

Assignment -4

Assignment Date	10 November 2022
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QUESTION:

Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cms send "alert" to IBM cloud and display in the device recent events.

Device Information	Recent Events	State	Logs
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its listed-show the live stream of data that is coming and going from this device.

Value	Format	Last Received
{"distance":152}	json	a few seconds ago
{"ALERT":91}	json	a few seconds ago
{"ALERT":42}	json	a few seconds ago
{"distance":186}	json	a few seconds ago
{"distance":190}	json	a few seconds ago

Output:

PROGRAM:

```
#include <WiFi.h> #include <PubSubClient.h> void callback(char*
subscribetopic,byte* payload, unsigned int payloadLength); #define
ORG "6t0grq"
#define DEVICE_TYPE "arduino"
#define DEVICE_ID "12345"
#define TOKEN "12345678"
String data3;
char server[]= ORG
".messaging.internetofthings.ibmcloud.com"; char
publishTopic[]="iot-2/evt/AKSHAYKP/fmt/json"; char
subscribeTopic[]="iot-2/cmd/test/fmt/String"; char
authMethod[]="use-token-auth"; char token[]=TOKEN; char
clientID[]="d:ORG":DEVICE_TYPE":DEVICE_ID;
```

```

WiFiClient wifiClient;
PubSubClient client(server,1883,callback,wifiClient);

#define ECHO_PIN 12
#define TRIG_PIN 13

#define led 14
void setup() {
    // put your setup code here, to run once:
    Serial.begin(115200);    pinMode(led,
    OUTPUT);    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);    wificonnect();
    mqttconnect(); } float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2); digitalWrite(TRIG_PIN,
    HIGH); delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW); int
    duration=random(1,200);
    //Serial.println(duration);    //duration =
    pulseIn(ECHO_PIN, HIGH);    return duration
    ;
    //Serial.println(duration);

} void
loop() {
    float distance = readDistanceCM();
    //Serial.println(distance);
    bool isNearby = distance <
    100;    digitalWrite(led,
    isNearby);

    Serial.print("Measured distance: ");
    Serial.println(distance);    if(distance<100){
        PublishData2(distance);

    }else{
        PublishData1(distance);

    }
    //PublishData(distance);
    delay(1000);    if(!client.loop()){
    mqttconnect();
    }

    //delay(2000);
} void PublishData1(float
dist){    mqttconnect();
    String payload= "{\"distance\":";
    payload += dist;    payload+="}";

```

```

Serial.print("Sending payload:");
Serial.println(payload);

if(client.publish(publishTopic,(char*)payload.c_str())){

    Serial.println("publish ok");
} else{
    Serial.println("publish failed");
} } void PublishData2(float
dist){  mqttconnect();
String payload= "{\\"ALERT\\":\\"";
payload += dist;    payload+="}";

Serial.print("Sending payload:");
Serial.println(payload);

if(client.publish(publishTopic,(char*)payload.c_str())){
    Serial.println("publish ok");
} else{
    Serial.println("publish failed");
} } void mqttconnect(){
if(!client.connected()){
    Serial.print("Reconnecting to");
Serial.println(server);
    while(!client.connect(clientID, authMethod, token)){
Serial.print(".");    delay(500);    }
    initManagedDevice();
    Serial.println();
}
}
void wificonnect(){
Serial.println();
    Serial.print("Connecting to");    WiFi.begin("Wokwi-GUEST","",6);
while(WiFi.status()!=WL_CONNECTED){    delay(500);
    Serial.print(".");
}
Serial.println("");
Serial.println("WIFI CONNECTED");
Serial.println("IP address:");
Serial.println(WiFi.localIP());
} void initManagedDevice(){
if(client.subscribe(subscribeTopic)){
Serial.println((subscribeTopic));
    Serial.println("subscribe to cmd ok");
}else{

```

```

        Serial.println("subscribe to cmd failed");
    }
} void callback(char* subscribeTopic, byte* payload, unsignedint
payloadLength){
    Serial.print("callback invoked for topic:");
    Serial.println(subscribeTopic);    for(int i=0;
i<payloadLength; i++){        data3 +=
(char)payload[i];

    }
    Serial.println("data:" + data3);
    if(data3=="lighton"){
        Serial.println(data3);
        digitalWrite(led,HIGH);
    }else{
        Serial.println(data3);
        digitalWrite(led,LOW);
    }
    data3="";
}

```