## Assignment -4 Python Programming

Assignment Date	17November2022
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Maximum Marks	2 Marks

## Question-1:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cms send an "alert" to the IBM cloud and display in the device recent events. Upload document with wokwi share link and images of IBM cloud

```
Solution:
```

```
#include<WiFi.h>
#include<PubSubClient.h>
voidcallback(char* subscribetopic, byte* payload, unsignedint
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "90pizh"//IBM ORGANITION ID
#define DEVICE_TYPE "NodeMCU"//Device type mentioned in ibmwatson IOT
#define DEVICE_ID "123456"//Device ID mentioned in ibmwatson IOT
Platform
#define TOKEN "8098439666"//Token
String data3;
charserver[] = ORG ".messaging.internetofthings.ibmcloud.com";
charpublishTopic[] = "iot-2/evt/Data/fmt/json";
charsubscribetopic[] = "iot-2/cmd/test/fmt/String";
charauthMethod[] = "use-token-auth";
chartoken[] = TOKEN;
charclientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClientwifiClient;
PubSubClientclient(server, 1883, callback ,wifiClient);
constinttrigPin = 5;
constintechoPin = 18;
#define SOUND SPEED 0.034
long duration;
float distance;
voidsetup() {
```

```
Serial.begin(115200);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
wificonnect();
mqttconnect();
}
voidloop()
digitalWrite(trigPin, LOW);
delayMicroseconds(2);
digitalWrite(trigPin, HIGH);
delayMicroseconds(10);
digitalWrite(trigPin, LOW);
duration = pulseIn(echoPin, HIGH);
distance = duration * SOUND_SPEED/2;
Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)</pre>
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if(!client.loop()) {
mqttconnect();
}
}
delay(1000);
}
voidPublishData(floatdist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}
voidmqttconnect() {
if(!client.connected()) {
```

```
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!!!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
initManagedDevice();
Serial.println();
}
voidwificonnect()
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());
}
voidinitManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
voidcallback(char* subscribetopic, byte* payload, unsignedintpayloadLength)
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (inti = 0; i<payloadLength; i++) {</pre>
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
}
```



