurement
Delay(1000);
}

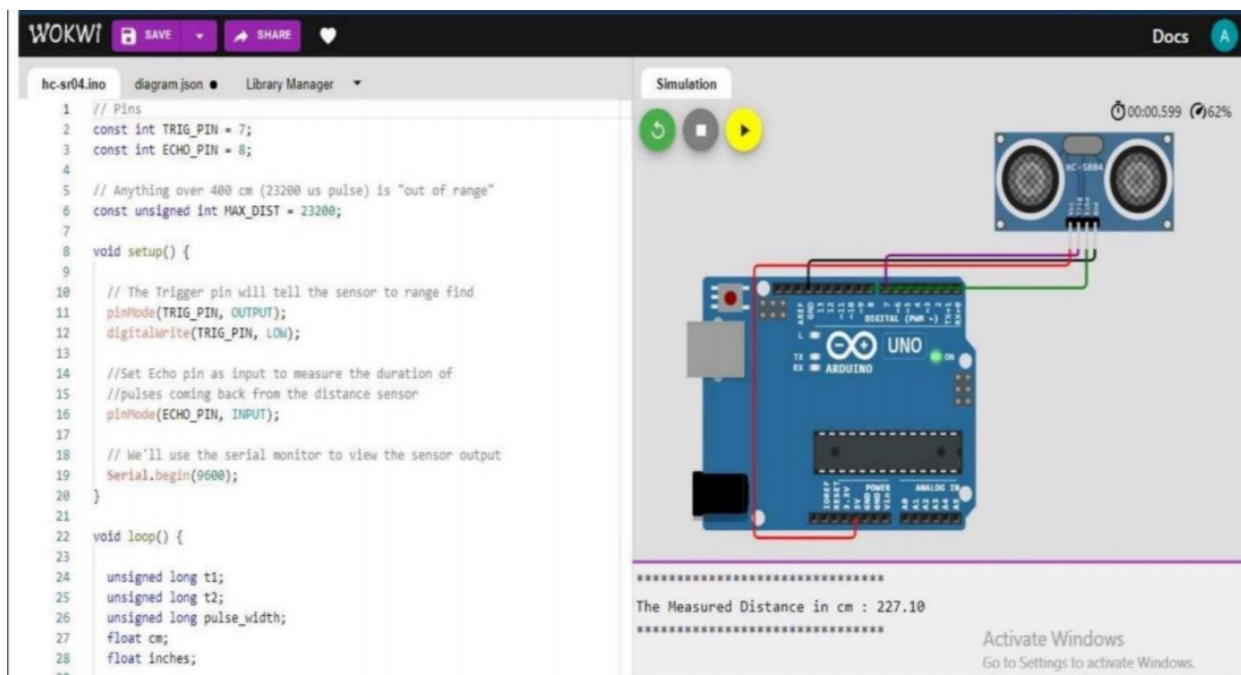
```

## Output:

**1.If the distance is less than 100 cms ,it alerts.**



2.If the distance is more than 100 cms,it won't alert



### 3.Simulation and code execution

