PROJECT DEVELOPMENT PHASE

SPRINT 1

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Project Name	Project – Signs with Smart Connectivity for Better Road Safety

PROGRAM CODE:

10km is 100% and 0km is 0%

1. Weather.py

This file contains a utility function that uses the OpenWeather API to retrieve the weather. Only a few of the necessary API response parameters are returned.

```
# Python code

import requests as reqs

def get(myLocation,APIKEY):
    apiURL =

f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appid={APIKEY}"

    responseJSON = (reqs.get(apiURL)).json()
    returnObject = {
        "temperature" : responseJSON['main']['temp'] - 273.15,
        "weather" : [responseJSON['weather'][_]['main'].lower() for _ in

range(len(responseJSON['weather']))],
        "visibility" : responseJSON['visibility']/100, # visibility in percentage where
```

```
}
  if("rain" in responseJSON):
     returnObject["rain"] = [responseJSON["rain"][key] for key in
responseJSON["rain"]]
  return(returnObject)
```

2. brain.py

returns the information that is necessary to be displayed on the hardware side. The logic for the code flow is carried out here.

```
This file is a utility function that abstracts all unnecessary details and only
# Python code
import weather
from datetime import datetime as dt
def processConditions(myLocation,APIKEY,localityInfo):
  weatherData = weather.get(myLocation,APIKEY)
  finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
  finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
  if(localityInfo["hospitalsNearby"]):
     # hospital zone
     doNotHonk = True
  else:
     if(localityInfo["schools"]["schoolZone"]==False):
       # neither school nor hospital zone
       doNotHonk = False
```

```
else:
    # school zone
    now = [dt.now().hour,dt.now().minute]
    activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
    doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]

return({
    "speed" : finalSpeed,
    "doNotHonk" : doNotHonk
})</pre>
```

3. Main.py

The code that runs in a forever loop in the microcontroller. This calls all the utilfunctions from other python files and based on the return value transduces changes in the output hardware display.

```
# Python code
import brain

myLocation = "Chennai,IN"

APIKEY = "c76d51c15c0e7c6c5f2002ad65efcec1"

localityInfo = {
    "schools" : {
        "schoolZone" : True,
        "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
        },
```

```
"hospitalsNearby" : False,

"usualSpeedLimit" : 40 # in km/hr
```

print(brain.processConditions(myLocation,APIKEY,localityInfo))

OUTPUT:

Code Output

{'speed': 40, 'doNotHonk': False}

