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ASSIGNMENT-4

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Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud and display in device recent events.

Code

```
//Pins

const int TRIG_PIN = 7 ;  const

int ECHO_PIN = 8;


//Anything over 400 cm (23200 us pulse) is "out of range"  const

unsigned int MAX_DIST = 23200;


void setup() {


// The Trigger pin will tell the sensor to range find

Pin Mode(TRIG_PIN, OUTPUT);  digital

Write(TRIG_PIN, LOW);
```

```cpp
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT ) ;
 // We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
}
void loop() { unsigned
long t1; unsigned
long t2;  unsigned
long pulse_width;
float cm;  float
inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW);

// Wait for pulse on echo pin while
(digitalRead( ECHO_PIN )==0 );

// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min  t1=
micros ();
  while (digitalRead(ECHO_PIN) == 1);
t2= micros ();   pulse_width = t2-t1;
```

```
  // Calculate distance in centimeters and inches. The constants
 //are found in the datasheet, and calculated from the assumed speed
 // of sound in air at sea level (- 340m/s)
cm=pulse_Width  /  58 ;    inches  =  pulse_width/148.0;

//   Print   out   results   if  (pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.println("*****************************”);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

if( cm < 100 ){
    //while(true){
     Serial.println(“Alert!!”);
    //}
}
Serial.print(“*******************************”);
}
//wait at least 1000ms before next measurement
Delay(1000);
}
```
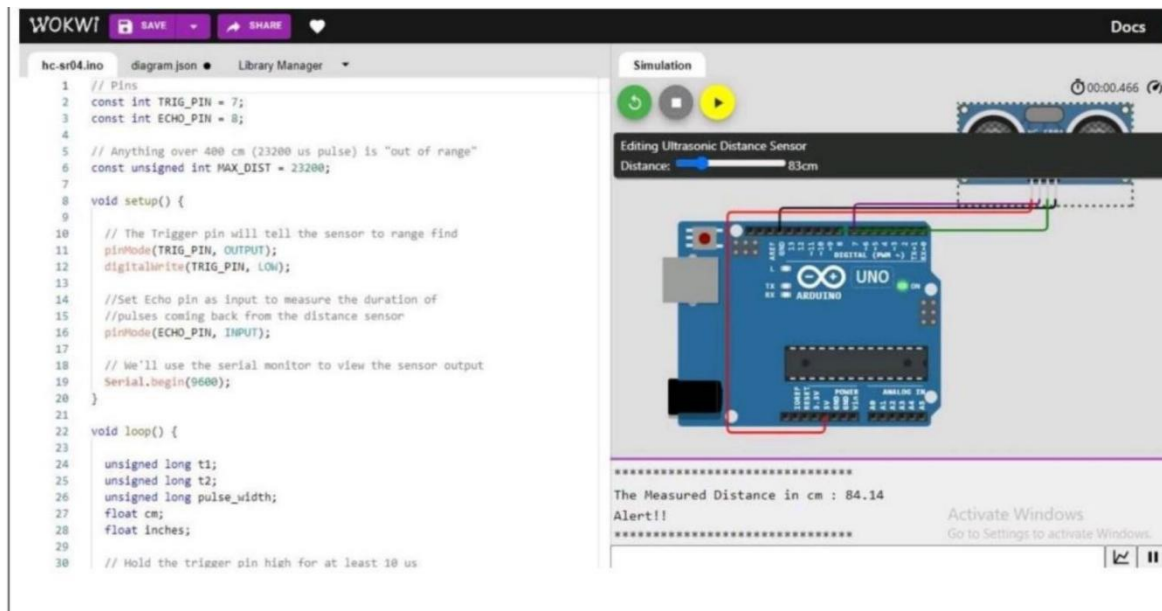
Output:

1.If the distance is less than 100 centimeters,it alerts.

2.If the distance is more than 100 centimeters,it won't alert