#### **ASSIGNMENT-4**

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### **Question:**

Writecodeandconnections in wokwiforul trasonic sensor. Whenever distance is less than 100 centimetersit should send "alert" to IBM cloud and display in devicerecentevents

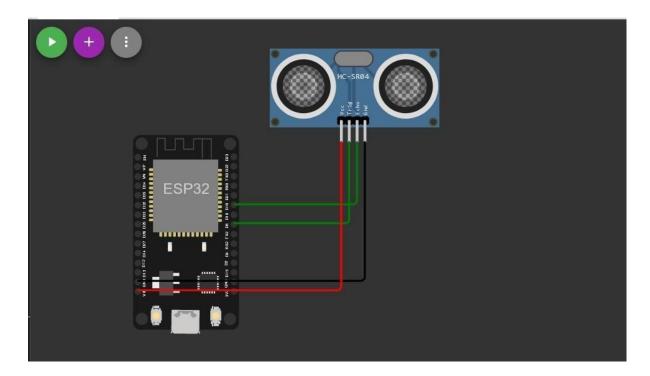
### Code:

```
#include<WiFi.h>
#include<PubSub
Client.h>
#include<Arduino
Json.h>
WiFiClient
wifiClient;
#defineORG"9tg03j"
#defineDEVICE_TYPE"RaspberryPi"
#defineDEVICE ID"12345"
#defineTOKEN"12345678"
#definespeed0.034
charserver[]=ORG".messaging.internetofthings.ibmcloud.com";charp
ublishTopic[]="iot-2/evt/status1/fmt/json";
chartopic[]="iot-
2/cmd/home/fmt/String";charauthMethod[]="
use-token-auth";
chartoken[]=TOKEN;
charclientId[]="d:"ORG":"DEVICE_TYPE":"DEVICE_ID;
PubSubClientclient(server,1883,wifiClient);vo
idpublishData();
constinttrigpin=5;
constintechopin=19;St
ring
```

```
command;Stringdata=
"";String
name="Alert";Stringic
on="";
long
duration;intdi
st;
voidsetup()
  Serial.begin(115200);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
void loop() {
publishData();
delay(500);
if(!client.loop())
{
mqttConnect();
 }
void wifiConnect()
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST","",6);
while(WiFi.status()!=WL_CONNECTED)
delay(500);
Serial.print(".");
  Serial.print("WiFiconnected, IPaddress:"); Serial.println(WiFi.localIP());
voidmqttConnect(){
  if(!client.connected()){
   Serial.print("ReconnectingMQTTclientto");Serial.println(server);whi
   le (!client.connect(clientId, authMethod, token)) {Serial.print(".");
    Serial.print("*");
    delay(1000);
   initManagedDevice();Se
   rial.println();
 }
```

```
voidinitManagedDevice(){
if (client.subscribe(topic))
{Serial.println(client.subscribe(topic));Serial.pr
intln("subscribetocmdOK");
  }
  else{
   Serial.println("subscribetocmdFAILED");
 }
voidpublishData()
  digitalWrite(trigpin,LOW);digital
  Write(trigpin,HIGH);delayMicrose
  conds(10);digitalWrite(trigpin,LO
  W);duration=pulseIn(echopin,HIG
  H);dist=duration*speed/2;if(dist<1
  00){
   dist=100-
   dist;icon="Not-
   Crashed";
  else{dis
   t=0;
   icon="Crashed";
  DynamicJsonDocument
  doc(1024);String
  payload;doc["Name"]=name;doc["I
  mpact"]=icon;doc["Distance"]=dist
  ;serializeJson(doc,
  payload);delay(3000);
  Serial.print("\n");Serial.print("Sendi
  ngpayload:");Serial.println(payload);
  if(client.publish(publishTopic,(char*)payload.c_str())){Serial.println
   ("PublishOK");
  else{
   Serial.println("PublishFAILED");
  }
 }
```

# **DIAGRAM:**



## **OUTPUT:**

```
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```

