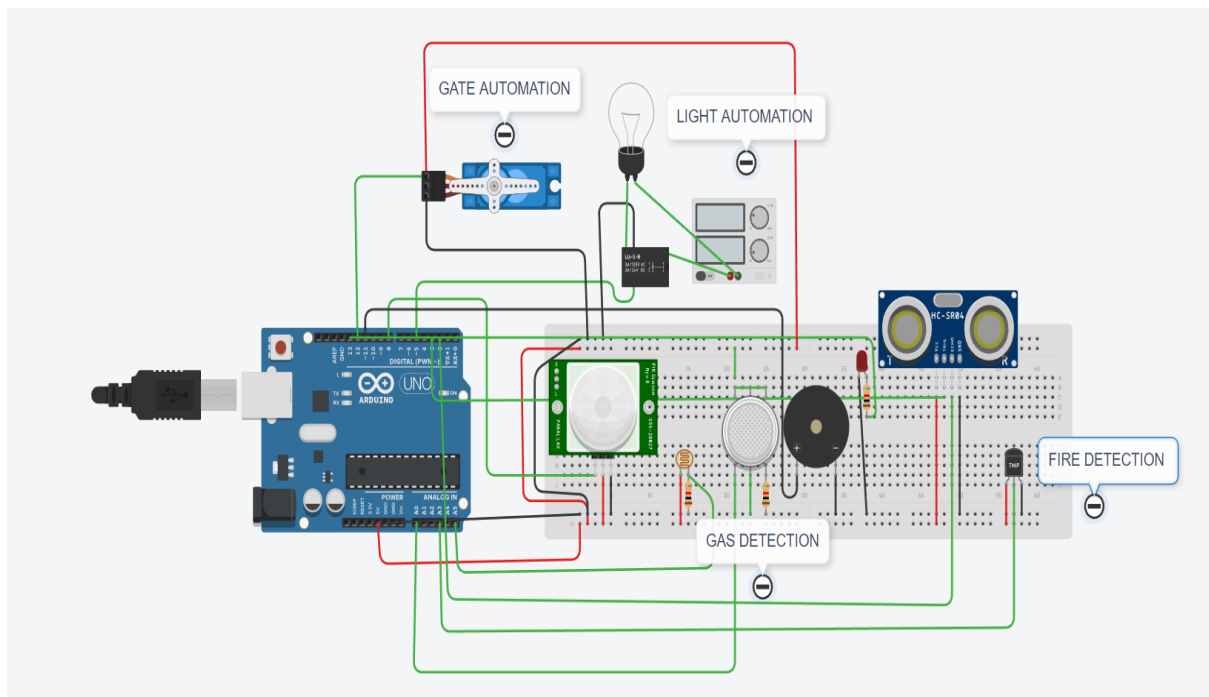


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# HOME AUTOMATION- ASSIGNMENT 1

## CIRCUIT DIAGRAM



Sensors used

- Temperature Sensor
- Passive Infrared Sensor
- Ultrasonic Sensor
- Gas sensor

## CODE

```
#include<Servo.h>

Servo s;

int trig=3;

int ec=2;

int led_pin=13;

int buzz_pin;

void setup()

{

    pinMode(8,INPUT);
    pinMode(5,OUTPUT);
    pinMode(A5,INPUT);
    pinMode(11,OUTPUT);
    pinMode(13,OUTPUT);
    pinMode(trig,OUTPUT);
    pinMode(ec,INPUT);
    s.attach(12);
    s.write(0);
    Serial.begin(9600);
}

void loop()

{/*LIGHT AUTOMATION*/

    float x,y;

    x= digitalRead(8);

    y= analogRead(A5);

    if ( (x>0) && (y<500))

    { digitalWrite(5,HIGH);

        Serial.println("BULB ON");
```

```
    delay (10000);  
    Serial.println("BULB OFF");  
}  
else  
    digitalWrite(5,0);
```

```
/*GAS DETECTION*/  
  
int a,b;  
  
a=analogRead(A0);  
b=map(a,0,1023,0,255);  
Serial.println(b);  
if(b>70)  
{analogWrite(buzz_pin,50);  
  digitalWrite(13,HIGH);  
  delay(300);  
  analogWrite(buzz_pin,0);  
  digitalWrite(led_pin,LOW);  
  delay(300);  
  analogWrite(buzz_pin,50);  
  digitalWrite(led_pin,HIGH);  
  Serial.println("Smoke detected");  
}  
else  
    analogWrite(buzz_pin,0);
```

```
/*automatic gate control*/  
digitalWrite(trig,LOW);  
digitalWrite(trig,HIGH);  
delayMicroseconds(10);
```

```

digitalWrite(trig,LOW);

float duration;

duration=pulseIn(ec,HIGH);

float dist;

dist=(duration*0.0343)/2;

if(dist<75)

{for(int i=0;i<=90;i=i+10)

    {s.write(i);

      delay(50);

    }

  delay(10000);

  for(int j=90;j>=0;j--)

    {s.write(j);

      delay(50);

    }

}

/*fire alert based on temperature*/

double f=analogRead(A3);

double t=((f/1024)*5)-0.5)*100;

if(t>70)

{digitalWrite(led_pin,HIGH);

  analogWrite(buzz_pin,50);

  delay(200);

  analogWrite(buzz_pin,50);

    digitalWrite(led_pin,LOW);

  delay(200); }}

```