ASSIGNMENT-4

S.HARIHARAN 421319106011(batch9) Smartwasteman agement for metropolitan cities

Question:

Writecodeandconnections in wokwiforul trasonic sensor. Whenever distance is less than 100 centimetersit should send "alert" to IBM cloud and display in devicerecentevents

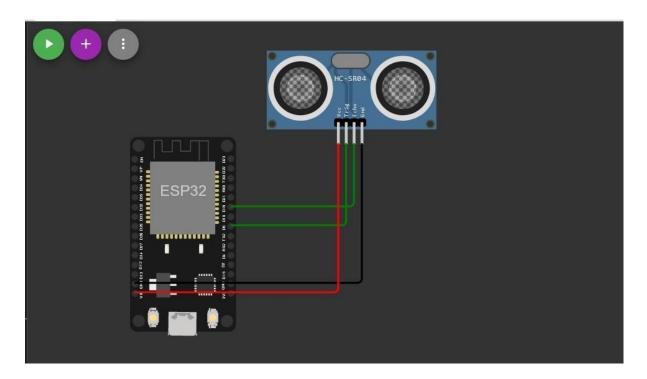
Code:

```
#include<WiFi.h>
#include
<PubSubClient.h>#includ
e<ArduinoJson.h>
WiFiClient
wifiClient;#defineOR
G"9tg03j"
#defineDEVICE_TYPE"RaspberryPi"#define
DEVICE_ID"12345"
#defineTOKEN"12345678"
#definespeed0.034
charserver[]=ORG".messaging.internetofthings.ibmcloud.com";charp
ublishTopic[]="iot-2/evt/status1/fmt/json";
chartopic[]="iot-
2/cmd/home/fmt/String";charauthMethod[]="
use-token-auth";
chartoken[]=TOKEN;
charclientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
PubSubClientclient(server, 1883, wifiClient); vo
idpublishData();
constinttrigpin=5;
constintechopin=19;St
command;Stringdata=
"";String
```

```
name="Alert";Stringic
on="";
 long
 duration;intdi
 st;
 voidsetup()
  Serial.begin(115200);pinMo
  de(trigpin,
  OUTPUT);pinMode(echopin
  INPUT);wifiConnect();mqtt
  Connect();
 void loop()
  {publishData(
  );delay(500);
  if(!client.loop()){
   mqttConnect();
  }
 }
 void wifiConnect()
  {Serial.print("Connecting to
  ");Serial.print("Wifi");WiFi.begin("
  Wokwi-GUEST","",6);
  while(WiFi.status()!=WL_CONNECTED){delay(500);
   Serial.print(".");
  Serial.print("WiFiconnected, IPaddress:"); Serial.println(WiFi.localIP());
 voidmqttConnect(){
  if(!client.connected()){
   Serial.print("ReconnectingMQTTclientto");Serial.println(server);whi
   le (!client.connect(clientId, authMethod, token)) {Serial.print(".");
    Serial.print("*");
    delay(1000);
   initManagedDevice();Se
   rial.println();
 voidinitManagedDevice(){
if (client.subscribe(topic))
{Serial.println(client.subscribe(topic));Serial.pr
intln("subscribetocmdOK");
  }
```

```
else{
  Serial.println("subscribetocmdFAILED");
 }
}
voidpublishData()
 digitalWrite(trigpin,LOW);digital
 Write(trigpin,HIGH);delayMicrose
 conds(10);digitalWrite(trigpin,LO
 W);duration=pulseIn(echopin,HIG
 H);dist=duration*speed/2;if(dist<1
 00){
  dist=100-
  dist;icon="Not-
  Crashed";
 }
 else{dis
  t=0;
  icon="Crashed";
 }
 DynamicJsonDocument
 doc(1024);String
 payload;doc["Name"]=name;doc["I
 mpact"]=icon;doc["Distance"]=dist
 ;serializeJson(doc,
 payload);delay(3000);
 Serial.print("\n");Serial.print("Sendi
 ngpayload:");Serial.println(payload);
 if(client.publish(publishTopic,(char*)payload.c_str())){Serial.println
  ("PublishOK");
 }
 else{
  Serial.println("PublishFAILED");
}
```

DIAGRAM:



OUTPUT:

