IBM ASSIGNMENT - 4

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1. Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud aand display in device recent events.

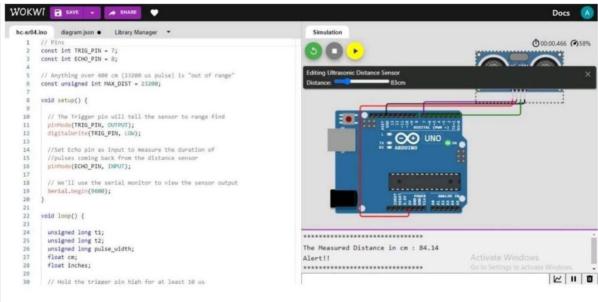
```
Solution:
//Pins
const int TRIG_PIN = 7; const
int ECHO_PIN = 8;
//Anything over 400 cm (23200 us pulse) is "out of range" const
unsigned int MAX DIST = 23200;
void setup() {
// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT); digital
Write(TRIG PIN, LOW);
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO PIN, INPUT);
```

```
// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() { unsigned
long t1; unsigned
long t2;
unsigned long pulse_width;
float cm; float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10); digitalWrite(TRIG_PIN,
LOW);
// Wait for pulse on echo pin
while (digitalRead( ECHO PIN )==0 );
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min t1=
micros (); while (digitalRead(ECHO PIN) == 1);
 t2= micros ();
  pulse_width = t2-t1;
// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58; inches =
pulse_width/148.0;
// Print out results if
(pulse_width >MAX _ DIST ){
```

```
Serial.println("Out of range");
} else {
Serial.println("*********************************);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);
if( cm < 100 ){
   //while(true){
    Serial.println("Alert!!");
   //}
}
Serial.print("********************************);
}
//wait at least 1000ms before next measurement
Delay(1000);
}
```

Output:

1. If the distance is less than 100 cms, it alerts.



2. If the distance is more than 100 cms, it won't alert

```
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                                                                                           Simulation
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         const int TRIG PIN = 7;
        const int ECHO_PIN = 8;
        // Anything over 400 cm (23200 us pulse) is "out of range"
        const unsigned int MAX_DIST = 23200;
        void setup() {
          // The Trigger pin will tell the sensor to range find
pinMode(TRIG_PIN, OUTPUT);
   11
           digitalWrite(TRIG_PIN, LOW);
                                                                                                                     ONU (OC)
   13
           //Set Echo pin as input to measure the duration of //pulses coming back from the distance sensor
           pinMode(ECHO_PIN, INPUT);
   16
           // We'll use the serial monitor to view the sensor output
   19
20
          Serial.begin(9600);
                                                                                                                    POMES MALON IN
   21
22
         void loop() {
   24
25
           unsigned long t1;
                                                                                        ***********
           unsigned long t2;
                                                                                        The Measured Distance in cm : 227.10
           unsigned long pulse_width;
                                                                                         ************************
           float cm;
float inches;
                                                                                                                                            Activate Windows
                                                                                                                                            Go to Settings to activate Windows
```

3. Simulation and code execution

